

# NAVAL POSTGRADUATE SCHOOL

## Monterey, California



# THESIS

**AEROSOL OPTICAL DEPTH ANALYSIS WITH NOAA  
GOES AND POES IN THE WESTERN ATLANTIC**

by

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June 2002

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**AEROSOL OPTICAL DEPTH ANALYSIS WITH NOAA GOES AND POES IN  
THE WESTERN ATLANTIC**

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## ABSTRACT

An aerosol optical depth retrieval algorithm in the visible wavelengths for the NOAA POES AVHRR and GOES-8 visible imager is presented for the cloud free, marine atmosphere. The algorithm combines linearized single-scatter theory with an estimate of surface reflectance. Phase functions are parameterized using an aerosol size distribution model and the ratio of radiance values measured in channels 1 and 2 of the AVHRR. Retrieved satellite aerosol optical depth (AOD) is compared to three land-based sun photometer stations located on islands in the western Atlantic during July and September, 2001. GOES-8 channel 1 (visible wavelength) radiance values were initially calibrated using techniques developed by Rao. Additional corrections to the channel 1 GOES-8 radiances were made by applying a linear offset factor obtained during the experimental time period through comparison with AVHRR radiances. The results for the GOES-derived AOD compare favorably to the AERONET-measured AOD values. For both NOAA and GOES data, the comparison dataset has a correlation coefficient of 0.67 with a standard error of 0.07. For higher AOD cases ( $d = 0.25$ ), the general trend was for the satellite-derived AOD values to underestimate AERONET-observed conditions. During these higher conditions, the scattering phase function pattern contained within the algorithm deviated from the expected pattern, especially between  $140^\circ - 180^\circ$ . Overall, the more accurate calculations of AOD occurred over scatter angles between  $140^\circ - 150^\circ$  and  $170^\circ - 180^\circ$ .

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## I. INTRODUCTION

Monitoring tropospheric aerosols on a global scale is essential for evaluating the earth's radiation budget. Aerosols are known to cause a net cooling effect by scattering incident solar radiation back to space and by interacting with clouds in a way that increases overall albedo (Charlson *et al.*, 1992, Twomey *et al.*, 1977, IPCC, 1996). King *et al.* (1999) reports that the impact of aerosol radiative forcing, both directly (scattering) and indirectly (interaction with clouds), produces a cooling range of  $-1.4 \pm 1.5 \text{ W m}^{-2}$  to  $-2.5 \pm 2 \text{ W m}^{-2}$ . This result offsets the well-known concept of the greenhouse warming impact, estimated to be  $+2.5 \pm 0.3 \text{ W m}^{-2}$ .

Assessing aerosol properties also has military implications. Infrared wavelength image and ranging systems, laser-guided weapons systems, and laser communication systems are sensitive to the environment. Infrared imaging and ranging systems are strongly affected by variations of atmospheric aerosols. Laser systems used for radio and satellite communications operate within the visible and near-IR wavelength ranges, and can be greatly affected by varying aerosol properties, such as density, size distribution, chemical and physical composition (Bloembergen *et al.* 1987; Cordray *et al.* 1977). Brown (1997) reports that the proper interpretation of aerosol radiative properties in the coastal zone is "important to the design, planning, and operation of electro-optical weapons and sensor systems near coastal boundaries".

Another research area of global aerosol impact focuses on the transport of dust and pollutants from one region to another. ACE-Asia is a 4-year project (2001 – 2004) devoted to the study of aerosol profiles in the Pacific basin generated by desert dust and industrial pollution over Asia. The Puerto Rico Dust Experiment (PRIDE) in 2000 studied the impacts of African desert dust that is transported over to the Caribbean and the eastern U.S.

Given the challenges listed above, there is a developing interest to globally quantify aerosol properties on fine spatial and temporal scales. Thus far, this analysis has proven to be a daunting task, since most established aerosol sensing is land-based, providing

poor spatial and temporal coverage. Higurashi *et al.* (1999) suggests that aerosol concentration, size distribution, composition, and optical properties will have to be measured globally, and that satellite remote sensing is an effective tool for such a task. Over the past few decades, scientists have developed algorithms to convert satellite upwelling radiances into aerosol properties such as optical depth. So far, most of the aerosol remote sensing studies have used the NOAA Advanced Very High Resolution Radiometer (AVHRR) channel 1 and 2 sensors. These algorithms were developed by assuming certain aerosol characteristics before processing the upwelling radiances (Durkee *et al.* (1991), Kaufman *et al.* (1990), Higurashi and Nakajima (1999)).

This study focuses on one such algorithm developed by Durkee *et al.* (1992) (hereafter referred to as the NPS algorithm). The NPS algorithm ingests AVHRR data within a cloud-free, single scatter environment. By using the ratio of channel 1 and 2 radiances, an estimate of the aerosol size distribution is extracted. During three recent field campaigns, Durkee *et al.* (1999) has shown that the NPS algorithm performs well for aerosol optical depth (AOD) below about 0.4 at  $0.63\mu\text{m}$  wavelength. But the results only provided snapshots of the experimental regions, since AVHRR passes over a particular region a few times per day. Brown (1997) incorporated both the AVHRR and the Geosynchronous Operational Environmental Satellite (GOES) satellite to provide temporal coverage of AOD over an experimental region. In the upgraded NPS algorithm, an aerosol model index is derived from the AVHRR data is applied to the GOES retrieval. The results were encouraging, but limited. The focus of this report is to expand this approach. The following issues will be addressed:

- Proper radiance calibration of the visible sensor of GOES
- Validation of the AOD derived from NOAA and GOES-8
- Evaluation of the phase function parameters used in the retrieval algorithm

Chapter II describes the radiative transfer theory and the simplifying atmospheric assumptions used in the satellite optical depth retrievals. Chapter III describes the data sets and the instrumentation used. Chapter IV describes the calibration and correction techniques applied to the retrieved GOES channel 1 radiance. In addition, the AOD retrieval procedures for both the AVHRR and GOES are discussed. Chapter V discusses

the results and Chapter VI presents the conclusions and recommendations for future research.

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## II. THEORY

### A. RADIATIVE TRANSFER THEORY

Estimates of AOD from satellite-sensed upwelling radiances are calculated by the Radiative Transfer Equation (referred to hereafter as RTE). The RTE takes into account the various paths and interactions that solar radiation encounters with atmospheric particles and the earth's surface before reaching the satellite sensor. From Liou (1980), the general form of the RTE for a given solar wavelength in a plane parallel atmosphere is:

$$\begin{aligned} \mu \frac{dL(d, O)}{dd} = & L(d, O) - \frac{?}{4p} \int_0^{4p} L(d, O') p(O, O') dO' \\ & - \frac{?}{4p} p F_o p(O - O_o) e^{-d/\mu_o} \end{aligned} \quad (1)$$

where:

$L$  = diffuse radiance ( $\text{W/m}^2 \mu\text{m sr}$ )

$\delta$  = optical depth,

$\omega_o$  = single scatter albedo,

$\mu$  =  $\cos\theta$  ( $\theta$  = satellite zenith angle),

$\mu_o$  =  $\cos\theta_o$  ( $\theta_o$  = solar zenith angle)

$\Omega$  = solid angle ( $\theta, \phi$ ) ( $\phi$  = azimuth angle),

$p(\Omega, \Omega_o)$  = scattering phase function and

$\pi F_o$  = incoming solar radiative flux.

The terms on the right hand side of the equation describe the radiation loss due to atmospheric attenuation, the intensity gained by multiple scattering into the beam and the beam addition due to single scatter events.

For the aerosol optical depth environment, Brown (1997) and Durkee *et al.* (1991) greatly simplify the Eq. (1) by making the following assumptions: the satellite scans the region only in a cloud-free, marine environment, with a single scatter approximation. In addition, contributions from ozone absorption, Rayleigh and ocean surface effects are eliminated from the calculation. The equation is then reduced to:

$$L_a = \frac{\omega_o F_o}{4\mu} p(\Psi_s) d_a \quad (2)$$

where the subscript “a” refers to aerosol related quantities and  $\Psi_s$  represents the scattering angle. In Eq. (2), the incoming solar radiance ( $F_o$ ) is a known constant and the satellite zenith angle ( $\mu$ ) is obtained by the satellite-earth geometry. The single scatter albedo is a measure of the ratio of radiance scattered versus radiance absorbed. For marine aerosols sensed by visible wavelengths, the particles (salt, sulfate) are weakly absorbing and therefore, the single scatter albedo ( $\omega_o$ ) is nearly one.  $L_a$  represents the satellite-detected upwelling radiance only from contributions of atmospheric aerosol particles. Radiances due to sun glint (Cox and Munk, 1954), Rayleigh scatter and surface reflected radiance were eliminated. Brown (1997) describes in detail the steps involved to eliminate these radiances. This leaves the single scatter phase function,  $p(\Psi_s)$ , and the AOD,  $\delta_a$ , which are discussed below in greater detail.

## B. OPTICAL DEPTH

Solar radiation interacts with the atmosphere in three ways: absorption, scatter and emission. The density and absorbing properties of the particles determine how much incoming solar radiation is attenuated before reaching the satellite sensor. The combination of absorption and scattering is called extinction, which is described by the following equation:

$$s_{ext} = \int_0^{\infty} \sigma_{ext} r^2 Q_{ext}(m, r) n(r) dr \quad (3)$$

where  $\sigma_{ext}$  is the extinction coefficient, which describes how easily the particle interacts with the solar photons. For the remaining terms,  $r$  is the particle radius,  $\pi r^2$  is the particle

cross-section area,  $Q_{ext}(m,r)$  is the extinction efficiency factor that varies with the radius ( $r$ ), wavelength and composition,  $m$  is the complex index of refraction, and  $n(r)$  is the number of particles in a size increment  $r$  to  $r + dr$ . Changes in the size, composition, and distribution of constituents of suspended particles in the atmosphere lead to a change in extinction. Therefore, measurement of extinction can provide information about the characteristics of the atmosphere's particulate distribution. The scattering of solar radiation is the largest contributing factor to extinction in the visible and near infrared wavelengths. Since this report deals with aerosol extinction only, Rayleigh scattering can be accounted for and factored out of the optical depth calculation because the atmospheric molecular particles are nearly uniform both spatially and temporally (Durkee *et al.*, 1991). There is also a small contribution of absorption by ozone gases within the upper atmosphere, but its effect is minimal and easily factored out as well. This leaves scattering effects due only to aerosol particles. Scattering due to cloud particles are not considered. Therefore, for a cloud-free marine environment, the extinction coefficient can be approximated by the scattering coefficient:

$$s_{scat} = \int_0^{\infty} pr^2 Q_{scat}(m,?,r) n(r) dr \quad (4)$$

where  $\sigma_{scat}$  is the extinction coefficient due to scattering, and  $Q_{scat}(m,\lambda,r)$  is the scattering efficiency factor, representing the ratio of total energy scattered in all directions to incident energy.

Optical depth, as sensed by satellite is expressed as the sum of the atmospheric extinction integrated vertically from the surface through the atmosphere and is expressed as:

$$d = \int_0^H s_{ext} dz \approx \int_0^H s_{scat} dz \quad (5)$$

where "H" represents the height of the satellite above the earth's surface. As mentioned earlier, the study is conducted under atmospheric conditions where most of the extinction is due to scatter.

### C. SCATTERING PHASE FUNCTION ( $p(y_s)$ )

The scattering phase function determines which direction the radiation is scattered when it encounters a particle. In the case of atmospheric aerosol particles, the satellite senses solar radiation that encounters a particle and is scattered into the viewing direction of the sensor. This scatter angle is illustrated in Figure 1. The scattering phase function is dependent on the size, shape and distribution of the atmospheric particles. In the case of aerosol particles, Mie theory is used to quantify the phase function. Knowledge of aerosol size distribution and composition is a necessary step in the proper assessment of the phase function. However, identifying the actual aerosol size distribution and composition over a particular region is nearly impossible. Therefore, the phase function must be parameterized. Durkee *et al.* (1991), uses the ratio of the two visible wavelength channels of the NOAA AVHRR since the ratio is sensitive to changes within the aerosol size distribution.

Using a single scatter model, there are three possible paths by which solar radiance can interact with aerosol particles and eventually reach the satellite sensor. Figure 2 displays these paths. The first path (path (a)), known as direct scatter, occurs when incident solar radiation scatters off of an aerosol particle, in a backscatter direction, directly to the satellite sensor. The other two paths are created by reflectance off of the ocean surface. Path (b) is solar radiation reflected off the ocean surface and then forward scattered ( $0 - 90^\circ$ ) off of an aerosol particle and toward the satellite sensor. Path (c) is forward scatter ( $0$  to  $90^\circ$ ) off of an aerosol particle, and then is reflected off the ocean surface and toward the satellite sensor. The reflectance off of the ocean surface can be estimated using Fresnel reflection coefficients, as shown in the following equation:

$$r_i = 0.5 \left[ \left( \frac{\sin(\theta_i - \theta_t)}{\sin(\theta_i + \theta_t)} \right)^2 + \left( \frac{\tan(\theta_i - \theta_t)}{\tan(\theta_i + \theta_t)} \right)^2 \right] \quad (6)$$

where:

$\theta_i$ : angle of reflectance

$\theta_t$ : angle of transmission

From Snells's Law,  $\theta_t = \sin^{-1}(\sin(\theta_i)/m)$  where  $m$  is the index of refraction of seawater (1.33). Combining all three scatter paths, the result is an effective phase function that is defined by:

$$p_{\text{eff}} = p_- + p_+ (r_{\mu_o} + r_{\mu}) \quad (7)$$

where:

$p_{\text{eff}}$  = effective phase function

$P_-$  = phase function at back scatter angle (90 to 180°)

$P_+$  = phase function at forward scatter angle (0 to 90°)

$r$  = Fresnel reflection coefficients at both  $\mu_o$  and  $\mu$

It is the effective phase function value ( $p_{\text{eff}}$ ) that is applied to the optical depth calculation in Eq. (2).

#### **D. SUMMARY OF ASSUMPTIONS TO THE NPS ALGORITHM**

For this study, the NPS algorithm processes AOD output by applying a simplified version of the radiative transfer theory, shown in Eq. (2). This process was accomplished by noting the following assumptions. The algorithm was applied to regions free of cloud and sun-glint. The aerosols are assumed to be spherical and non-absorbing, and the optical depth is low enough to be dominated by single scattering. These assumptions have been shown to provide reasonable results within low to moderate AOD conditions (Brown, 1997 and Smith, 1998).

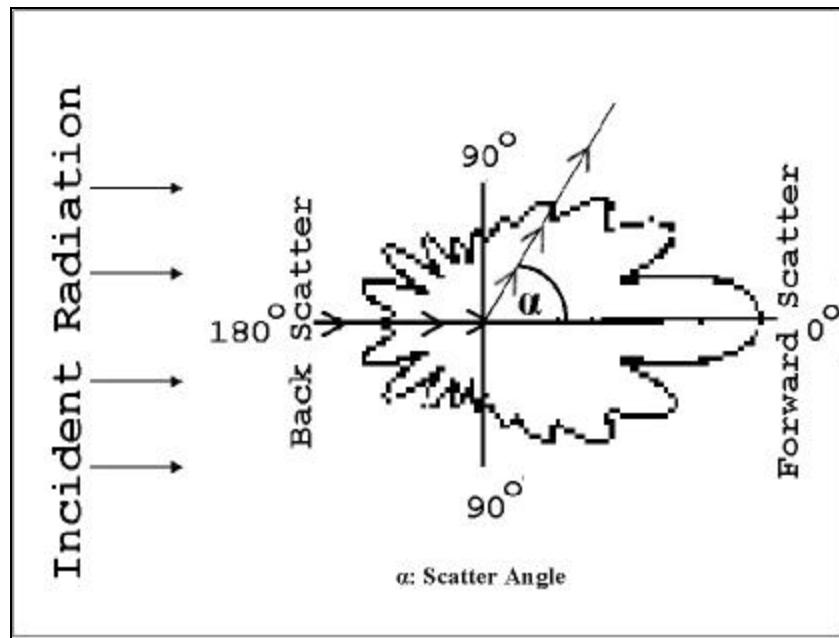


Figure 1. Polar plot of scattering phase function describing the scatter angle of incident radiation with an aerosol particle.

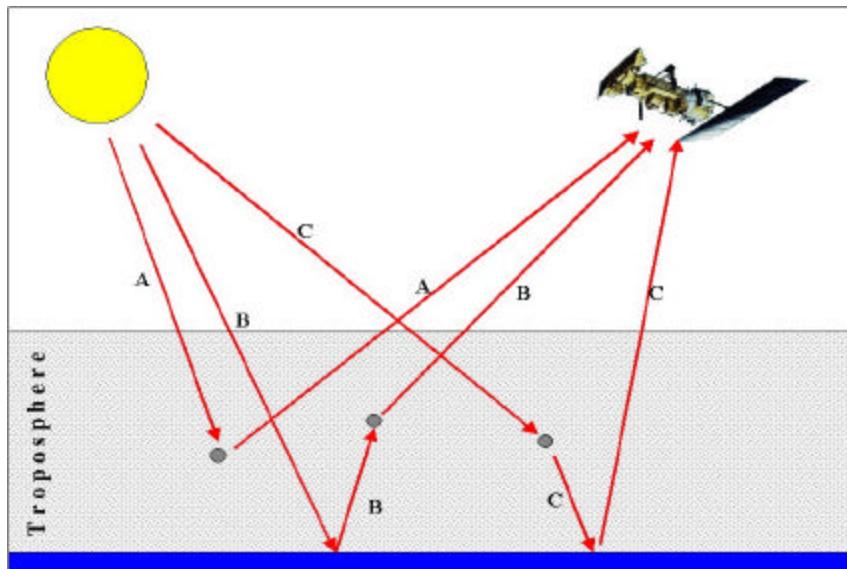


Figure 2. Schematic of solar radiation trajectories that interact once (single scatter) with aerosol particles and eventually reach the satellite sensor. Path "A" describes direct scatter while paths "B" and "C" indicate diffuse scatter.

### III. DATA

To validate the optical depth retrieval method, case study days were chosen based on the availability of matching datasets between GOES, NOAA and AERONET. This chapter briefly describes the data sets and instrumentation used for this study.

#### A. INSTRUMENTS

##### 1. NOAA Advanced Very High Resolution Radiometer (AVHRR)

The AVHRR instrument senses upwelling radiances of 5 channels, ranging from visible to infrared. Table 1 describes the bandwidths of these channels. The AVHRR instrument is part of the National Oceanic and Atmospheric Administration (NOAA) Polar Orbiting Operational Environmental Satellite (POES) series of satellites. These satellites are in sun synchronous orbit at a height of 883 km and provide at least four passes per day over a given region of the earth. The AVHRR scans at nadir with a width of approximately 2000 km and a sub-satellite pixel resolution of 1.1 km by 1.1 km.

The AVHRR instruments onboard the NOAA-14 (launched on 01 January 1995) and NOAA-16 (launched on 02 February 2001) satellites provided the data for this study. Over the experimental region, the NOAA-16 AVHRR provided the local afternoon data while the NOAA-14 AVHRR provided data late in the afternoon. The data from the NOAA-14 was at times questionable due to low sun angle problems. Therefore, the NOAA-16 data was the more reliable dataset.

The AVHRR dataset was transmitted to the receiver at Wallops Island, Virginia, and archived by the NOAA National Environmental Satellite, Data and Information Service (NESDIS) Satellite Active Archive, in Level 1b format. AVHRR Level 1b data is in 10 bit precision format that have been quality controlled, assembled into discrete data sets, and to which earth location and calibration information has been appended, but not applied to the data. Other parameters included are time, quality flags, solar zenith angles, and telemetry. All AVHRR channels are calibrated prior to launch. Channels 1 and 2 have no onboard calibration systems. Post calibration methods for these channels

were developed by the NOAA/NESDIS Office of Research Applications based on results of Rao and Chen (1995).CHECK SPACING HERE, BETWEEN TEXT AND HEADING

## **2. GOES-8 Imager**

The GOES-8 imager is part of the Geosynchronous Operational Environmental Satellite (GOES) series of satellites that covers the western Atlantic region. GOES-8, launched on 13 April 1994, operates at a geosynchronous orbit at 36,000 km over the equatorial subpoint at 75 W. Like the AVHRR, the GOES imager scans in 5 channels. However, the GOES only senses in one visible wavelength. In addition, the scanning resolution varies between channels. Table 2 provides the bandwidths of the GOES imager. For this research, only the visible channel (channel 1) data is used for the AOD calculations. Like the NOAA AVHRR, the visible channel does not have an onboard calibration system. In addition, immediately after the launch, there was a nonlinear decrease in signal strength. Compared to the AVHRR, the GOES dataset was much noisier and required several steps of adjustments before the data was comparable to the expected radiances. Chapter 4 describes these correction procedures.

## **3. AERONET Sun-sky Scanning Spectral Radiometer**

Data collected from the Aerosol Robotic NETwork (AERONET) automated radiometers are applied as ground truth of AOD for this study. AERONET contains a global network of ground-based automated radiometers, each of which consists of a CIMEL Electroniques 318A spectral radiometer that makes direct sun or sky measurements. The direct sun measurements are made in 8 spectral bands; 340, 380, 440, 500, 670, 870, 940, and 1020 nm. The 670 nm wavelength data is comparable to that used in the optical depth calculation obtained from both the GOES and NOAA retrievals. Optical depth is calculated from the spectral estimation of direct beam radiation based on the Beer-Bouguer Law. As with the NPS AOD algorithm, attenuation due to Rayleigh scatter and absorption of ozone is taken into account. In addition, contributions from gaseous pollutants are also eliminated. Detailed information about the operations and instruments of the AERONET system is provided in Holben *et al.* (1998).

AERONET data was obtained from radiometer instruments installed on three island sites: eastern Bermuda, (U.K.) (32 22'N/64 41'W), La Paguera, Puerto Rico (17

58°N/67°02'W) and Guadaloup, Island (Fr.) (16°19'N/61°30'W), all within the western Atlantic Basin (see Fig. 3). For all 3 sites, the dataset contains only the times that have not been contaminated by clouds. Data from the La Paguera site has an additional quality control check for clouds.

Table 1. NOAA AVHRR Radiometric Channels.

<b>Channel</b>	<b>Band Widths (mm)</b>
1 (visible)	0.58 – 0.68
2 (Near Infrared)	0.725 – 1.10
3 (infrared)	3.55 – 3.93
4 (infrared)	10.3 – 11.3
5 (infrared)	11.5 – 12.5

Table 2. GOES Imager Radiometric Channels

<b>Channel</b>	<b>Band widths (mm)</b>	<b>Resolution (km)</b>
1 (Visible)	0.55 – 0.75	1
2 (infrared)	3.80 – 4.00	4
3 (infrared)	6.50 – 7.00	8
4 (infrared)	10.20 – 11.20	4
5 (infrared)	11.50 – 12.50	4

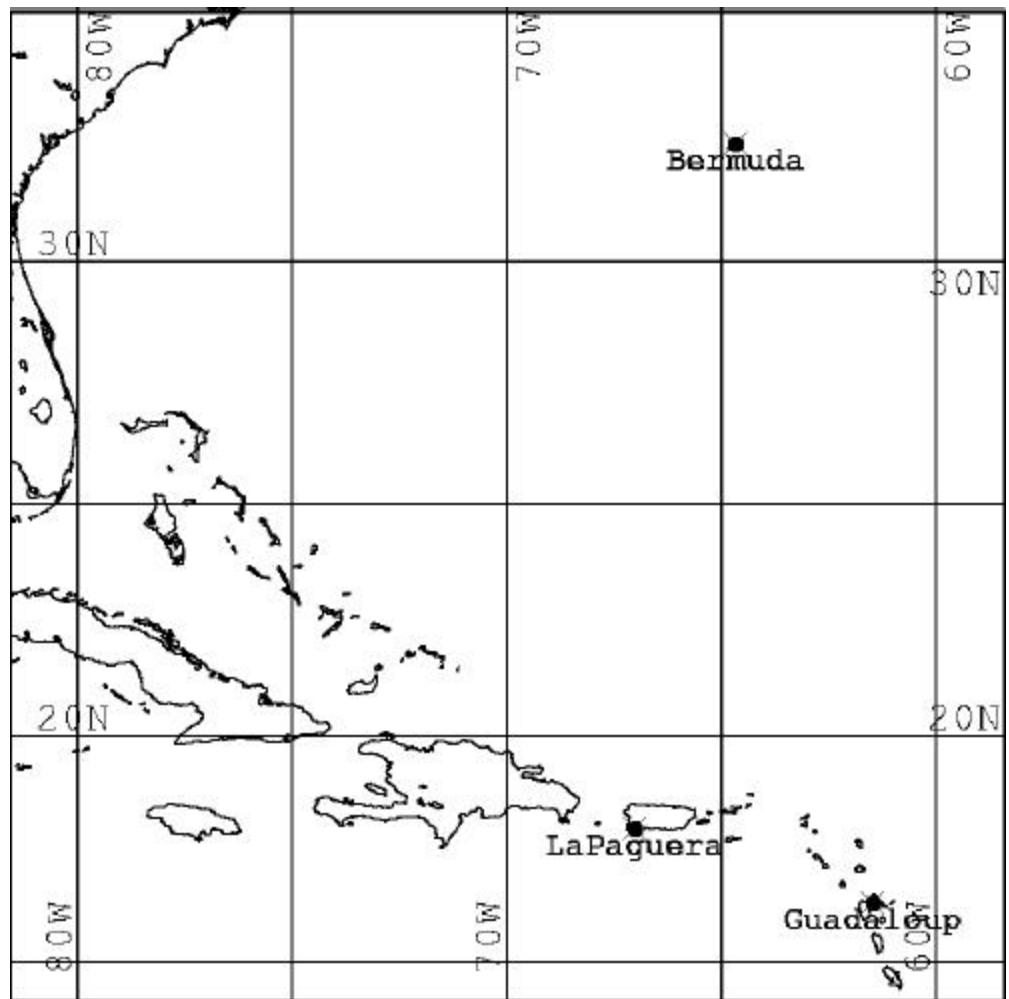


Figure 3. Map of the experimental region with locations of the AERONET stations.

## IV. METHODOLOGY

### A. SELECTION OF CASES

Datasets were collected on a daily basis from the GOES-8, NOAA, and AERONET instruments. The process started in the middle of July 2001 and lasted until the end of September 2001. GOES-8 data was collected from a Terascan receiving platform located at the Naval Research Laboratory, in Monterey, CA. The data was downloaded in a short (10 bit) format to a UNIX workstation every half-hour. GOES-8 data in August was downloaded into 8 bit instead of the 10 bit format, and was not suitable for processing. As a result, all data in August was rejected.

NOAA data was readily available through a NOAA NESDIS archives. Of the two satellite sensors, data from NOAA-16 AVHRR was more suitable than the NOAA-14 because NOAA-16 orbital passes occurred over the study region (eastern Atlantic and Caribbean Sea) during the times of interest - late morning through early afternoon. NOAA-14 orbital passes occurred during the late afternoon and its data was often rejected because of low sun angles. For both NOAA sensors, datasets were also rejected when the sun glint pattern (specular solar reflection) covered the study area. The NPS algorithm identifies and rejects the contaminated region during data processing.

AERONET data was also readily available via NASA's AERONET archive for all 3 locations. Cases were rejected if there was insufficient data covering the particular site during the local afternoon hours. These conditions usually occurred because of the presence of clouds over the AERONET radiometer's field of view, which unfortunately, is a common diurnal occurrence over all 3 islands, especially during the afternoon hours. Data was manually rejected during times that the observed AOD values showed tendencies of significant increase before a cloudy episode.

### B. GOES-8 CALIBRATION AND CORRECTION PROCESSES

Although extensive studies have shown that the NPS algorithm performed well with NOAA AVHRR data, the results using GOES-8 data were very limited. For GOES-8, there is no on-board calibration for the channel 1 radiances. In addition, there was a problem of non-linear signal degradation immediately after the launch in 1994. There

have been several attempts to perform vicarious calibration techniques to adjust for the weakening signal strength and to take into account the post-launch degradation. There is an additional problem with noise and signal radiometric resolution generated from GOES sensors. Figure 4 displays an example of radiance comparisons between the calibrated GOES and AVHRR datasets. The image passes occurred at a similar time and were registered over the same 100 km by 100 km domain surrounding Bermuda. In addition, both satellites had similar viewing geometries (scatter angles were  $\pm 0.1^\circ$  of each other). The atmospheric conditions immediately south of Bermuda (outlined in red) were clear and homogeneous at this time. The panel to the right of Figure 4 are plots of the histogram frequency distribution of radiances that were extracted within the outlined region. As expected, the NOAA-16 image in (b) displays a relatively homogeneous field of radiances; its corresponding frequency histogram displays shows a pronounced signal peak with a narrow radiometric width, indicative of the pristine atmospheric conditions. In contrast, the GOES-8 sensor, situated in an orbit that is 40 times the distance of the NOAA sensor, produces an image (shown in (a)) that is significantly noisier; its corresponding histogram profile displays a weaker signal peak and wider radiometric range. As atmospheric conditions become hazier, the GOES-8 peak signal and radiometric resolutions become even less discernable, thus complicating the processed AOD calculations. In addition, the GOES-8 signal peak at  $\sim 16 \text{ Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$  is significantly weaker than the NOAA-16 signal peak at  $\sim 22.5 \text{ Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$ , thus necessitating a further correction factor to GOES-8 for further processing.

For this study, in order to match GOES with NOAA data during AOD processing, two correction techniques were applied to the GOES channel 1 radiance data. Dr. C. R. N. Rao (personal communication in July, 2000) developed a calibration methodology of GOES-8 channel radiance by a vicarious technique, selecting a radiometrically stable calibration site located in the Sonoran desert ( $34.0^\circ\text{N}/114.1^\circ\text{W}$ ). Radiometrically stable calibration is defined as the long term mean value at the top of the atmosphere albedo that remains uniform in time. Details of this method can be found in Rao and Zhang (1999) and Rao *et al.* (1999).

Dr. Rao developed a simplified version of the correction factor (gain factor) that can be expressed in the following equation:

$$GAIN\_FACTOR = \frac{A(d;post)}{A(pre)} = 1.192 * (1 + 1.688E-04 * d) \quad (8)$$

where:

$d$  = number of days since the launch date of the GOES-8 satellite

$A(pre)$  = albedo (%) calculated using the pre-launch calibration coefficients

$A(d;post)$  = albedo (%) calculated on day ‘ $d$ ’ after the launch of GOES-8, that accounts for degradation in orbit

Table 1 in Appendix A lists the calibration factor applied to GOES-8 for each case study day in this report. However, a preliminary assessment of the calibrated GOES data indicated that its resulting AOD values were significantly higher than the NOAA-generated AOD as well as the AERONET observations of AOD. Therefore, a further correction method was applied, as discussed below.

The correction technique involved comparisons between GOES-8 and NOAA-16 channel 1 radiances, whose wavelengths, centered on 0.65 and 0.63  $\mu\text{m}$ , respectively, were similar. The assumption is that the calibrated AVHRR channel 1 radiances are accurate. The process involved the collection of a sample of cases when the GOES and NOAA viewing geometries over a selected location were similar. GOES and NOAA viewing geometries were defined as ‘similar’ when the scatter and azimuth angles were within  $\pm 0.1^\circ$  of each other. Figure 5 presents the comparisons over 296 pairs of GOES and NOAA channel 1 radiances. As shown, the radiance ranged along the low end of the radiance spectrum ( $0$  to  $40 \text{ Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$ ) which is where the detection of aerosols would occur. As shown, there was very poor correlation between the NOAA and GOES data, due to the large noise problem in GOES. As a plausible correction, it was decided to perform a manually-determined selection of the “center of mass” within the domain shown in Figure 5. Using the Cartesian coordinates, the selected center of mass of the distribution was positioned at point Y (NOAA axis) =  $24.0 \text{ Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$  and point X

(GOES axis) =  $19.0 \text{ Wm}^{-2} \text{sr}^{-1} \mu\text{m}^{-1}$ . Assuming there is a linear relationship between the channel 1 radiances of GOES and NOAA, the correction factor was determined by locating the X (GOES) intercept from the slope (red dashed line), which was estimated to be  $5.5 \text{ Wm}^{-2} \text{sr}^{-1} \mu\text{m}^{-1}$ . Therefore, before the actual AOD processing took place, the correction ion factor was added to the calibrated value of the GOES channel 1 radiances.

### C. AOD RETRIEVAL FROM SATELLITE DATA

Figure 6 displays a flowchart to the steps involved in the processing of the satellite data. A software algorithm (hereafter referred to as the “NPS algorithm”) was developed by Brown (1997), and then modified by both Smith (1998). The NPS algorithm consists of 3 major parts: pre-processing, processing, and post-processing. For the pre and post-process stages, a combination of Terascan, Cshell and PERL software manipulate the data. During the processing stage, the satellite data is processed and converted to AOD values by code written in FORTRAN 77.

#### 1. Pre-Processing Stage

For the preprocessing portion, the NOAA AVHRR raw data is initially converted from Level 1b to Terascan data Format (TDF). The data is then calibrated from raw radiance counts into albedo (%) from the visible wavelengths (channels 1 and 2), and temperature ( $^{\circ}\text{K}$ ) within the near IR and IR wavelengths (channels 3, 4, and 5). The GOES raw data is already in this format. Both the GOES and NOAA data then have the earth-sun-satellite geometry angles attached to the data, which consists of the solar and satellite zenith angles, the azimuth angle and the scattering angles. These angles were obtained from the telemetry dataset stored within Terascan. Next, the data is registered in Mercator coordinates to a predetermined area. For this study, the areas consist of 200 km  $\times$  200 km domains surrounding Bermuda, La Paguera, Puerto Rico, or Guadalupe Island. The final stage in the preprocessing is the conversion of the data from TDF to binary format for the next stage.

#### 2. Processing Stage

During the process stage, the radiances are converted to AOD for both GOES and NOAA data. For GOES, the channel 1 radiances data is initially calibrated and a correction factor is applied following the process described in the previous section. For

both datasets, sun glint contamination is removed by applying a method used by Cox and Munk (1954).

AOD is calculated following Eq. (2),

$$d_a = \frac{(4\mu L_a)}{(\alpha_o F_o p(\alpha_s))}.$$

The cosine of the satellite zenith angle ( $\mu$ ), the single-scatter albedo ( $\alpha_o$ ), and the solar radiance ( $F_o$ ) are all constants. Radiance due to aerosol scatter ( $L_a$ ), is mathematically straightforward and is described in detail by Brown (1997). The scattering phase function,  $p(\alpha_s)$ , is obtained from a process described below.

#### *a. Scattering Phase Function Processing*

Obtaining the scattering phase function values requires knowledge of the aerosol characteristics and size distribution, which is not routinely available. Therefore, the scattering phase function must be parameterized. Durkee *et al.* (1991) developed the parameterization technique used within the NPS algorithm. The technique consists of calculating the ratio of the NOAA channel 1 and 2 radiances, ' $S_{12}$ '. The scattering efficiency ( $Q_{scat}$ ) of an aerosol distribution is wavelength dependent and peaks when the radius of the aerosol particle is nearly equal to that of the radiation wavelength. As a result,  $S_{12}$  will be larger for smaller size particle distributions and smaller for larger size aerosol particle distributions.  $S_{12}$  varies from pixel to pixel. Therefore, variations in the aerosol size distribution can be detected within the pixel resolutions of the satellite image data.

Brown (1997) generated seven models of aerosol size distributions. These models typify general conditions within the maritime environment. The scattering phase function and extinctions for these models were calculated using Mie theory. Table 3 describes the attributes for each of the 7 models. These distributions consist of one single-mode and 6 two-mode log normal distributions with varying radii and standard deviations used to describe variations of aerosol distribution widths in the maritime atmosphere. Figures 7, 8, and 9 illustrate the effect of the aerosol size distribution models on  $S_{12}$  and the scattering phase function (developed by Brown, 1997). Figure 10

is a composite chart that illustrates the actual phase function extraction process. This process only applies to NOAA processing. For each pixel, the combination of the scatter angle and the computed  $S_{12}$  value is entered into a lookup table (LUT) represented in the upper left portion of Figure 10 to determine the model aerosol distribution that is consistent with the measured  $S_{12}$ . An aerosol model index (AMI) is interpolated between models M0 and M6. In the example shown, the interpolated value is situated between Models M2 and M3 (i.e., AMI is approximately 2.5). The AMI values are collected for each pixel and stored in a file. During the GOES processing, this data from the AMI file is accessed. For both GOES and NOAA processes, the next and final step to the NOAA phase function processing is entering the AMI value with the scatter angle to the scattering phase function LUT, as graphically represented in Figure 4.4 and in the lower left portion of Figure 10. For GOES processing, the AMI values are assumed to be constant during the entire time period. At this stage, all of the input parameters have been determined and the AOD is calculated using Eq. (2).

### 3. Post-Processing Stage

During the post-processing stage, all of the original channel data, calculated data, and extracted scattering phase function values are reformatted back to TDF; this data is in image form and can then be viewed and analyzed via the Terascan visualization software. Table 4 lists the output products generated by the NPS algorithm. For this study, only the channel 1 AOD is calculated for the case study analysis.

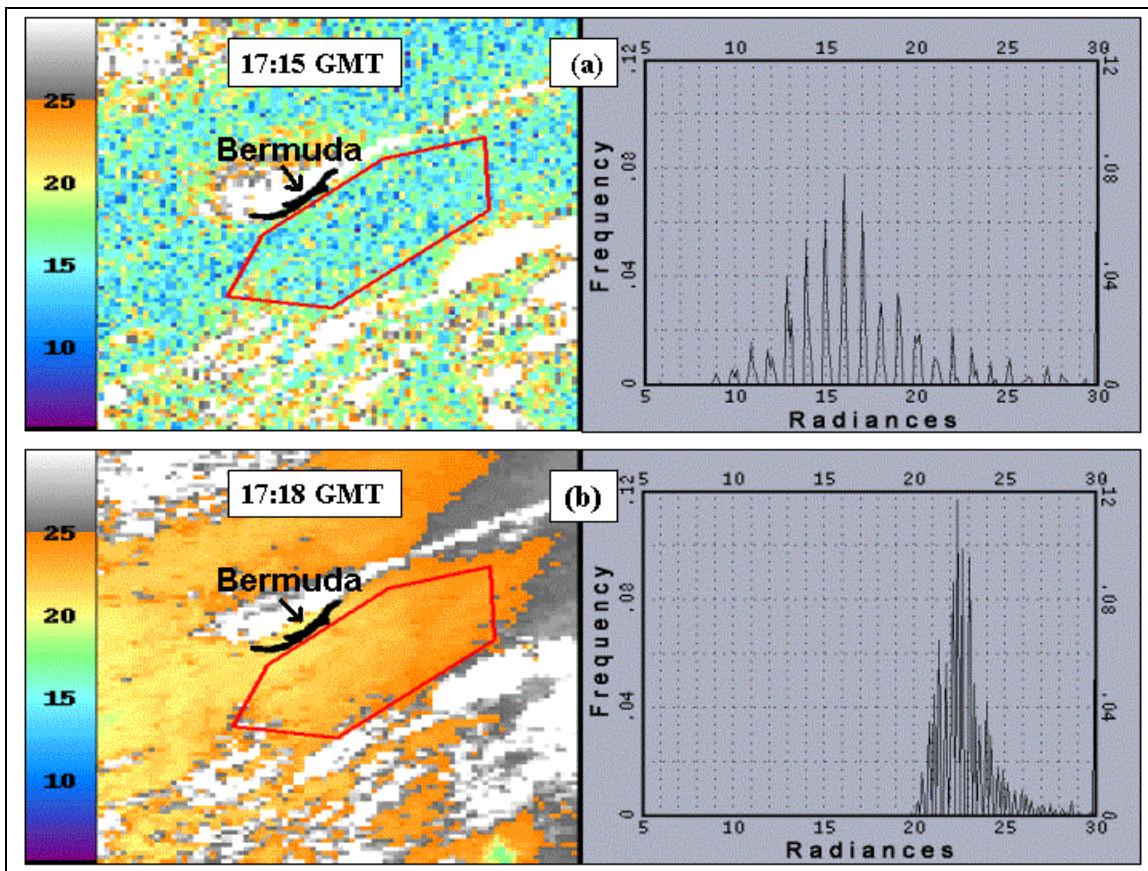


Figure 4. Comparisons of radiance images and associated frequency of radiance histograms between (a) GOES-8 and (b) NOAA-16 on 02 September 2001. Histograms were developed from areas within red annotations. Radiances, as shown within the color legend and the histogram x axis, are in units of  $\text{Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$ .

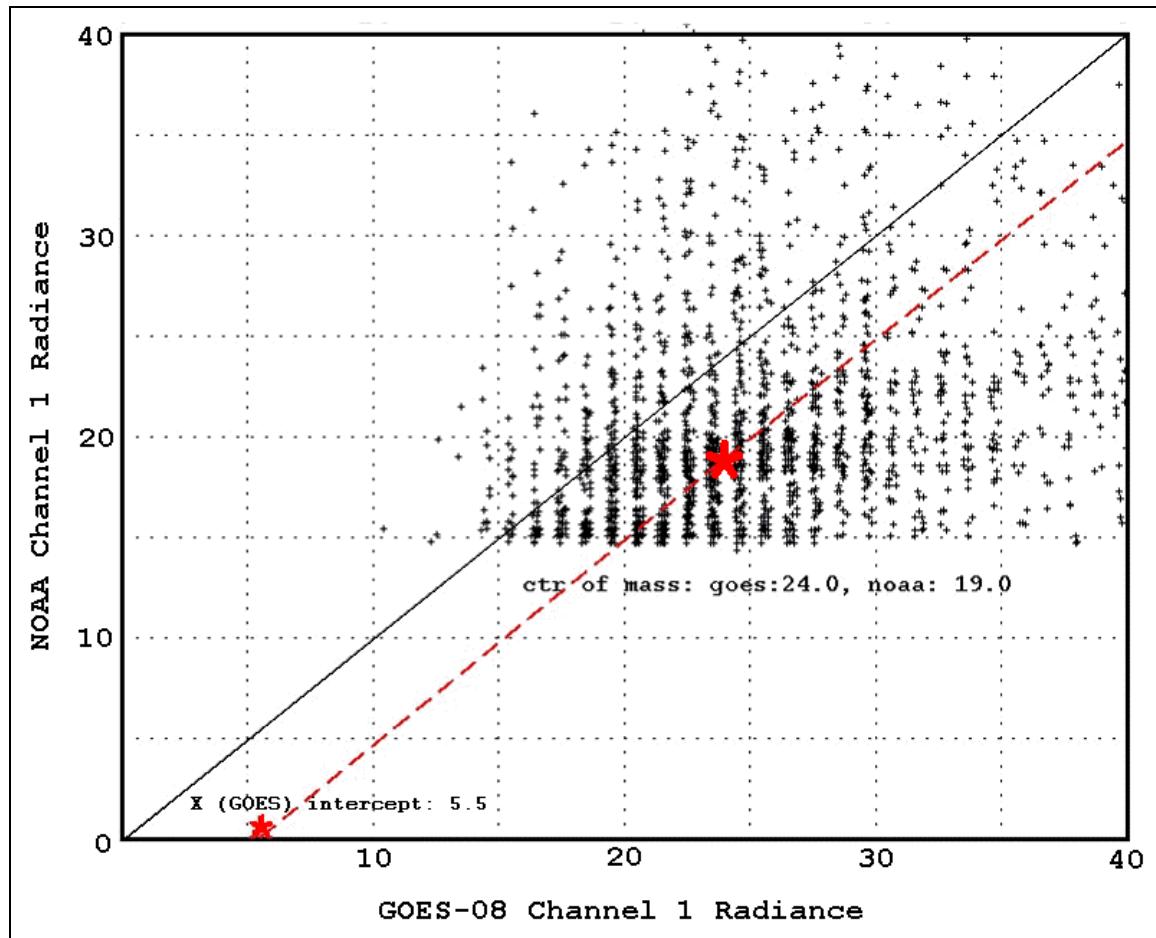


Figure 5. Comparisons of Channel 1 radiances between GOES-8 and NOAA-16.  
Radiances are in units of  $\text{Wm}^{-2}\text{sr}^{-1}\mu\text{m}^{-1}$ .

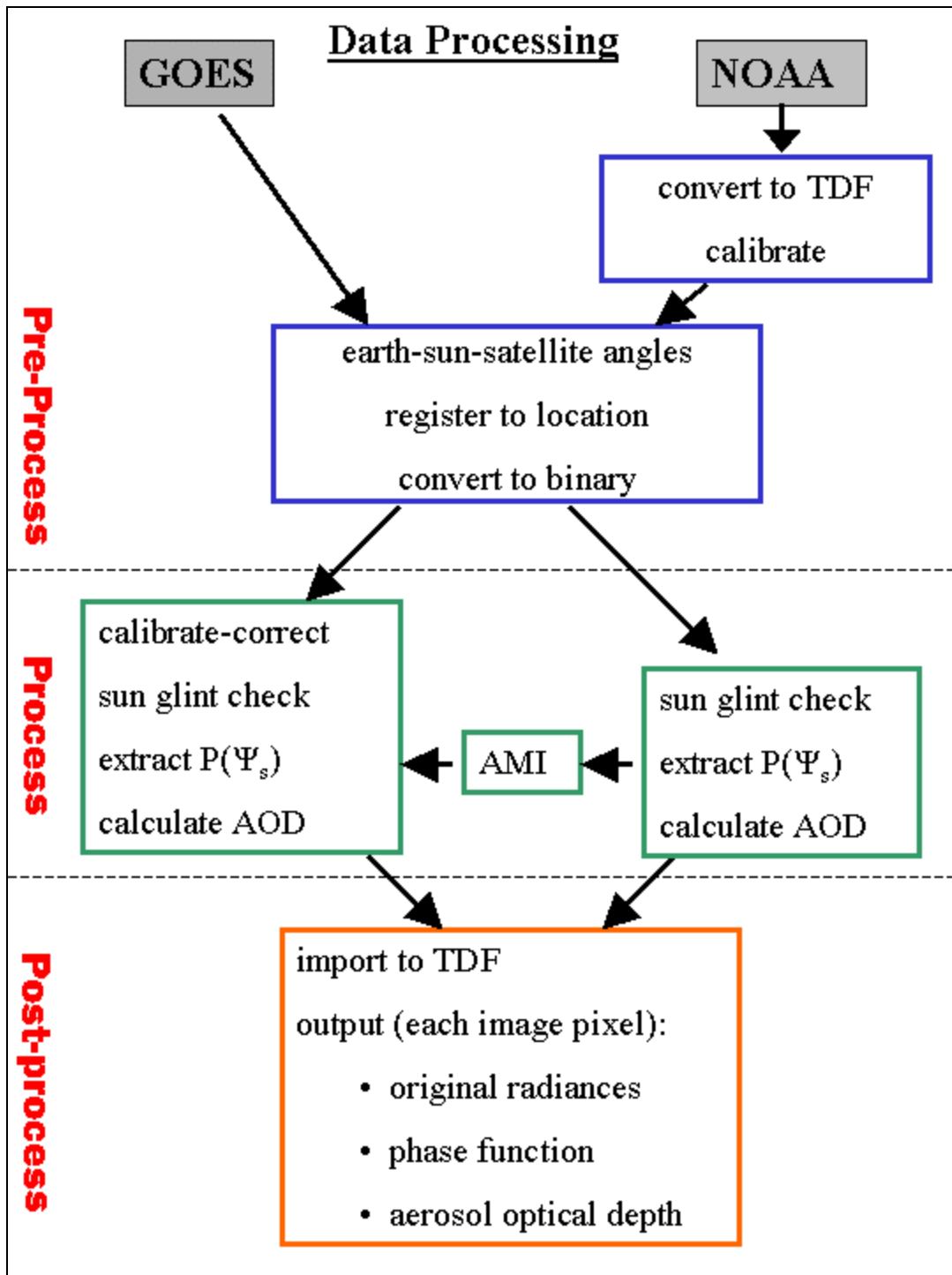


Figure 6. Satellite AOD retrieval process (portions obtained from Brown, 1997).

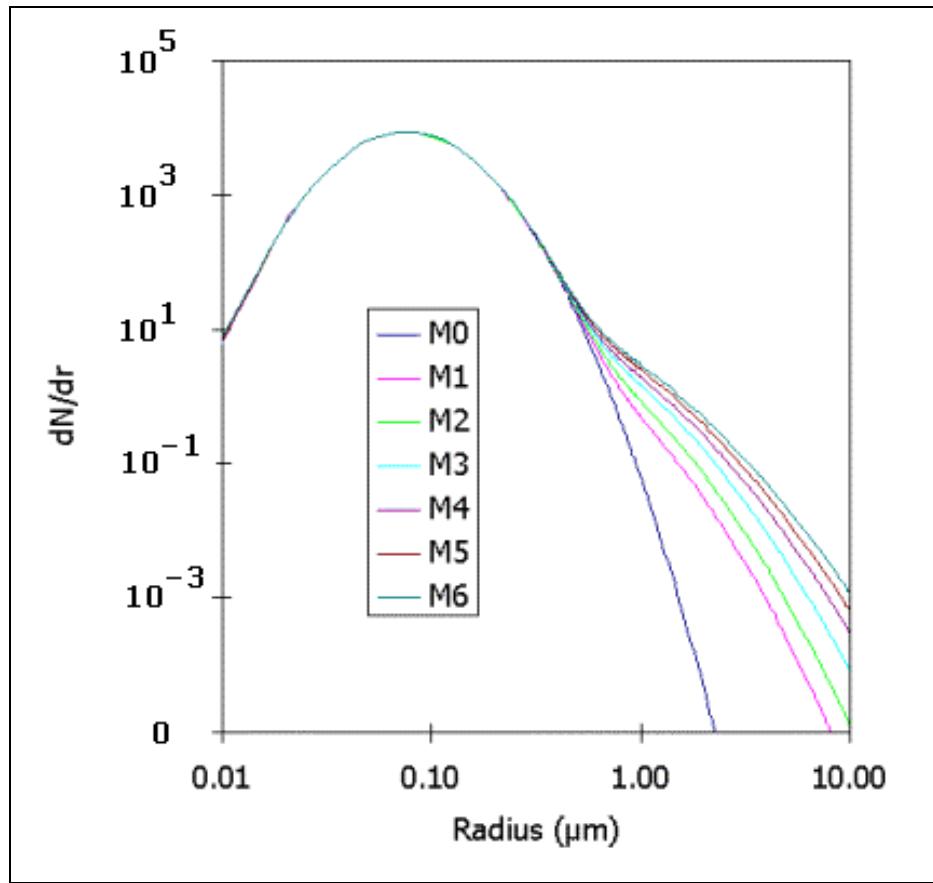


Figure 7. Model aerosol size distributions (from Brown, 1997).

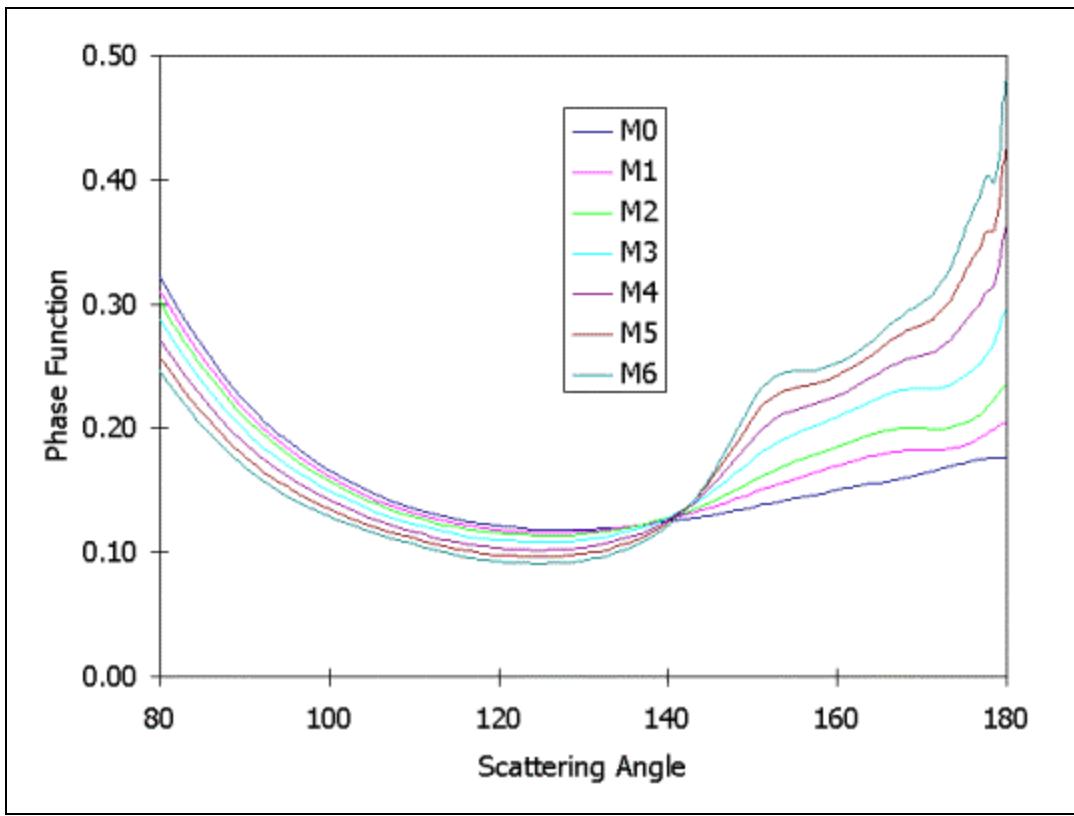


Figure 8. Model phase functions for NOAA's channel 1 (visible wavelength) (from Brown, 1997).

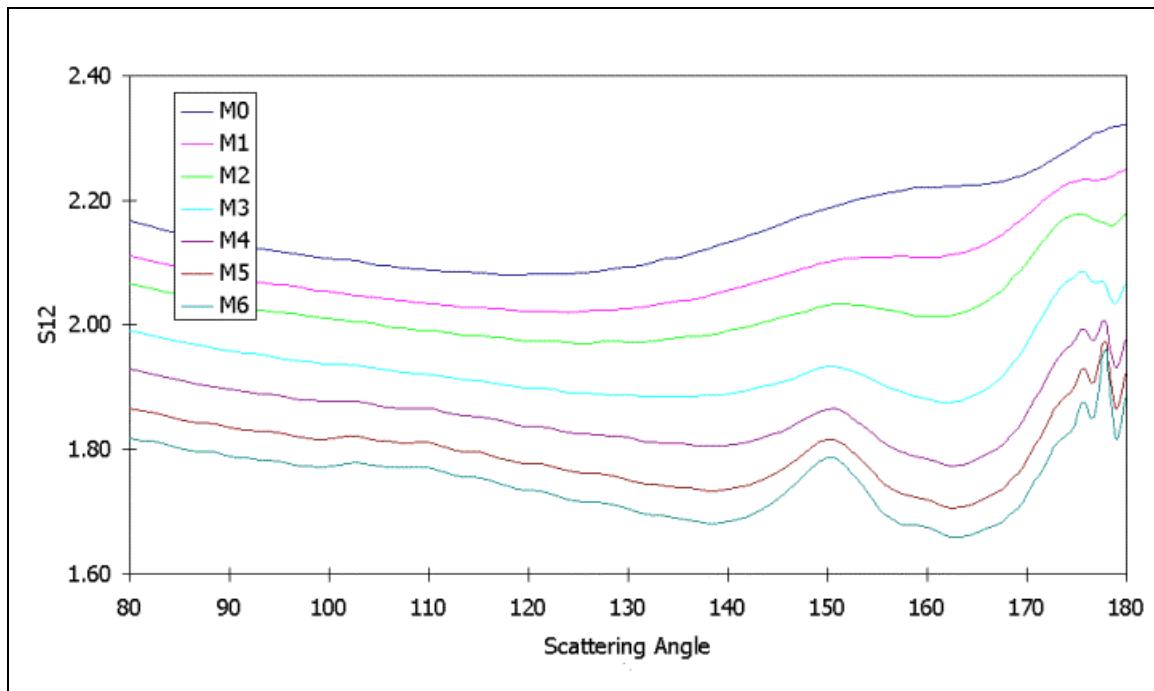


Figure 9. Model S12 values (from Brown, 1997).

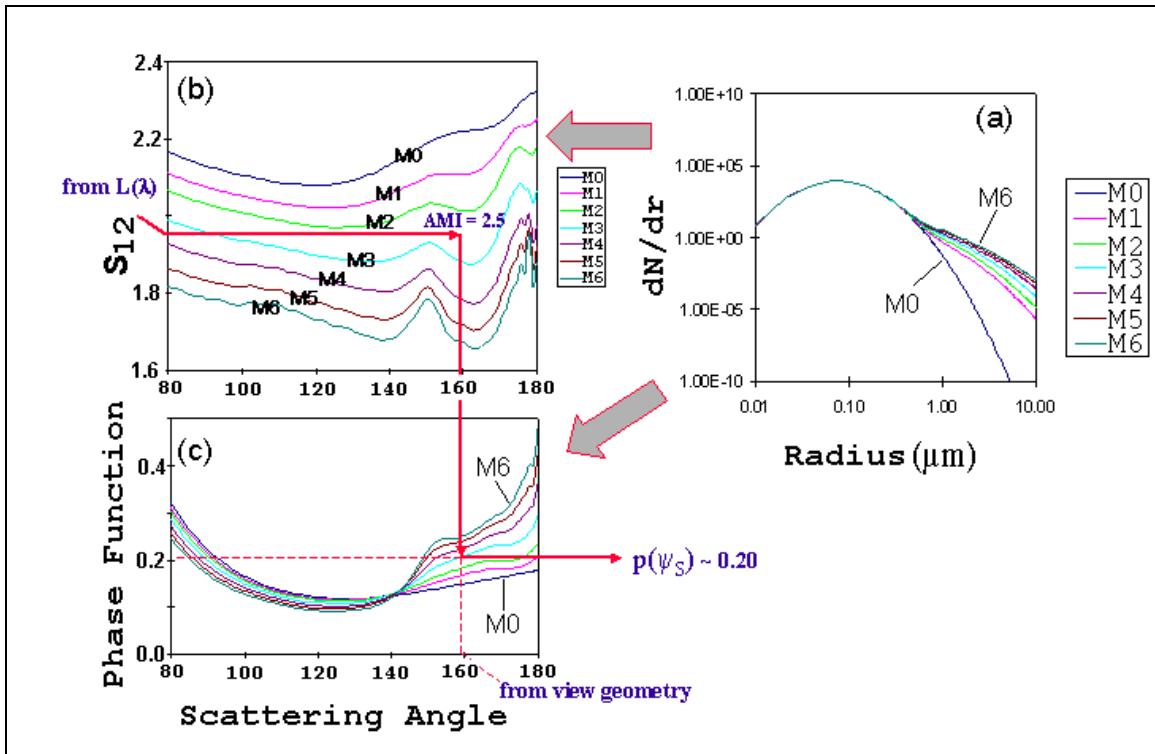


Figure 10. Parameterization of the scattering phase function,  $p(\psi_s)$ , is described. (a) Aerosol model size distributions. (b) size index,  $S_{12}$ , (c) scattering phase function calculated from the model size distributions as a function of scattering angle. (portions of figure obtained from Durkee *et al.*, 1999.)

Table 3. Characteristics for each of the 7 models of the aerosol size distribution. Mode 1 models the background aerosols while Mode 2 models the ocean-produced aerosols.

Model	Mode Radii ( $\mu\text{m}$ )		Number density (N)		Std dev (s)	
	Mode 1	Mode 2	Mode 1	Mode 2	Mode 1	Mode 2
M0	0.1	0.0	1000	0	1.7	0.00
M1	0.1	0.3	1000	3	1.7	2.10
M2	0.1	0.3	1000	5	1.7	2.20
M3	0.1	0.3	1000	8	1.7	2.35
M4	0.1	0.3	1000	10	1.7	2.51
M5	0.1	0.3	1000	13	1.7	2.60
M6	0.1	0.3	1000	15	1.7	2.70

Table 4. List of the output products for each pixel within the image file as generated by the NPS algorithm for both GOES and NOAA data processes.

<b>GOES-8 products</b>	<b>NOAA-14 and 16 products</b>	
Channel 1 total radiance	Channel 1 total radiance	Channel 2 total radiances
Channel 1 Rayleigh radiance	Channel 1 Rayleigh radiance	Channel 2 Rayleigh radiance
Channel 1 aerosol radiance	Channel 1 aerosol radiance	Channel 2 aerosol radiance
Satellite zenith angles	Satellite zenith angles	
Solar zenith angles	Solar zenith angles	
Relative azimuth angles	Relative azimuth angles	
Scatter angles	Scatter angles	
Channel 1 phase functions	Channel 1 phase functions	Channel 2 phase functions
Channel 1 AOD	Channel 1 AOD	Channel 2 AOD
	Ratio of channel1 and channel2 (S12)	
	Aerosol Model Index (AMI)	

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## V. RESULTS

For this study, 22 cases were selected to analyze the performance of the NPS algorithm in providing satellite-derived AOD calculations. In this chapter, Section 5.A discusses the results in a clear environment and Section 5.B. discusses conditions within a dust environment. Finally, Section 5.C summarizes all 22 cases.

### A. CASE 25 SEPTEMBER 2001. LOW AOD CONDITIONS OVER BERMUDA

#### 1. Synoptic Discussion

Figures 11a and b present composites of true color images generated by the polar orbiting sun synchronous Sea-viewing Wide Field of view Sensor (SeaWiFs). SeaWiFs is operated and managed by NASA's Goddard Space Flight Center and orbits the earth at an altitude of 705 km with a 1.1 km resolution at nadir. Although SeaWiFs is primarily designed to sense ocean surface properties, a benefit to meteorological research is its ability to detect atmospheric aerosol characteristics at high spatial resolutions. As shown in Figures 11 a and b, dust is quite visible west of Africa, and extends westward into the center of the Atlantic Ocean basin. The region surrounding Bermuda is within a clear environment, situated north of the dust and east of sulfate concentrations.

Figure 12 displays dust and sulfate concentrations as generated by the Navy Aerosol Analysis and Prediction System (NAAPS) (see Westphal, 2002) on 25 September 2001 at 18:00 UTC. In this figure, the NAAPS image was formatted to display both dust and sulfate concentrations with minimum optical depth thresholds of 0.1. As in Figure 11, Figure 12 depicts a clear environment surrounding Bermuda during the time of this case study. The 850 mb wind field pattern in Figure 12 suggests that the region surrounding Bermuda will remain clear during the immediate time period.

Figure 13 is a visible image of GOES-8 at 17:15 UTC, which is situated about local noon in the center of the image. As shown, the island of Bermuda is situated south of an eastward moving intense tropical depression. Bermuda is also located east of a strong cold front moving off of the US Atlantic seaboard. The immediate region surrounding Bermuda is within light convective activity. The associated scattered clouds

remain around the island throughout the day, but did not impact the AOD calculations conducted over water just east of the island.

## 2. AOD and Phase Function Analysis

Figures 14 and 15 show a series of AOD images processed by the NPS algorithm from GOES-8 data. The images occur every 60 minutes from 13:15 UTC to 20:45 UTC. The bright white and adjacent yellow features depict small-scale cumulus clouds surrounding Bermuda. The general aerosol conditions around Bermuda have very low AOD values, ranging from 0.0 to 0.1. Throughout the time range, clear conditions persist just east of the island. The location of the AERONET station is on the eastern edge of the island. The annotated boxes represent the locations where histogram measurements of center of mass took place. The boxes were manually selected and have approximate dimensions of 20 km  $\times$  20 km. Throughout the time period, the average distance between the AERONET station and the center of the box was approximately 25 km. As shown, clouds are always nearby, but do not interfere with AOD measurements within the boxes.

As discussed in Chapter 4, the GOES-8 data is quite noisy. In contrast to Figures 14 and 15, the NOAA-generated AOD image in Figure 16 is much smoother (less noise). Extracting reasonable AOD values from GOES and then comparing these values directly to AERONET observations was not a straightforward process. The following approach to both GOES and NOAA-generated AOD provided reasonable estimates to the study.

The method of measuring AOD is presented in an example within the frequency histogram plot in Figure 17. A curve is manually drawn (as shown by a solid red curve) representing the the frequency distribution of AOD. Then, the mode of the distribution was determined. As shown in the figure, the mode for this example translates to an AOD value of 0.03. The values on either side of the AOD value ( $\pm 0.11$  and  $+0.15$ ) describe the variability about the AOD estimate. As mentioned earlier, GOES sensing generally has a wider range of radiances than NOAA data. These values were obtained by drawing a horizontal bar at a level that is half of the maximum peak of the normalized curve. Figures 18, 19, and 20 display all of the corresponding sets of histograms for each of the red boxes annotated within the images presented in Figures 14, 15, and 16.

Figure 21 presents the time series plot of AOD obtained from Figures 18, 19, and 20. There is one NOAA measurement obtained at 18:16 UTC. “Variability” bars are plotted for each measurement. Because of the inherent noise within the GOES-8 radiances, the variability of AOD is significantly higher for GOES-8 ( $\Delta$ :  $\pm 0.10$  to  $0.15$ ) than NOAA data ( $\Delta$ :  $\pm 0.02$ ). Although AOD values can never fall below zero, the first two GOES points (Time = 13:15 UTC and 13:45 UTC) produce slightly negative AOD values, due again to the noise associated with GOES data. As shown, there is good agreement between the AERONET and GOES-derived AOD after about 17:00 UTC. The AVHRR-derived AOD value of 0.12 is significantly greater than the corresponding AERONET observed value of  $\sim 0.05$  at 18:16 UTC. Included within Figure 21 is the scatter angle pattern shown in a dashed line. Because of the geometric configuration between the sun and GOES-8 satellite, local noon occurs approximately where the scatter angle position is at its peak, which is also the closest to a direct backscatter configuration between the sun and satellite sensor. As time increases, the GOES-8 – sun geometry results in more of a side scatter. This geometry affects the phase function determination, which is discussed below.

Figure 22 displays the phase function values generated from both the NPS algorithm and AERONET observations. The satellite-derived phase function values (blue diamonds) are obtained from the algorithm’s lookup table, as described in Chapter 4. The corresponding red square at each scatter angle represents the phase function value required for the satellite-derived AOD to match AERONET AOD. As shown, all values are within the backscatter portion ( $90^\circ$  –  $180^\circ$ ). This figure provides an evaluation tool to determine the proper phase function pattern, given the aerosol conditions for a particular case. In this case, the AERONET phase function values are consistently lower than the satellite-derived phase functions.

## **B. CASE 18 SEPTEMBER 2001. HIGH AOD CONDITIONS OVER GUADALOUPE ISLAND**

### **1. Synoptic Discussion**

During the summer months, dust generated from the African deserts are often propagated across the southern latitudes of the Atlantic Ocean basin by the easterly trade winds, oftentimes impacting the visibility and aerosol characteristics over regions of the

Caribbean and the east coast of the US. For this case, the SeaWiFs images in Figures 23a and b display several pockets of dust plumes, one of which is approaching the island of Guadalupe on 17 September (Figure 23a). One can surmise that the plume has crossed over Guadalupe a day later on 18 September (Figure 23b). On 18 September, the scattered small cumulus clouds surround the Guadalupe Island region.

The NAAPS model in Figure 24 shows the leading edge of a significant dust plume ( $AOD > 1.0$ ) reaching Guadalupe on 18 September at 18:00 UTC. Contours of very high optical depth values ( $AOD > 0.4$ ) are shown within this plume.<sup>1</sup> The 850 mb wind pattern at 18:00 UTC supports the continuing propagation of the dust plume over the Guadalupe and Caribbean regions.

The GOES-8 image in Figure 25 displays a large region of aerosol dust surrounding the Guadalupe Island region (inside the annotated box). A large cloud mass just to the north of Guadalupe Island region eventually propagated south over the study region, which impacted some of the AOD measurements later in the day.

## 2. AOD and Phase Function Analysis

Figures 26 and 27 present the AOD images generated by the NPS algorithm on GOES-8 data. The time range for this study is from 1645 UTC through 2045 UTC. The data from NOAA-16 at 17:50 UTC and NOAA-14 at 21:16 UTC provided the aerosol model index (AMI) to the GOES AOD calculations; these AOD images are displayed in Figure 28. The locations of AOD measurements are shown by the red boxes annotated within Figures 11 and 12. A large cloud field is shown to be propagating southward toward Guadalupe Island throughout the time period. As a result, AOD measurements between 19:15 and 20:15 UTC were omitted due to cloud contamination.

Figure 29 shows the frequency histograms used to obtain AOD values derived from GOES-8 and NOAA-16. AOD values range from 0.33 to 0.48. As the cloud field began impacting the Guadalupe Island region, measurements of AOD were becoming increasingly difficult after 18:45 UTC. The normalized distribution pattern shown in Figure 29 became flatter, resulting in larger variability.

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<sup>1</sup> NAAPS optical depth values do not directly correspond to the AOD values obtained either by the NPS algorithm or AERONET observations.

Figure 30 presents the time series of AOD for this case. Both the GOES-generated AOD and the AERONET observations of AOD are in good agreement, with high AOD values throughout the time period. As mentioned earlier, cloud contamination resulted in limited AOD measurements after 19:15 UTC. The lengths of the variability bars associated with GOES-8 data increased with time. As a result, the proper selection of AOD measurements became increasingly more difficult. The AOD generated from the NOAA-16 data at 17:50 UTC (AOD  $\sim 0.45$ ) and the NOAA-14 data at 21:17 UTC (AOD  $\sim 0.48$ ) are also in agreement with AERONET observations. Based on the scatter angle profile, local noon occurred toward the beginning of the time period ( $\sim 16:45$  UTC). The AOD from AERONET observations tend toward higher values than the satellite-derived AOD during the early afternoon hours. The reverse occurs later in the day.

Figure 31 displays the phase function value profiles from satellite and AERONET data. As in the previous case (Figure 22), the AERONET phase function values are consistently lower than the satellite-derived phase functions. Due to the limited dataset, there was not a distinct phase function pattern to describe this dust environment. The next chapter will address this issue more clearly.

### C. RESULTS FROM 22 CASES

Table 1 in Appendix A lists the dates, times and locations of all of the cases in this study. The data was selected based on the availability of both satellite and AERONET data. Also, entire case study days were rejected when the NOAA data was contaminated by sun glint within the region of study.

Appendix B presents the AOD charts for all 22 cases. Most of the cases have AOD profiles that are fairly dust-free ( $d_a < 2.5$ ). The exceptions are cases 2, 7, 8, 12, 14, 16, and 20. Unfortunately, for the high dust cases, data for the analysis is usually limited because there tends to be more cloud contamination surrounding all 3 islands within the study. As a result the contaminated data are filtered out of the case studies. Within the GOES-8 data, local noon occurs during the peak of the scatter angle, between 16:45 and 17:15 UTC in September. During the late afternoon hours, the AOD profile becomes more questionable, as shadows from nearby clouds might affect the clear regions. Special care was taken to avoid these problem areas.

For each case, measurements were taken in such a way as to compare AOD between AERONET and satellite images as close to each other as possible without land or cloud contamination. Figure 32 presents the measurement distances between the satellite-derived AOD and the AERONET observations. The easiest region for measurements was Bermuda, with an average distance of 19 km between AERONET site and the satellite-derived AOD measurement. The islands of Guadalupe and Puerto Rico contain topography that often produces orographically enhanced cloud cover on a diurnal scale. To avoid cloud contamination, there were several instances where measurements had to be deviated by as much as 80 km from the AERONET site. Measurements were still conducted in regions further away, so long as the representative AOD value could be determined.

### 1. Evaluation of the NPS Algorithm

Figure 33 compares satellite-derived AOD data with AERONET ‘ground truth’ observations for all 22 cases. Within low AOD conditions ( $\delta_a < 0.2$ ), there is a slight bias for NOAA-derived AOD values toward higher values. The GOES-derived values have a slight bias toward lower AOD values. Within dust conditions ( $\delta_a > 0.25$ ), there is a bias within the NPS algorithm to an underestimate AOD. Similar findings found by Smith (1998) attributed the probable cause to the “no absorption” assumption ( $\omega_o = 1$ ) within the NPS algorithm. As shown in Figure 33, the overall standard error for AOD measurement is 0.066. For the regression analysis, the GOES and NOAA combined results in an  $R^2$  of 0.67. Individually, the NOAA regression is 0.62 while the GOES regression is higher at 0.67.

Another method to evaluate the performance of the NPS algorithm was to determine whether there was bias in AOD calculations due to varying geometries between the sun and satellite positions. Figure 34 is a display that categorizes several regression parameters into scatter angle categories. As mentioned earlier, due to the position of the study areas and the fixed location of the GOES-8 satellite, local noon occurs around the peaks of scatter angles (total backscatter). Therefore, in Figure 34, the scatter angle category of  $170^\circ - 180^\circ$  (complete backscatter) is within the region of local noon.  $R^2$  describes the degree of correlation between satellite-derived AOD and

AERONET data. For example,  $R^2 = 0.40$ , indicates that 40% of the original variability of the satellite-derived AOD can be explained, with a remaining 60% of residual variability. As shown within the bar patterns of Figure 34,  $R^2$  values are highest about  $140^\circ - 150^\circ$  ( $R^2 \sim 0.72$ ) and at  $170^\circ - 180^\circ$  ( $R^2 \sim 0.76$ ). Corresponding standard error (S.E.) values are at their lowest within the scatter angle categories of  $130^\circ - 140^\circ$  and  $170^\circ - 180^\circ$ , respectively. A possible explanation for the higher accuracy about 140 degrees could be that the model phase function table of values used within the NPS algorithm converge toward one value at  $\sim 140$  degrees. Therefore, there are no aerosol size distribution selection errors at this scatter angle.

Figure 35 displays the phase function analysis for the 22 cases within dust conditions  $\delta_a = 0.25$ . Satellite-derived phase functions (blue dots) and the phase functions required to match the AERONET AOD (red dots) are shown. Between  $140^\circ$  and  $180^\circ$ , phase function values generated by the NPS algorithm indicate a pattern of higher curvature than that of AERONET-based phase functions. This result is consistent with work conducted by Collins *et al.* (2000) in the ACE-2 experiment off the west African coast (upstream from the PRIDE region). Figure 36 presents their findings. Beyond the scatter angle of  $140^\circ$ , non-spherical dust particles were observed to produce a flatter phase function shape than non-dust conditions. Figure 37 shows the 7 aerosol size distribution models used in the NPS algorithm with the normalized phase function patterns supplied by Collins *et al.* (2000). As shown, within the forward scatter angles ( $0^\circ - 90^\circ$ ), both the spherical and non-spherical contours follow the phase function patterns of the 7 models. However, within the backscatter region ( $90^\circ - 180^\circ$ ), the non-spherical phase function curve deviates from all other curves by revealing a flatter profile. As mentioned earlier, the NPS algorithm applies its theory based on non-dust, spherical aerosol particles. Based on Figure 37, it would be plausible to apply to the NPS algorithm a modified phase function that is flatter in the backscatter region during dust events.

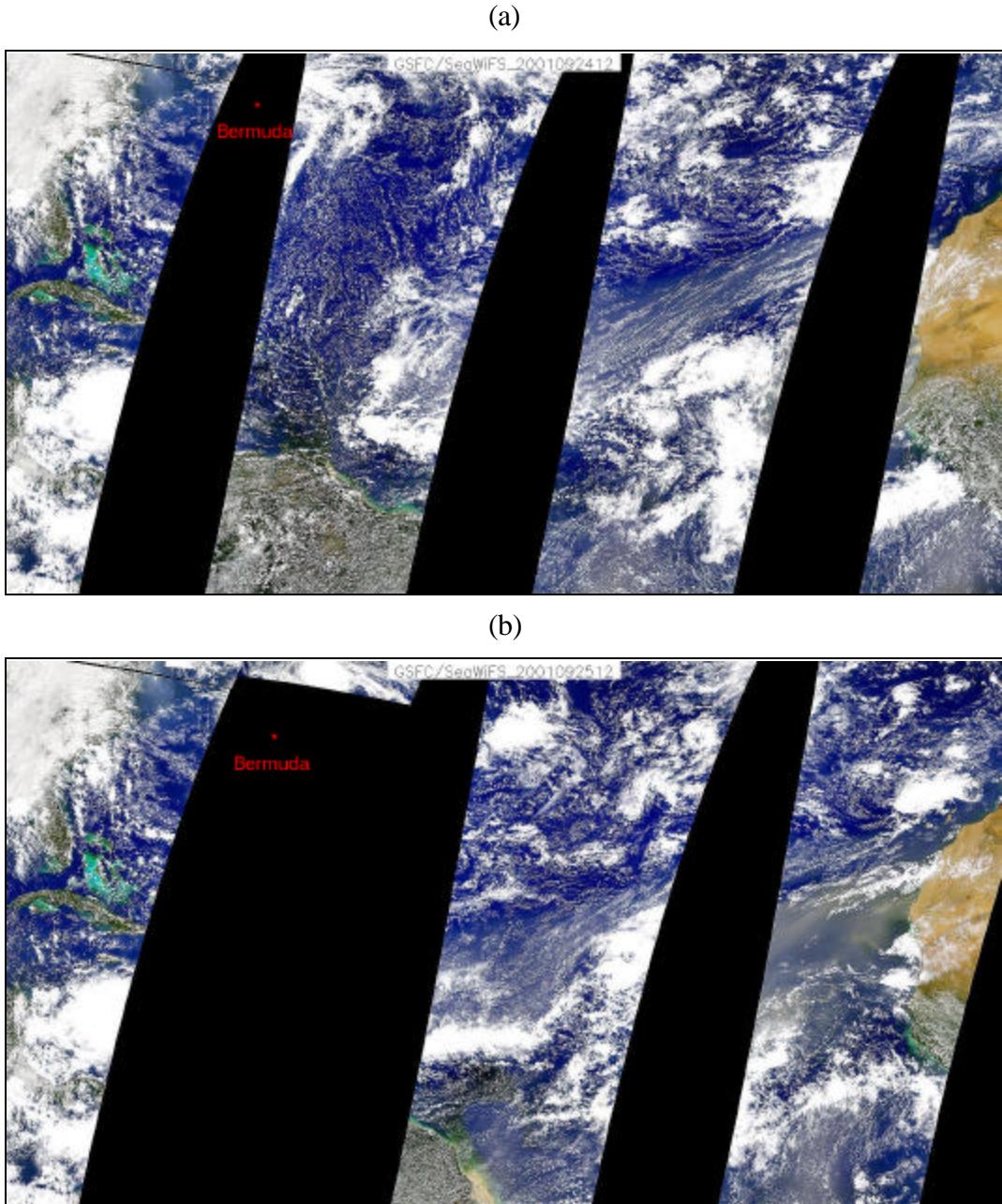


Figure 11. Composite of SeaWiFS images centered at 12 UTC on (a) 24 September, 2001 and (b) 25 September 2001 covering the Atlantic Basin. The location of interest for this study is the island of Bermuda. Over the ocean, clear (low aerosol content) regions are in dark blue, cloudy regions are solid white, and gray regions depict higher aerosol (dust) content. A large plume of dust is visible off the west coast of Africa. (Courtesy of Dr. Douglas L. Westphal at NRL)

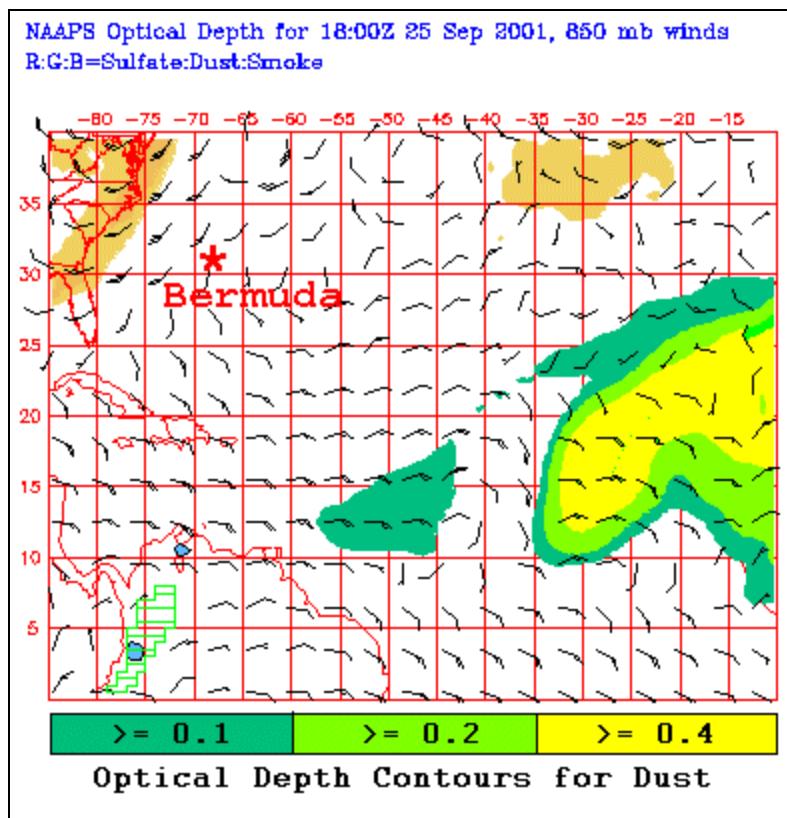


Figure 12. Plot of NAAPS display of optical depth for sulfate (red shades), dust and smoke (green and yellow shades) over the Atlantic Ocean basin for 25 September 2001, 18:00 UTC. The bottom color bar shows the AOD range for dust and smoke. 850 mb model-generated wind barbs are also displayed. (Courtesy of Dr. Douglas L. Westphal at NRL)

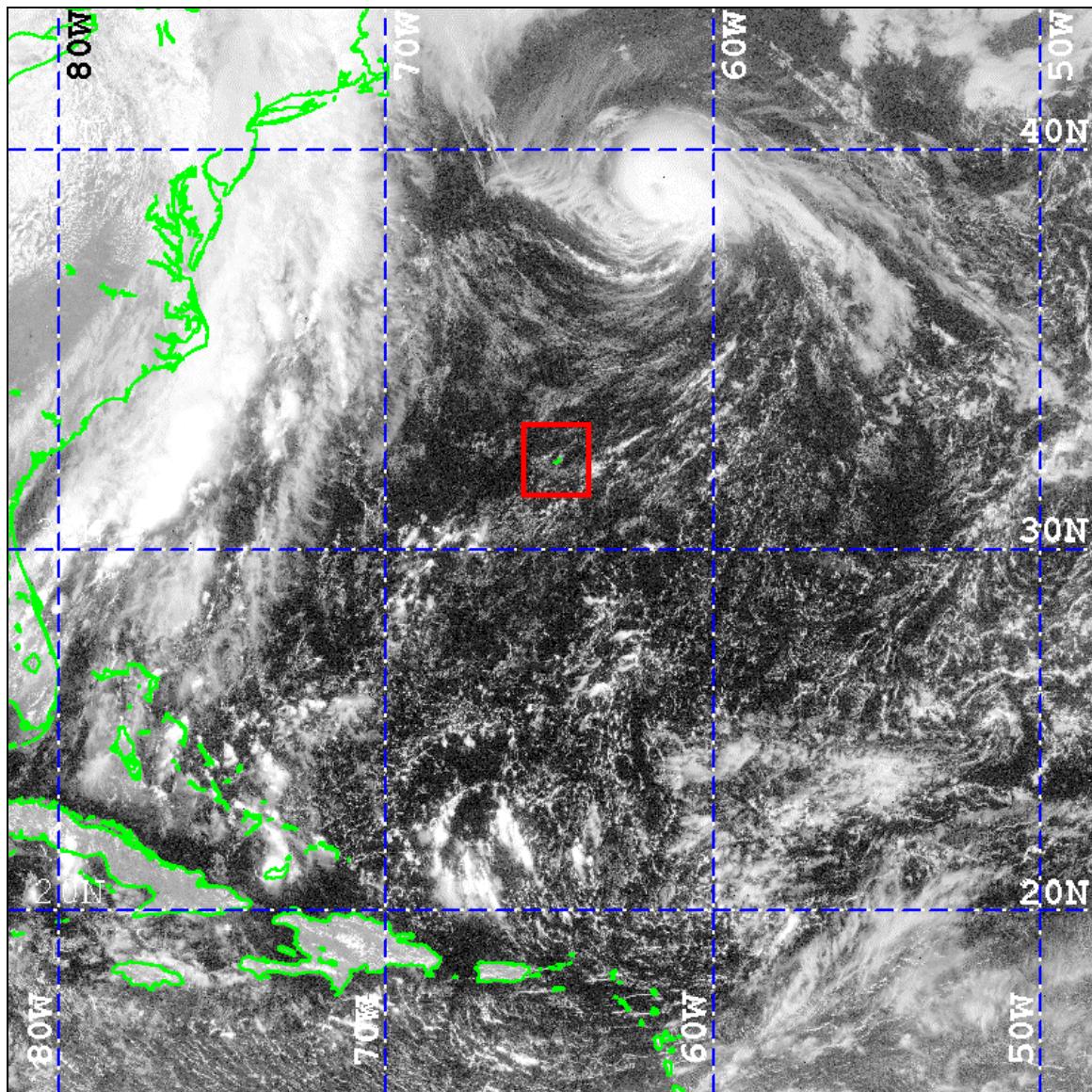


Figure 13. GOES-8 visible image on 25 September 2001 at 17:15 UTC. The annotated box surrounds the region of Bermuda.

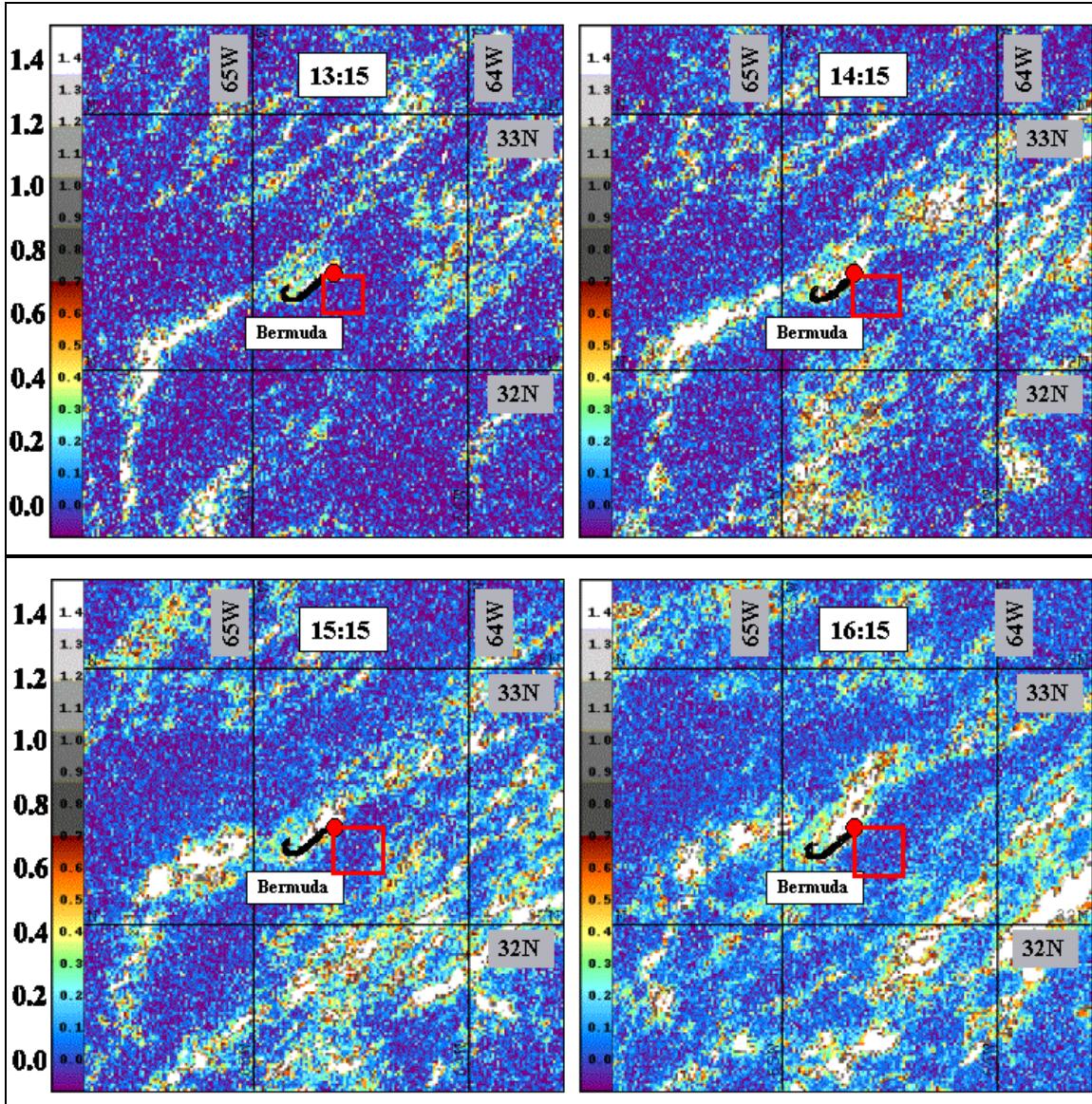


Figure 14. Time series of AOD images generated for 25 September 2001 from GOES-8 data that surrounds Bermuda. Pixel sizes are 1.1 km by 1.1 km and the domain is approximately 110 km by 110 km. The times range from 13:15 UTC to 16:15 UTC. Red boxes depict locations where the representative AOD for that area was measured. AOD color contours are defined on the left side of each image.

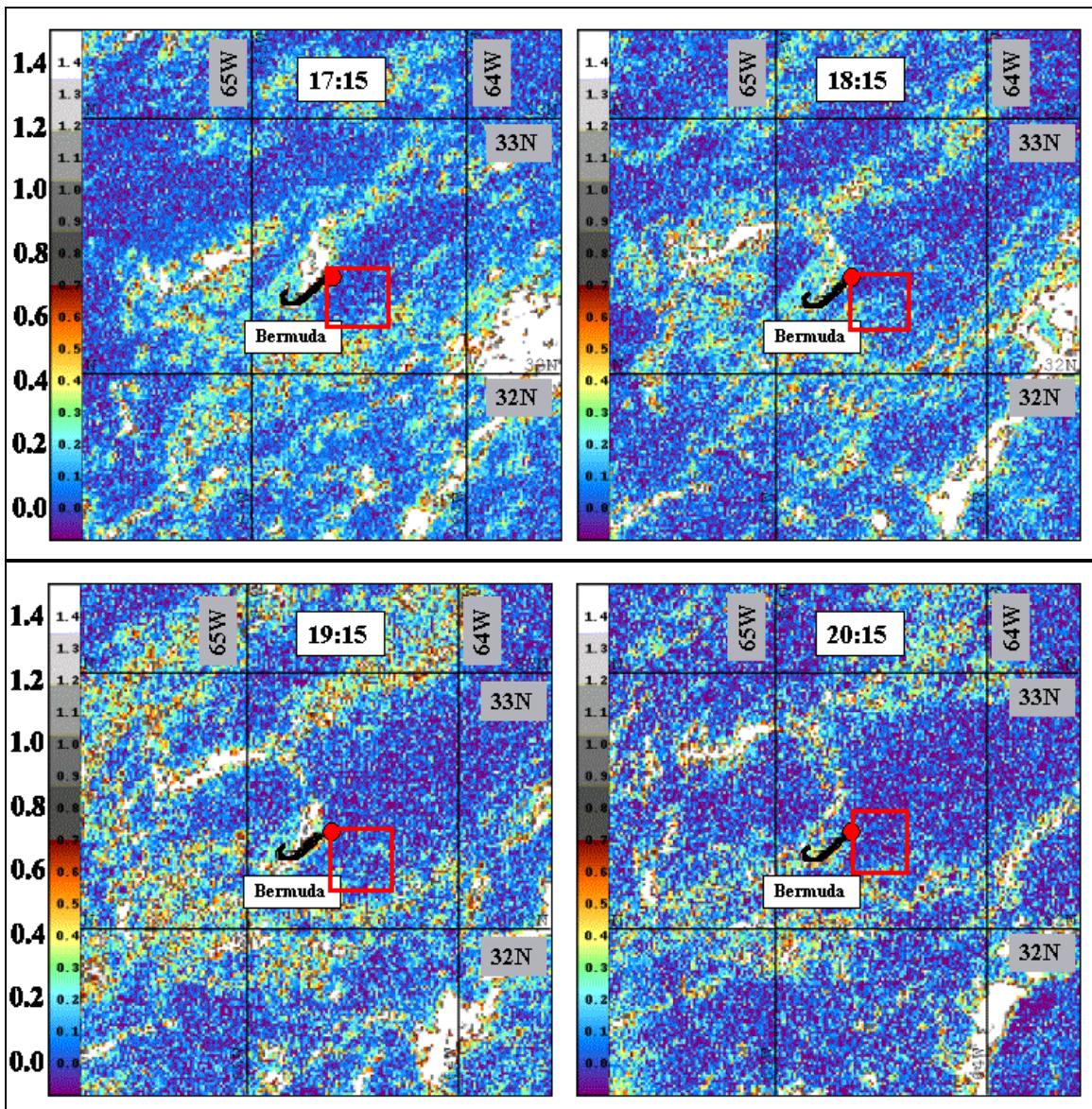


Figure 15. Continuation of Figure 14 for times ranging from 17:15 UTC to 20:15 UTC.

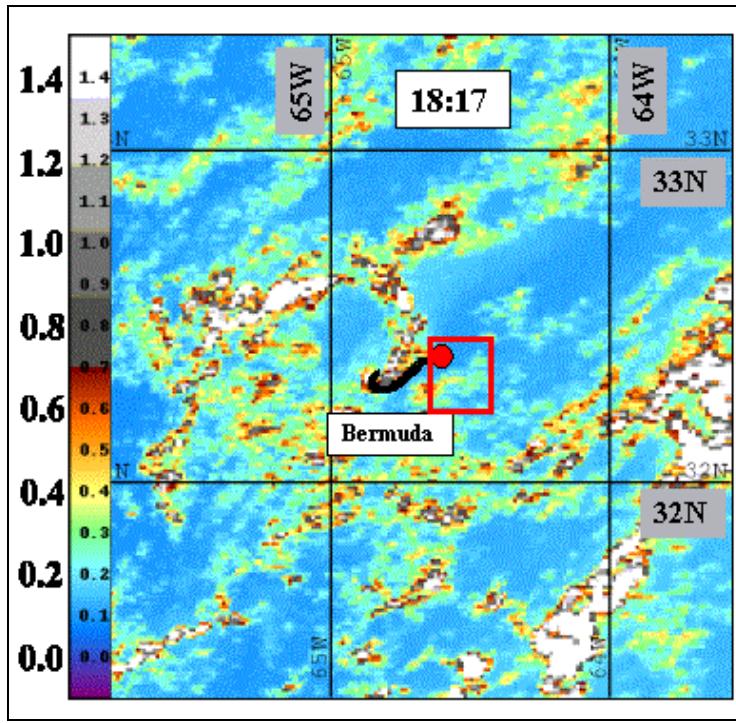


Figure 16. AOD image generated for 25 September 2001 at 18:17 UTC from NOAA-16 data that surrounds Bermuda. Pixel sizes are 1.1 km by 1.1 km and the domain is approximately 110 km by 110 km. Red box depicts the location where the representative AOD for that area was measured. AOD color contours are defined on the left side of the image.

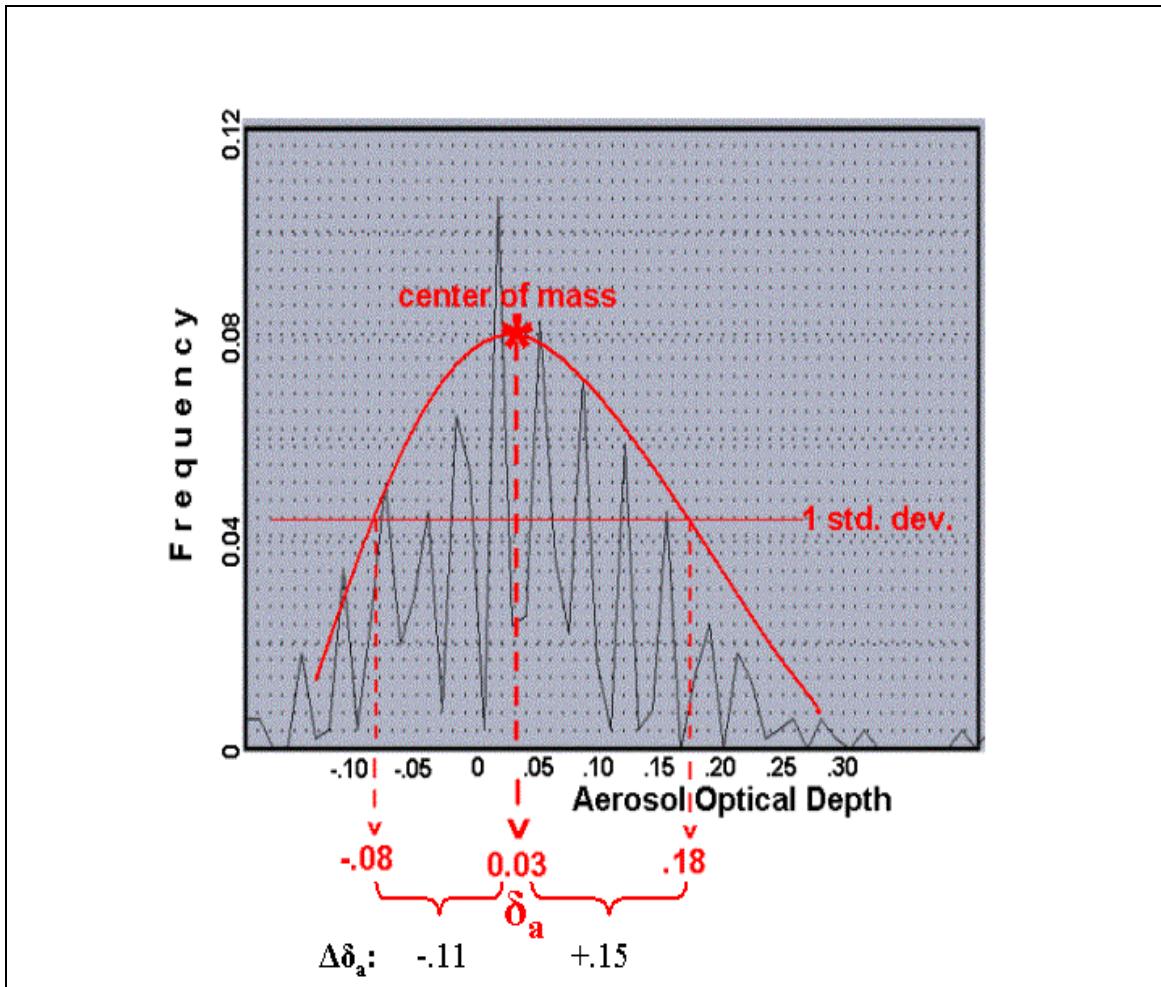


Figure 17. An example of a histogram frequency plot for determining AOD. A normalized curve (solid red curve) displays the distribution, where the center of mass (\*) is situated at the top of the curve. The resulting AOD value of 0.03 is then obtained. The variability measurements of AOD are obtained from a line drawn at half the amplitude of the normalized curve that indicates one standard deviation from the measured AOD value.

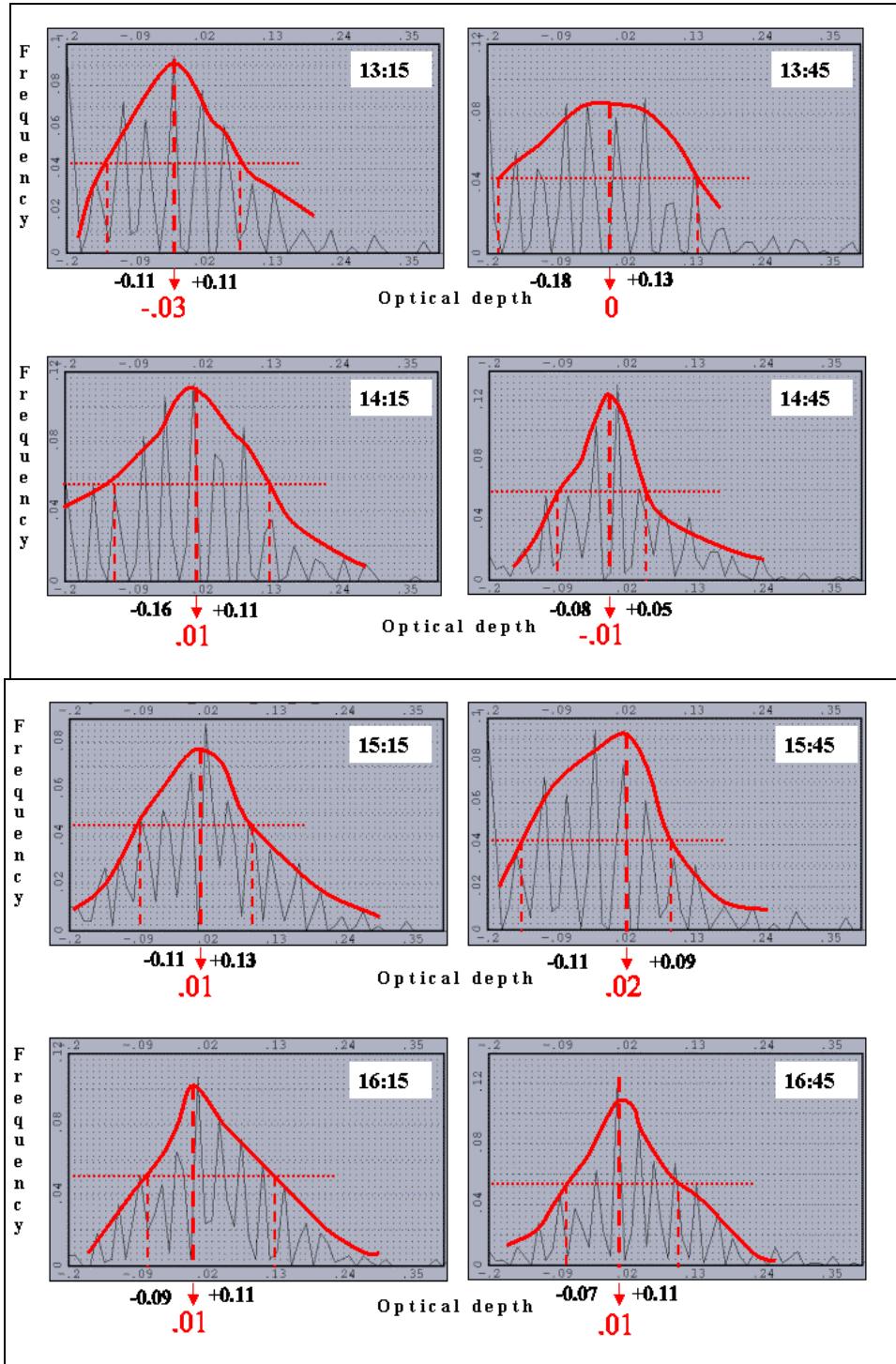


Figure 18. Time series of histogram plots of AOD for 25 September 2001, between 13:15 UTC and 16:45 UTC. Plots are generated from boxes defined in Figure 14. The AOD values are shown in red, while the two adjacent values represent the variability of AOD measurements. The red annotations depict the AOD measurement process that is described in Figure 17.

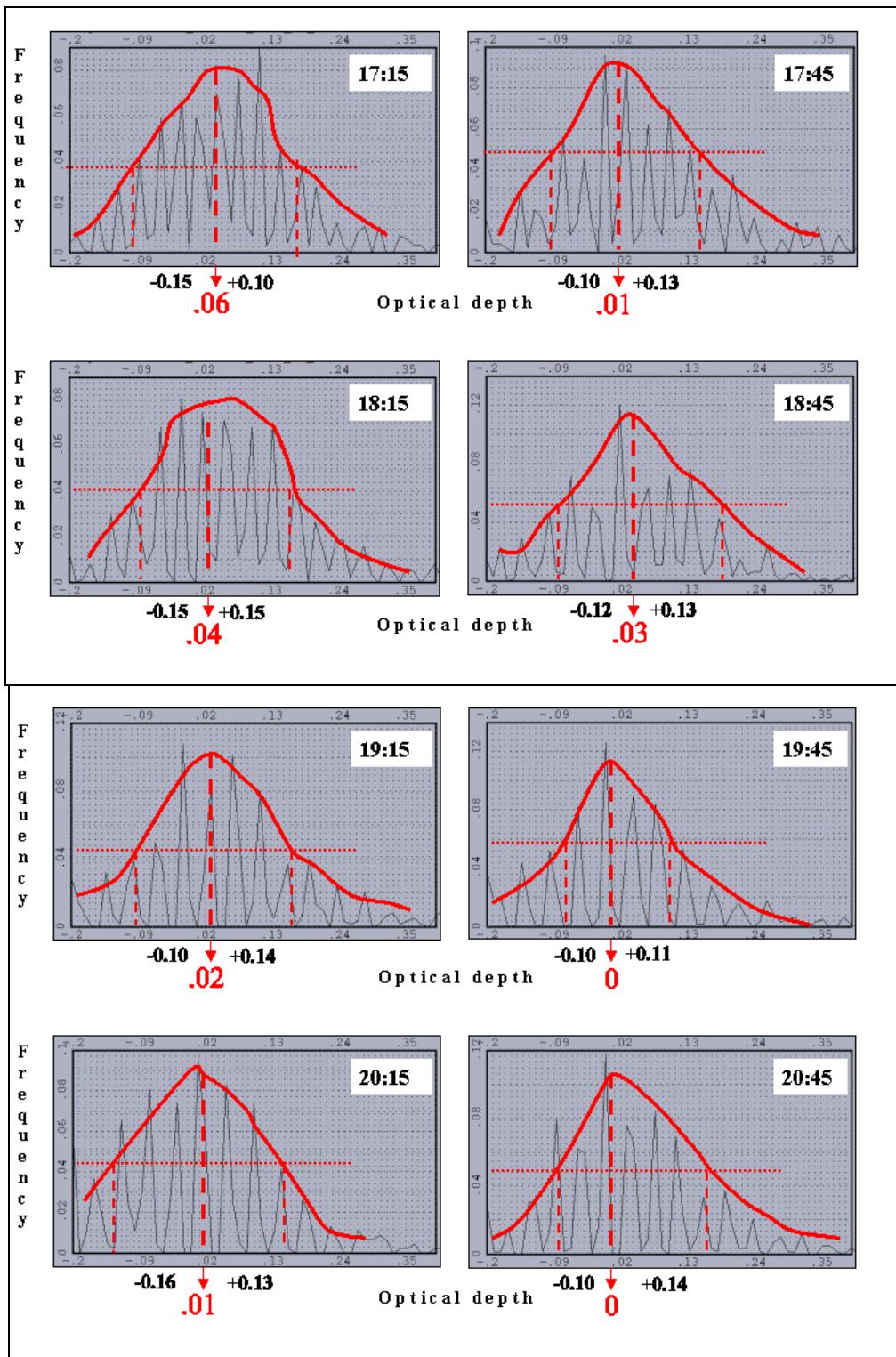


Figure 19. Continuation of time series of histogram plots from Figure 15 of AOD for 25 September 2001, between 17:15 UTC and 20:15 UTC.

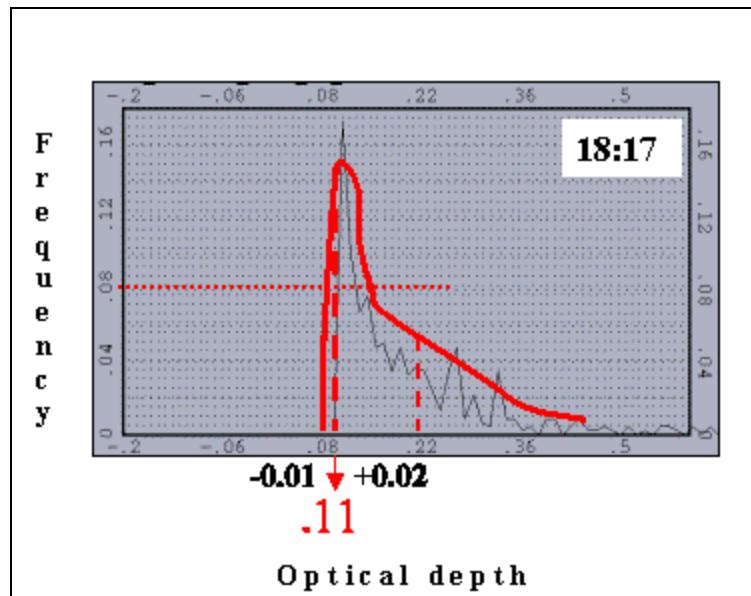


Figure 20. Histogram plot of AOD for 25 September 2001 at 18:17 UTC from NOAA-16 data. The plot is generated from box defined in Figure 16. Times are in UTC. The AOD values are shown in red, while the two adjacent values represent the variability in the AOD measurement.

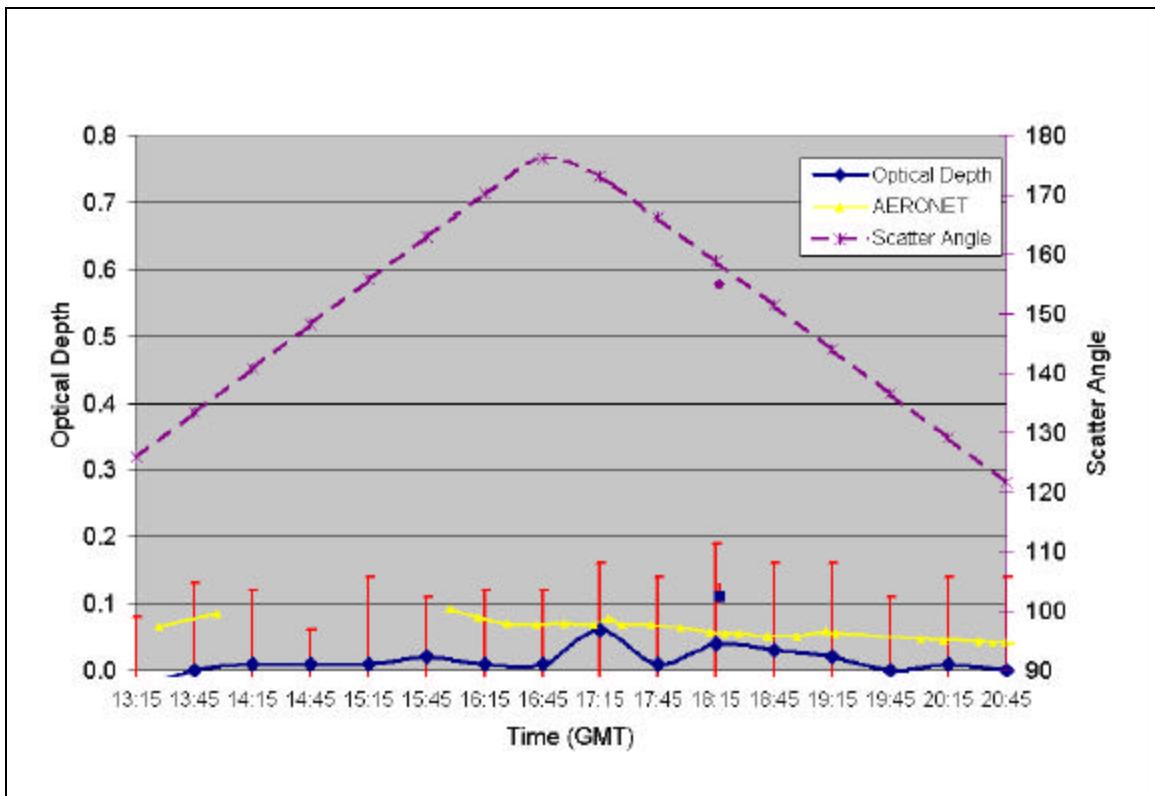


Figure 21. Time series of AOD for both satellite-derived data (navy blue dots) and AERONET observations (yellow) for 25 September 2001 over Bermuda. NOAA data are presented as individual blue dots whereas GOES-8 data are connected with a blue line. Red bars represent variability in AOD measurements. The corresponding scatter angle profile is represented as a purple dashed line.

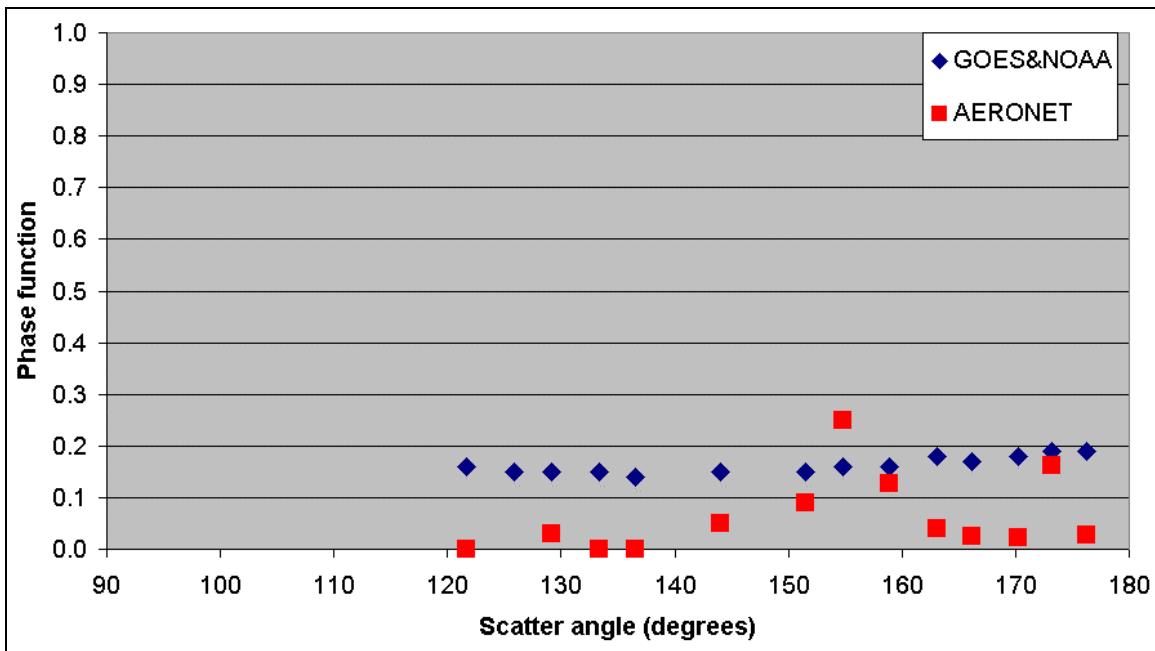


Figure 22. Plot of phase function as a function of scatter angle for the case of 25 September 2001 over Bermuda. Blue diamonds indicate phase functions obtained from satellite data. Red boxes indicate phase function values required for the satellite-derived AOD to match AERONET's AOD.

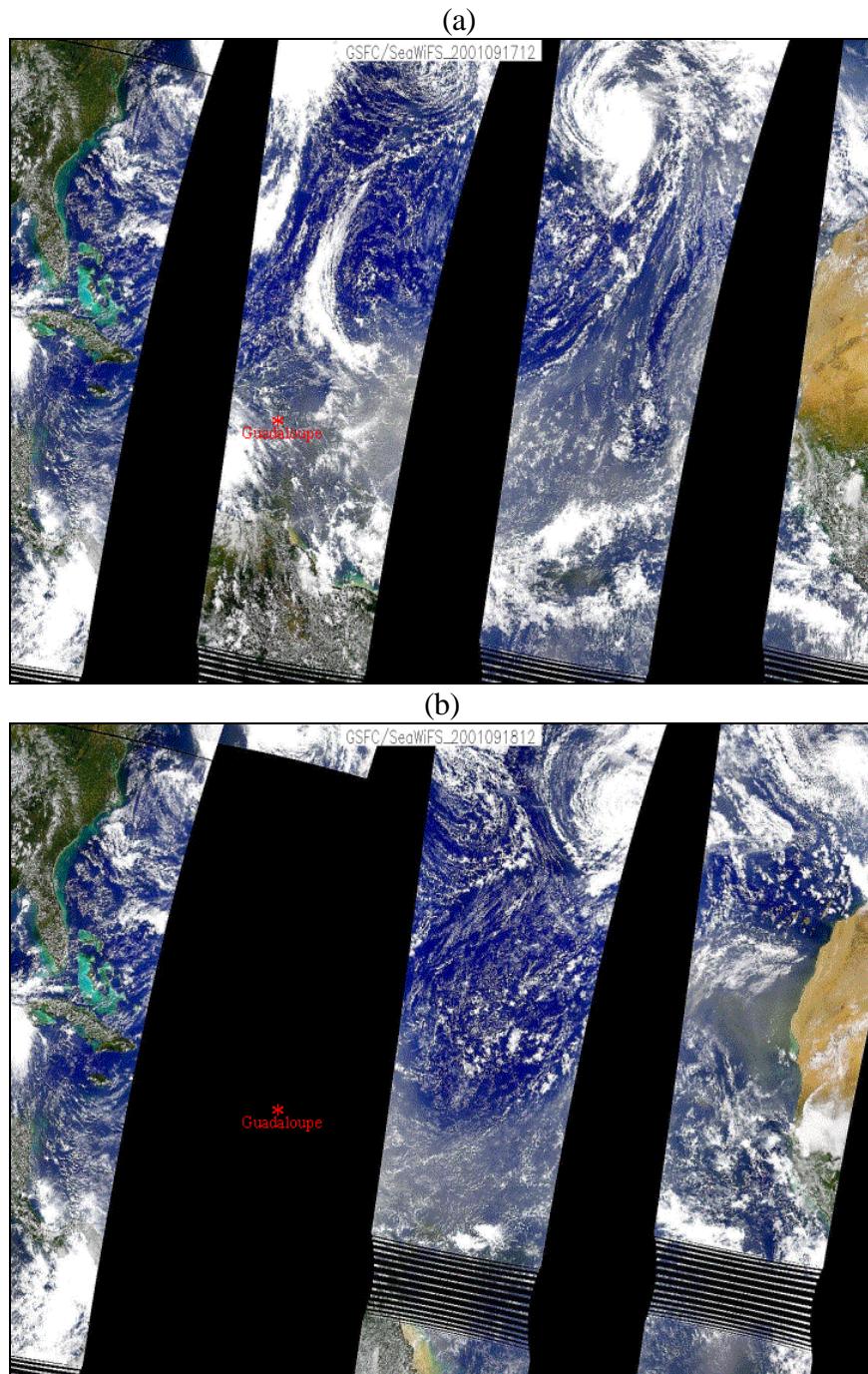


Figure 23. Composite of SeaWiFS images centered at 12 UTC on (a) 17 September 2001 and (b) 18 September, 2001 covering the Atlantic Basin. The location of interest for this study is Guadalupe Island. Over the ocean, clear (low aerosol content) regions are in dark blue, cloudy regions are solid white, and gray regions depict higher aerosol (dust) content. A large plume of dust is visible off of the west coast of Africa. (Courtesy of Dr. Douglas L. Westphal at NRL)

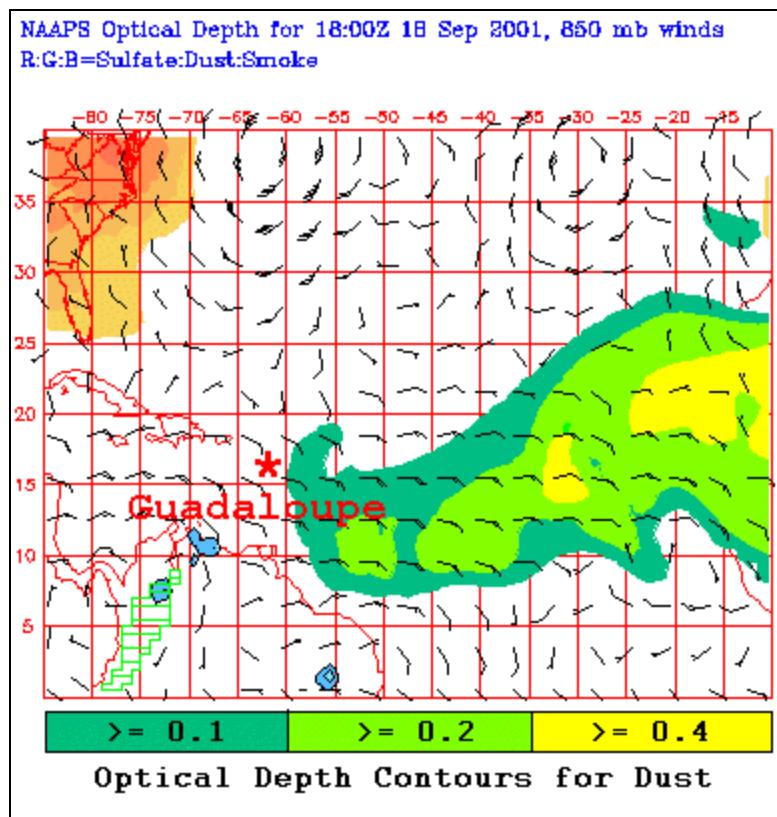


Figure 24. Plot of NAAPS display of optical depth for sulfate (red shades), dust and smoke (green and yellow shades) over the Atlantic Ocean basin for 18 September 2001, 18:00 UTC. (Courtesy of Dr. Douglas L. Westphal at NRL)

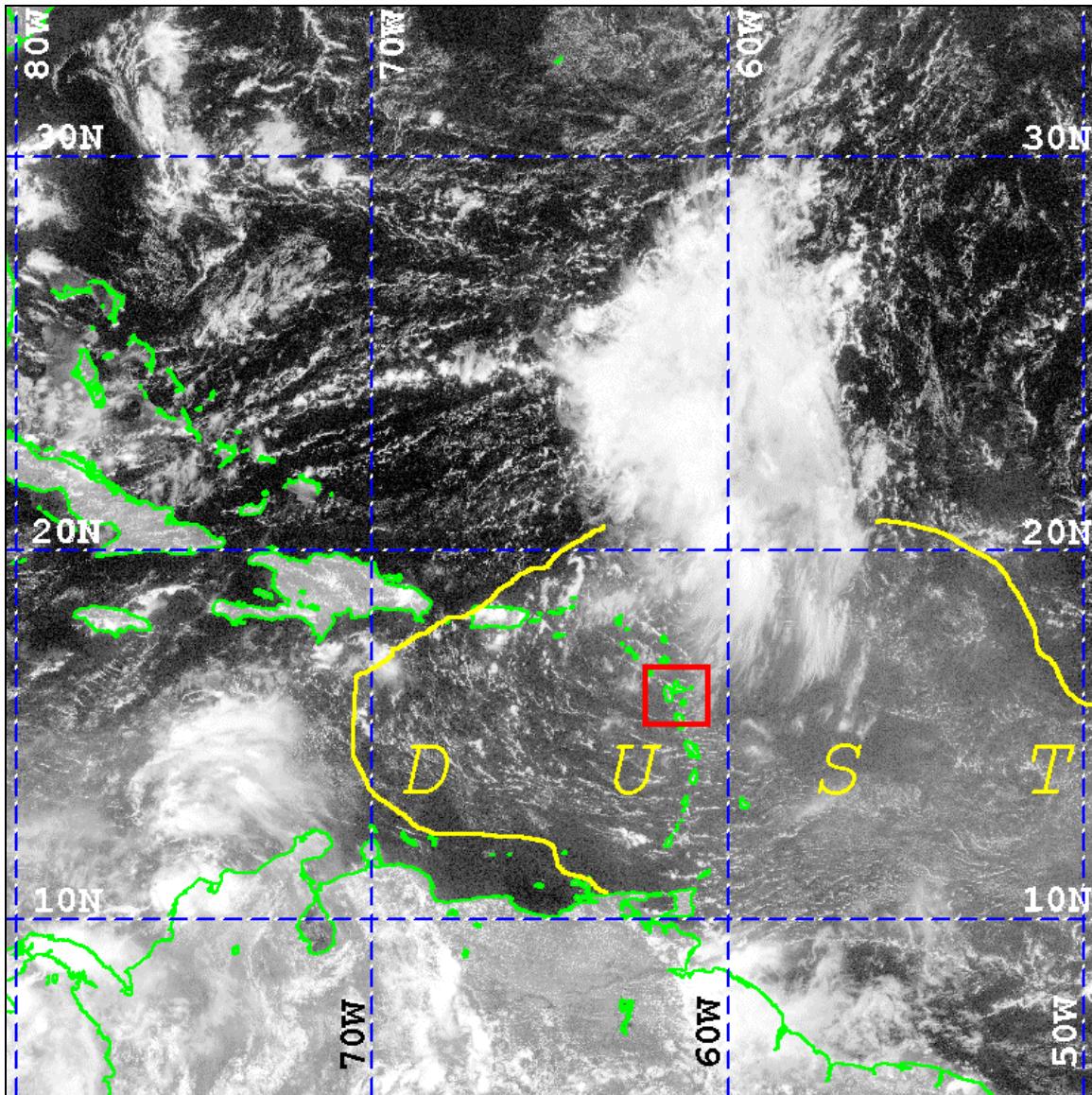


Figure 25. GOES-8 visible image on 18 September 2000 at 17:15 UTC. The annotated box surrounds the region of Guadalupe Island. The area of aerosol dust is also annotated.

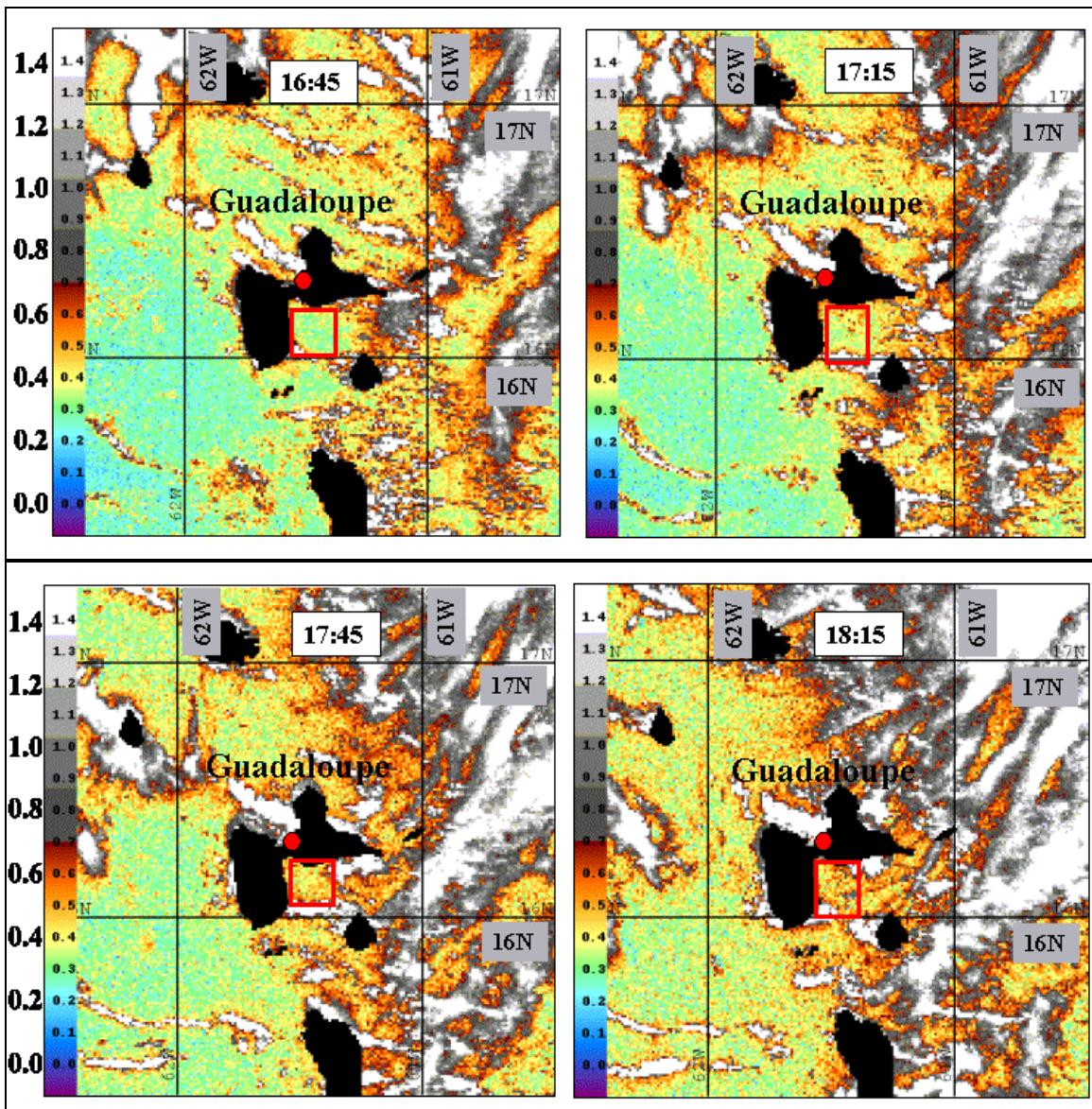


Figure 26. Time series of AOD images generated for 18 September 2001 from GOES-8 data that surrounds Guadalupe Island. Pixel sizes are 1.1 km by 1.1 km and the domain is approximately 110 km by 110 km. The times range from 16:45 UTC to 18:15 UTC. Red boxes depict locations where the representative AOD for that area was measured. AOD color contours are defined on the left side of each image.

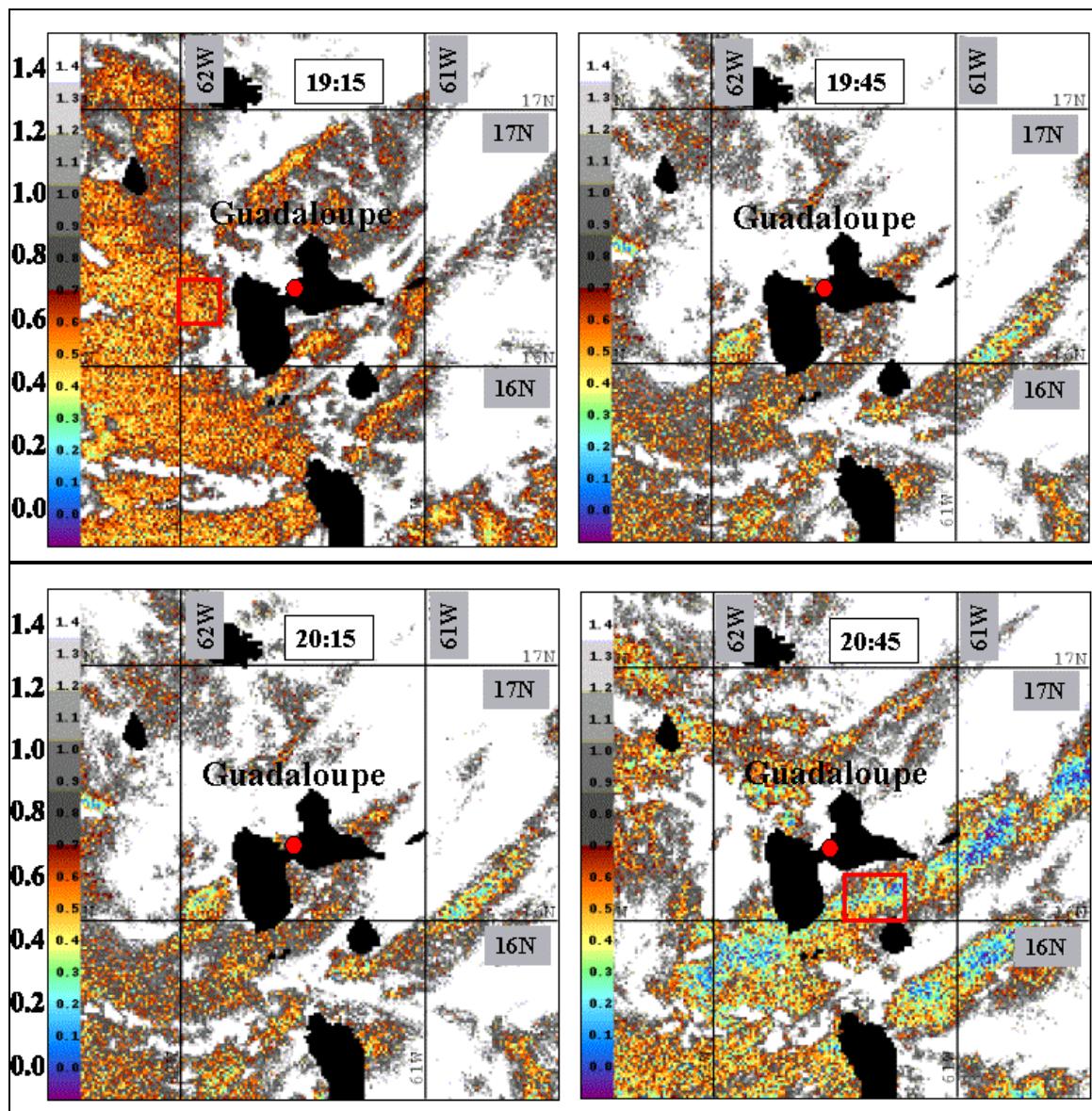


Figure 27. Continuation of Figure 26 for times ranging from 19:15 UTC to 20:45 UTC.

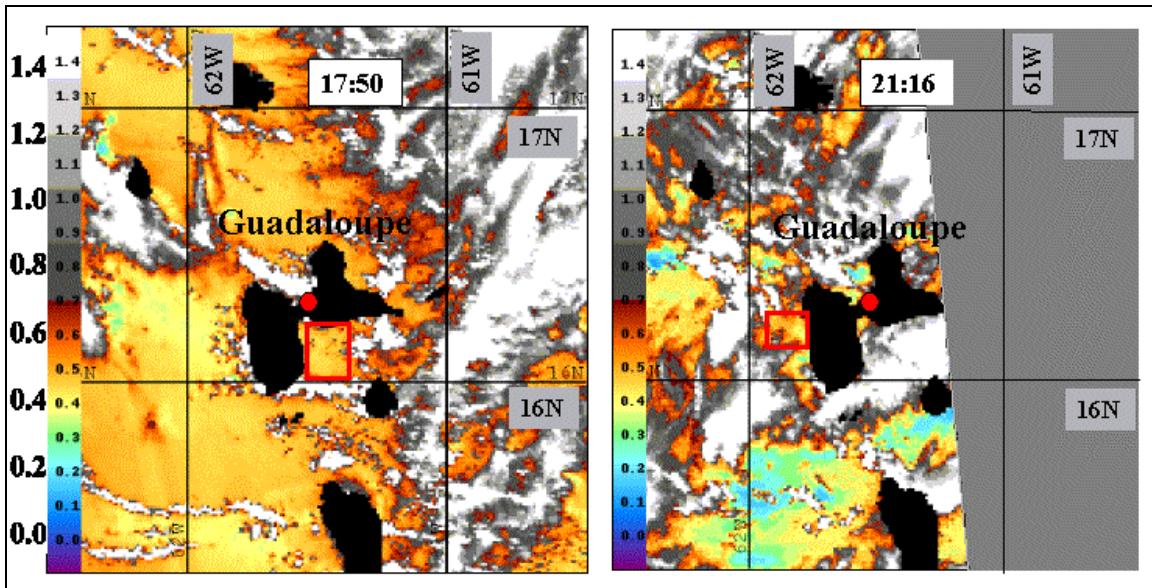


Figure 28. AOD images generated for 18 September 2001 at 17:50 UTC and 21:16 UTC from NOAA-16 and NOAA-14 data, respectively. Images surround Guadalupe Island. Pixel sizes are 1.1 km by 1.1 km and the domain is approximately 110 km by 110 km. Red boxes depict the locations where the representative AOD for that area were measured. AOD color contours are defined on the left side of each image.

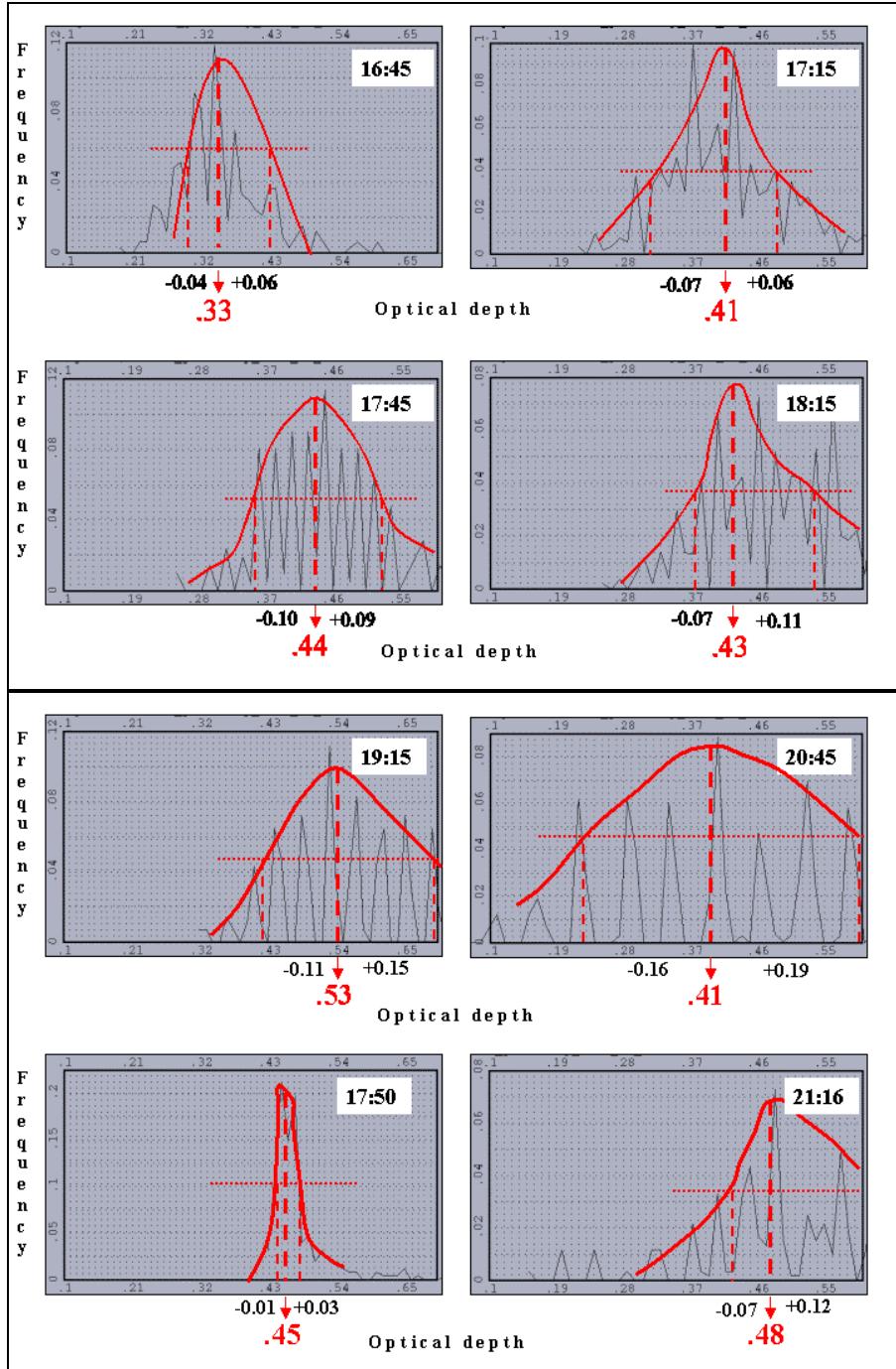


Figure 29. Time series of frequency histogram plots of AOD for 18 September 2001, between 16:45 UTC and 21:16 UTC. The top 6 plots are derived from GOES-8 data and the bottom 2 plots are derived from NOAA-16 and NOAA-14 data, respectively. Plots are generated from boxes defined in Figures 26 and 27. For each plot, the AOD value is shown in red, while the pair of black values represent the variability of AOD measurements. The red lines and curves depict the AOD measurement process that is described in Figure 17.

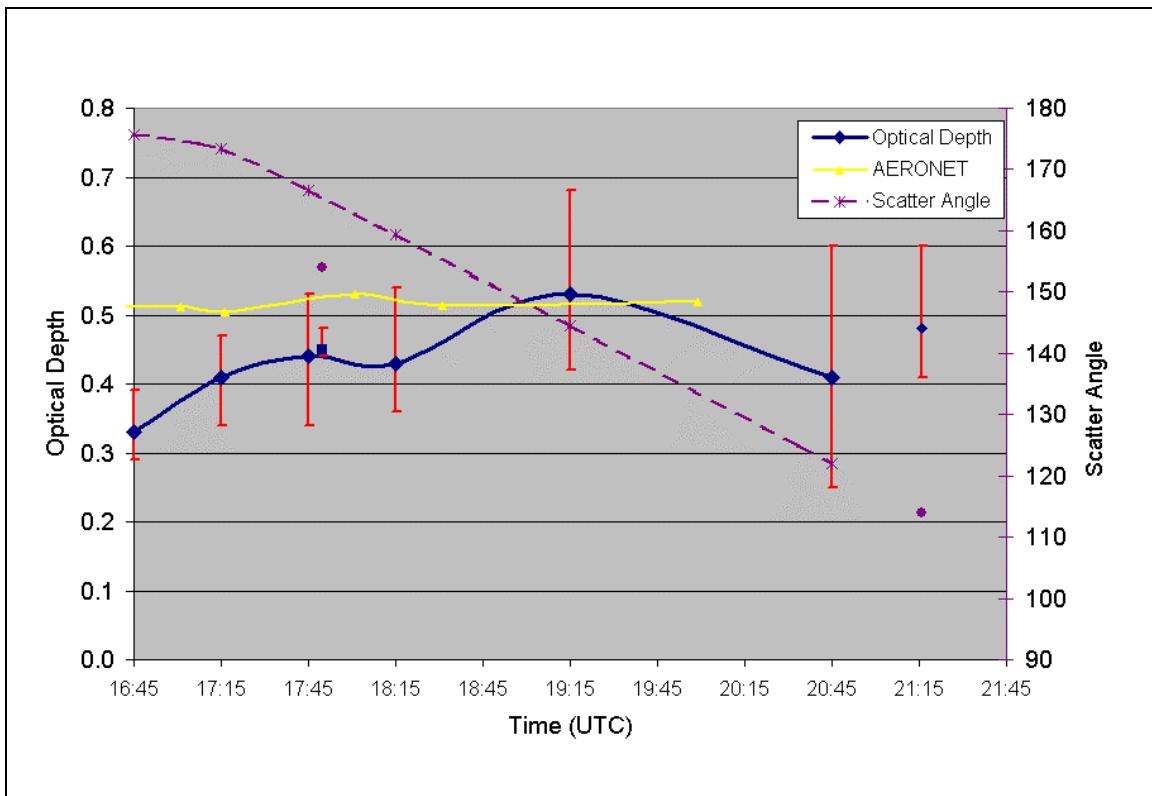


Figure 30. Chart of AOD for both satellite-derived data (navy blue dots) and AERONET observations (yellow) for 18 September 2001 over Guadalupe Island. NOAA data are presented as individual blue dots whereas GOES-8 data are connected with a blue line. Red bars represent variability in AOD measurements. The corresponding scatter angle profile is represented as a purple dashed line.

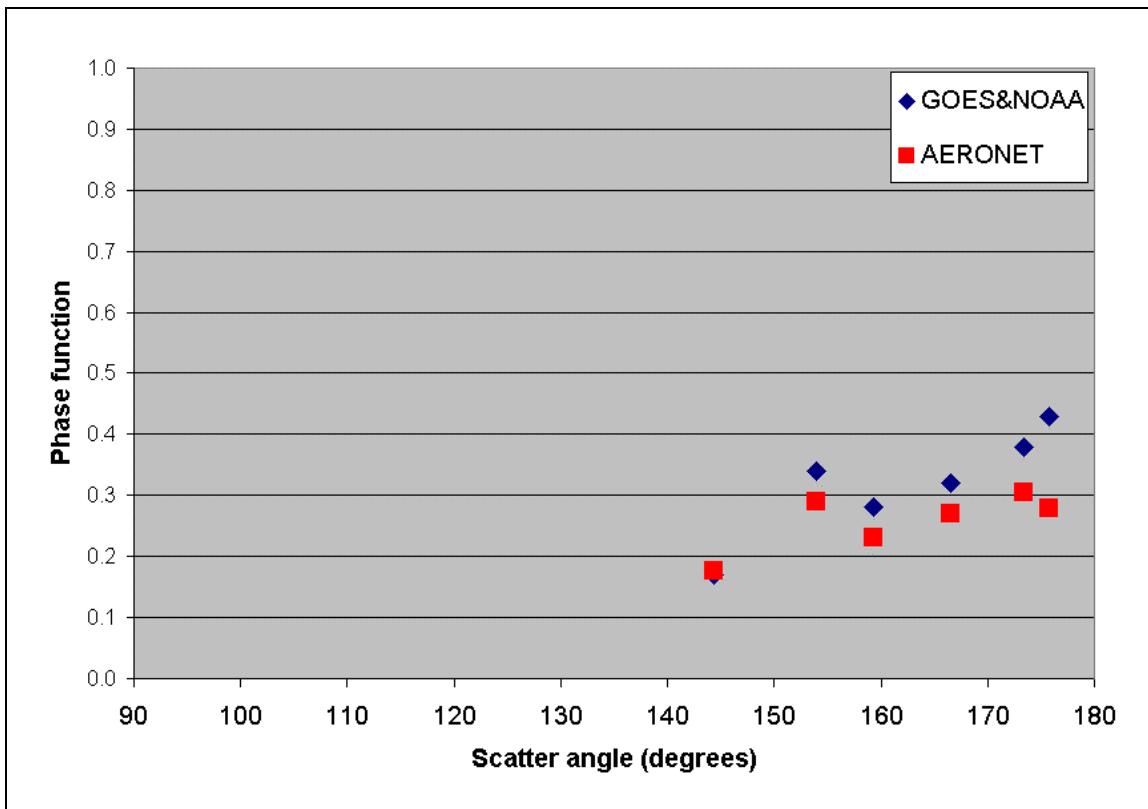


Figure 31. Plot of phase function as a function of scatter angle for the case of 18 September 2001 over Guadalupe Island. Blue diamonds indicate phase functions obtained from satellite data. Red boxes indicate the phase function values required for the satellite-derived AOD to match AERONET AOD.

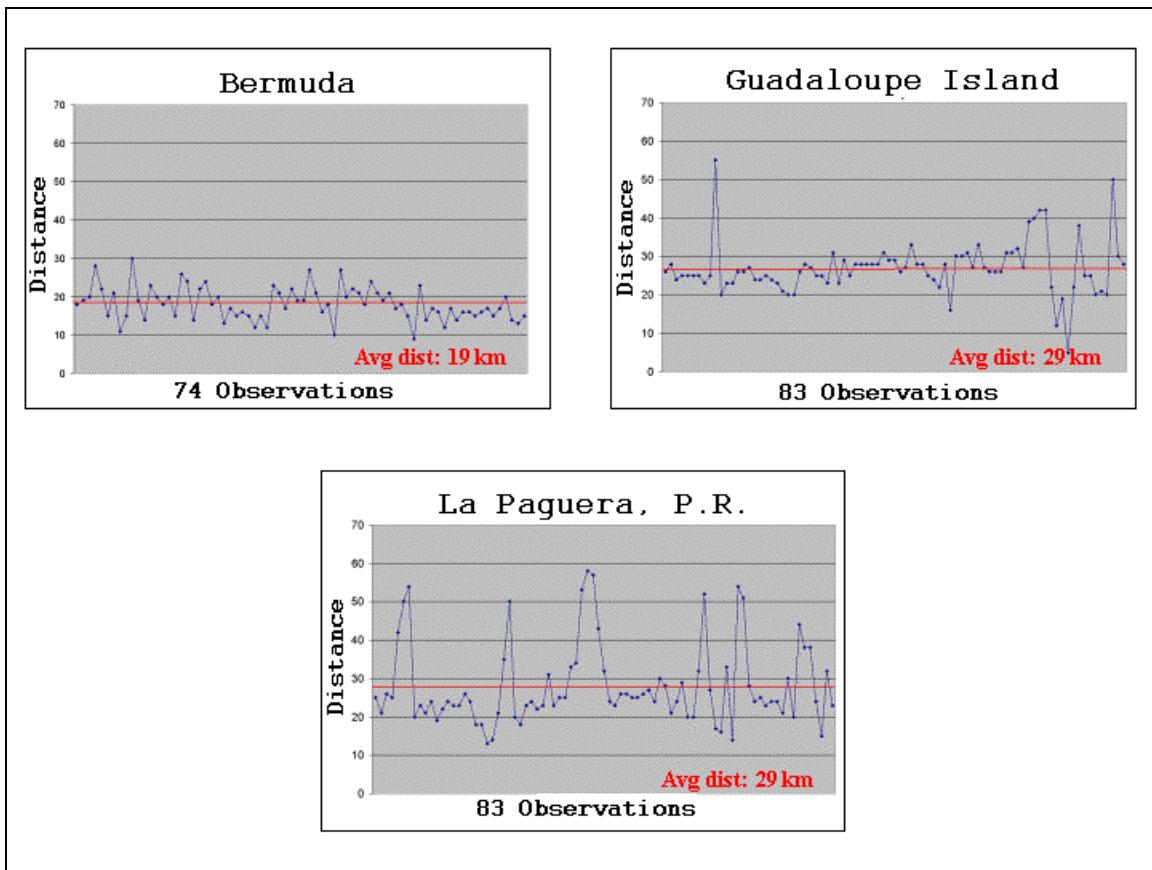


Figure 32. Distribution of distance measurements between each of the 3 AERONET sites and the location of the satellite-derived AOD for all 22 cases. For each AERONET region, the average distance from the AERONET station to the center of the satellite-derived measurement box is annotated in red.

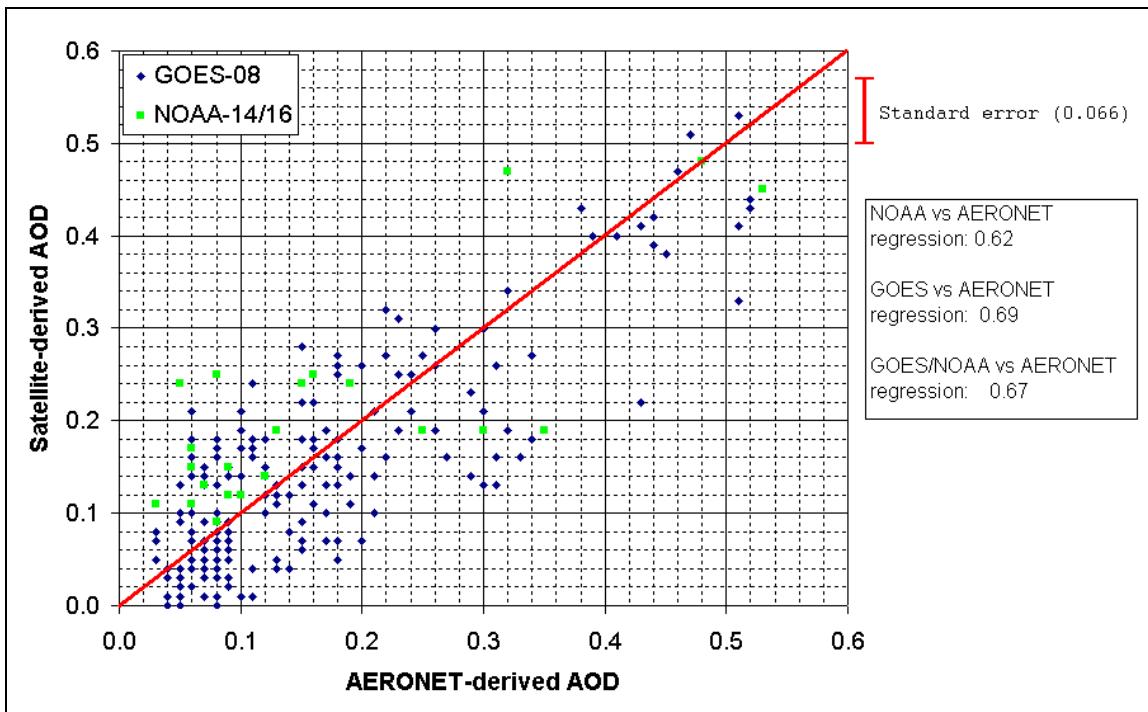


Figure 33. Comparisons between NPS-calculated AOD and AERONET-observations of AOD for the 22 cases as listed in Appendix A.1. The red line depicts one to one relationship.

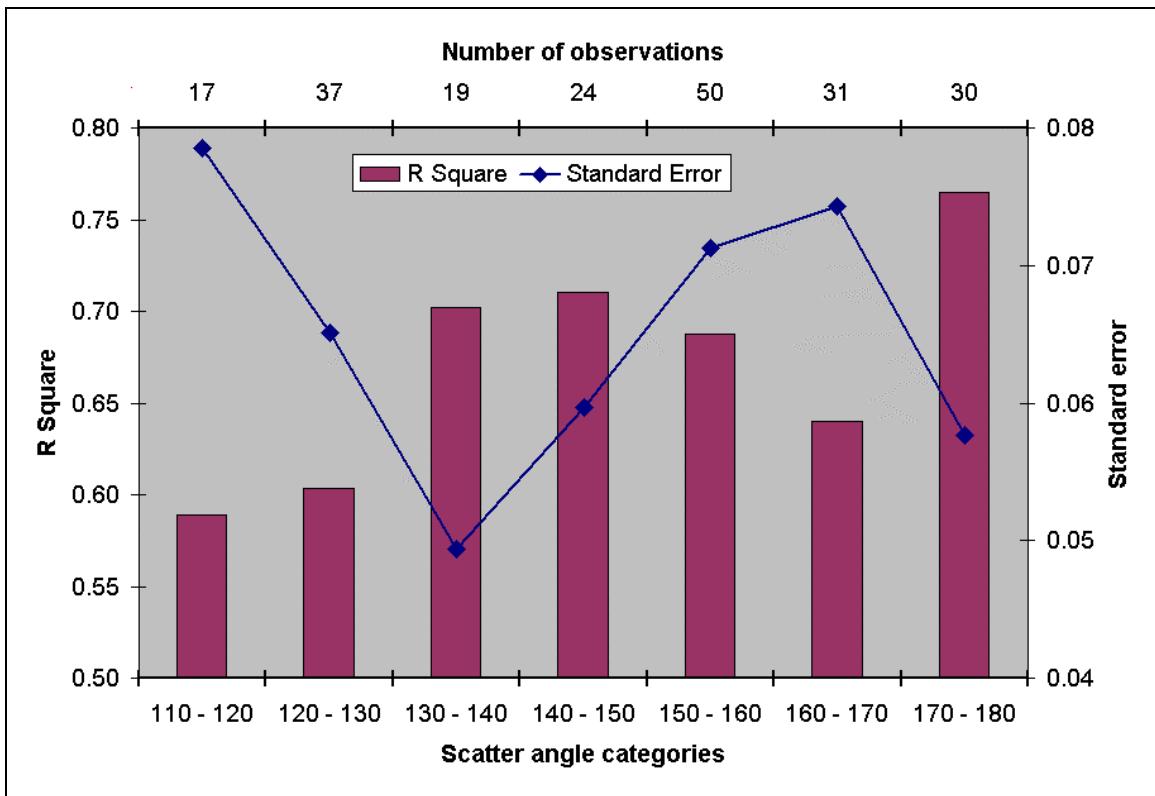


Figure 34. Evaluation of NPS algorithm, partitioned over categories of scatter angles.

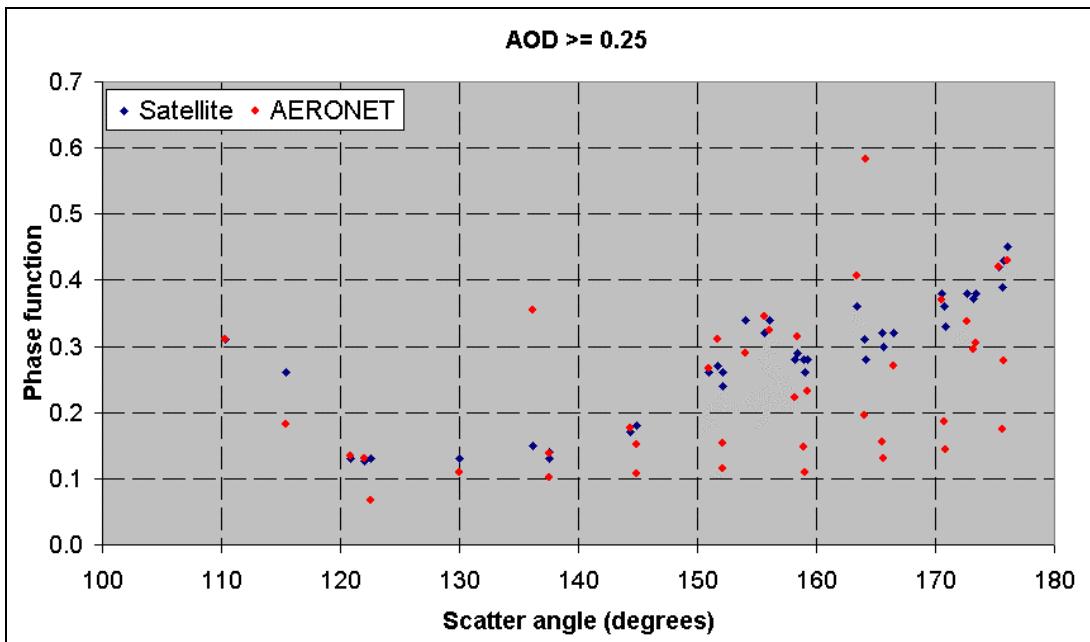


Figure 35. Comparisons of phase functions between satellite data and AERONET data for 22 cases. Figure only depicts dust conditions (AERONET AOD = 0.25).

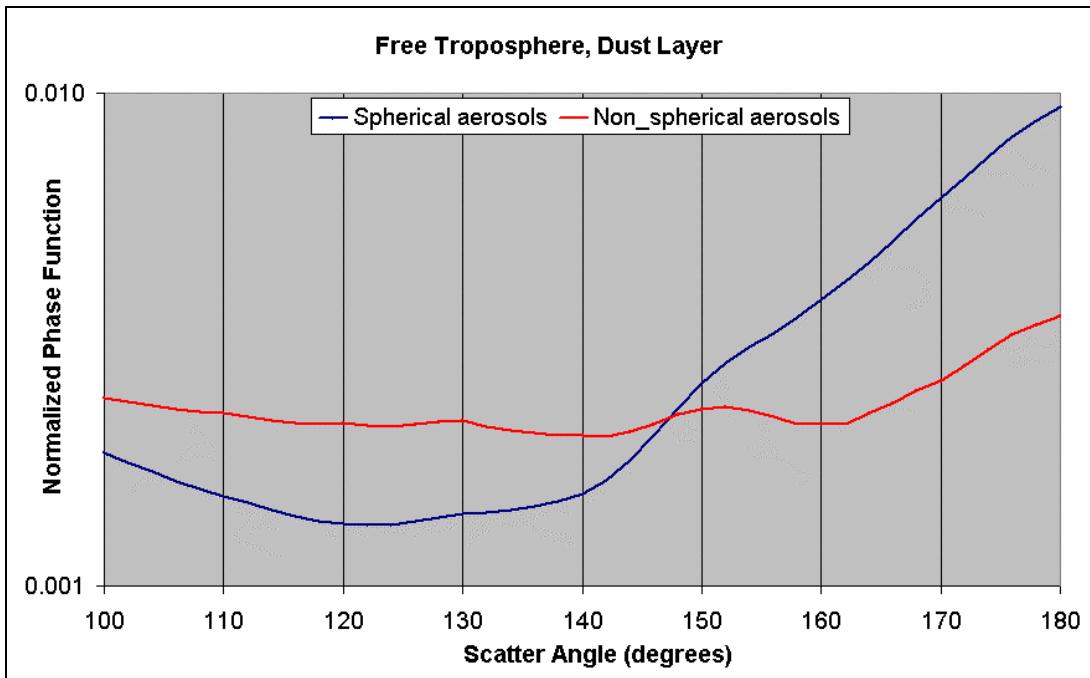


Figure 36. Phase function plots for the free troposphere, dust layer obtained from the second Aerosol Characterization Experiment (ACE-2). Data is supplied by Collins, *et al.* (2000). Phase function values are normalized.

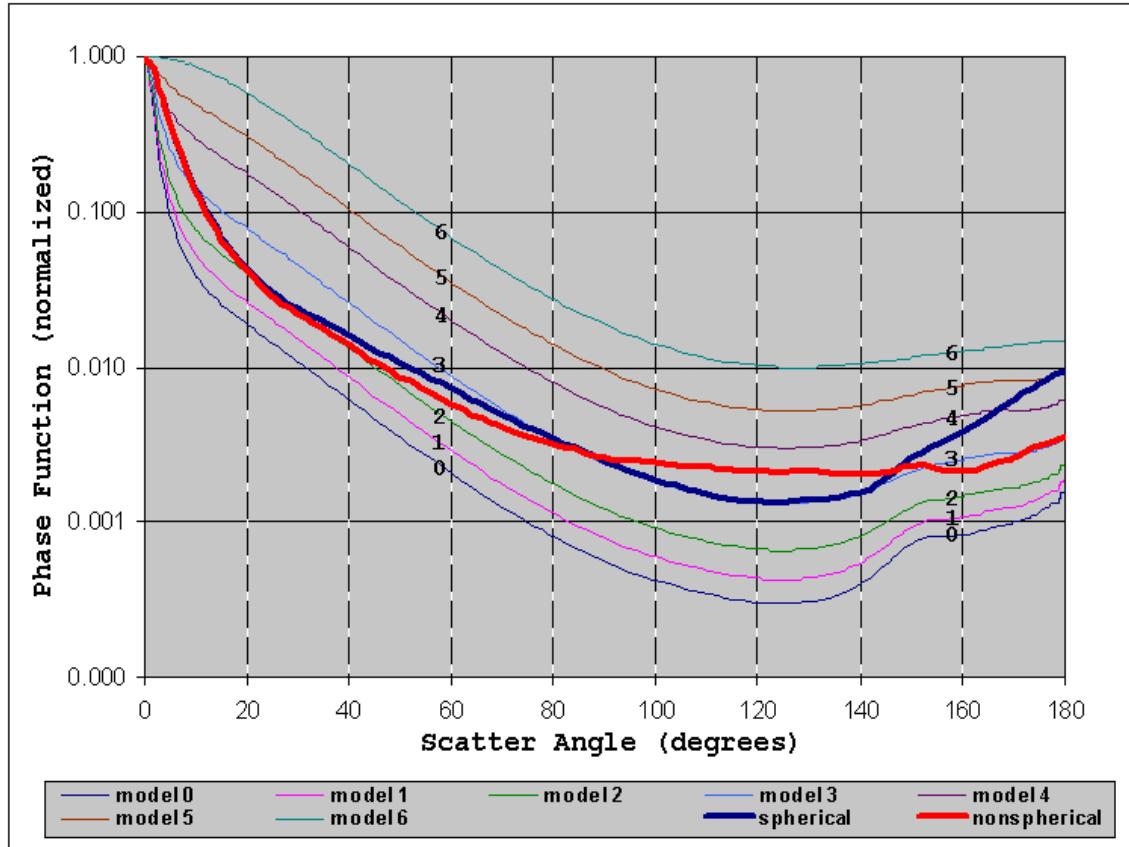


Figure 37. Phase function plots comparing the dust plots in Collins *et al.* (2000) (thick curves) with the model phase functions used in the NPS algorithm (thin curves). Annotated numbers are used to identify the model numbers.

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## VI. CONCLUSIONS AND RECOMMENDATIONS

### A. CONCLUSIONS

A radiative transfer algorithm (NPS algorithm) that processes AOD within a cloud-free maritime atmosphere was presented for the NOAA POES AVHRR and GOES imager. This algorithm applies linearized, single-scatter theory with an estimate of bi-directional surface reflectance. Using a technique developed by Durkee *et al.* (1991), scattering phase functions are parameterized to seven aerosol size distributions by applying the ratios of channel 1 and 2 radiances ( $S_{12}$ ) of the AVHRR. The  $S_{12}$  value is then translated to an aerosol model index (AMI) value that is accessed by GOES processing. Both the NOAA and GOES processing then apply the AMI to a look up table to determine the scattering phase function. The development and validation of the NPS algorithm is a continuation of the initial work performed by Brown (1997).

Unlike the AVHRR data, the GOES-8 visible radiance data required an unconventional calibration scheme developed by Rao *et al.* (1999) and Rao and Zhang (1999). During the analysis period of this paper (July and August, 2001) signal gain factors ranging from 1.727 during the first case study (July 27, 2001) through 1.740 during the last study (September 25, 2001) were applied to the GOES raw channel 1 albedo data. In addition, preliminary comparisons of AOD between GOES and NOAA, and AERONET revealed that an additional GOES-8 channel 1 correction factor of  $-5.5 \text{ W m}^{-2} \text{ sr}^{-1} \mu\text{m}^{-1}$  was necessary.

To validate the NPS algorithm, retrieved AOD data was collected from 22 cases during July and September of 2001 and compared to AERONET radiometers positioned within 3 island locations of the western Atlantic Ocean. For each case, a time series format was used to study temporal variations in AOD. Overall, the comparison dataset has a correlation coefficient of 0.67 with a standard error of 0.07. Within higher AOD cases ( $d_a > 2.5$ ), the general trend was for the NPS-generated AOD values to underestimate AERONET-observed conditions, probably due to assumptions of non-absorption applied to aerosol particles. When related to scatter angles, the NPS-generated AOD

calculations performed best within the backscatter angle ranges of  $130^{\circ}$  -  $140^{\circ}$  and  $170^{\circ}$  -  $180^{\circ}$ .

A major part of the uncertainty to the AOD processing is the proper selection of the scattering phase function. The problem with the AOD results generated from GOES data is that the aerosol conditions over a particular region were assumed to be unchanging throughout the entire time period, which might last for 8 hours. Unfortunately, trying to validate a representative aerosol distribution was beyond the scope of this study. The AOD results were apparently not very sensitive to any aerosol model assigned to the calculation.

The pattern of the NPS algorithm-generated phase functions was evaluated during the dust events ( $da = 0.25$ ). Between the scatter angles of  $140^{\circ}$  through  $180^{\circ}$ , the phase function pattern required to match AERONET observations indicated a flatter profile than that produced by the NPS algorithm on GOES and NOAA data. The AERONET-generated phase function profile was confirmed with studies by Collins *et al.* (2000) for non-spherical dust aerosols compared to spherical particles assumed in the NPS algorithm.

## B. RECOMMENDATIONS

Several research initiatives would aid in the improvement of the NPS algorithm:

- Coordinate with aerosol modelers to develop a more accurate assessment of aerosol conditions on a global scale. The NAAPS model developed at NRL is one such source. The NAAPs would greatly help the NPS algorithm in determining the proper phase function parameters.
- Apply the NPS algorithm to other satellite platforms. Preliminary studies by Brown (2001) indicate that the SeaWiFs sensor, with its suite of visible sensing channels, could greatly enhance the  $S_{12}$  phase function parameterization technique. Another instrument with great potential applications is the Moderate Resolution Imaging Spectroradiometer (MODIS).
- Improve sun glint removal process by incorporating wind speed, which is available from the Defense Meteorological Satellite Program's (DMSP) Special Sensor Microwave/Imager (SSM/I) data as well as from a variety of regional and global numerical models such as COAMPS<sup>TM</sup> and NOGAPS.

- Develop an on-board calibration to the GOES channel 1 sensors that will greatly reduce AOD uncertainties.
- Refine the phase function lookup table to include more realistic aerosol size distributions for dust events.
- Apply appropriate single-scatter albedo ( $\omega$ ) values for conditions with known absorption properties.

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## APPENDIX A.

Table 5. List of 22 cases that include the GOES and NOAA pass times (in UTC) and locations. The case studies are identified in sequential numbers, shown in parentheses.

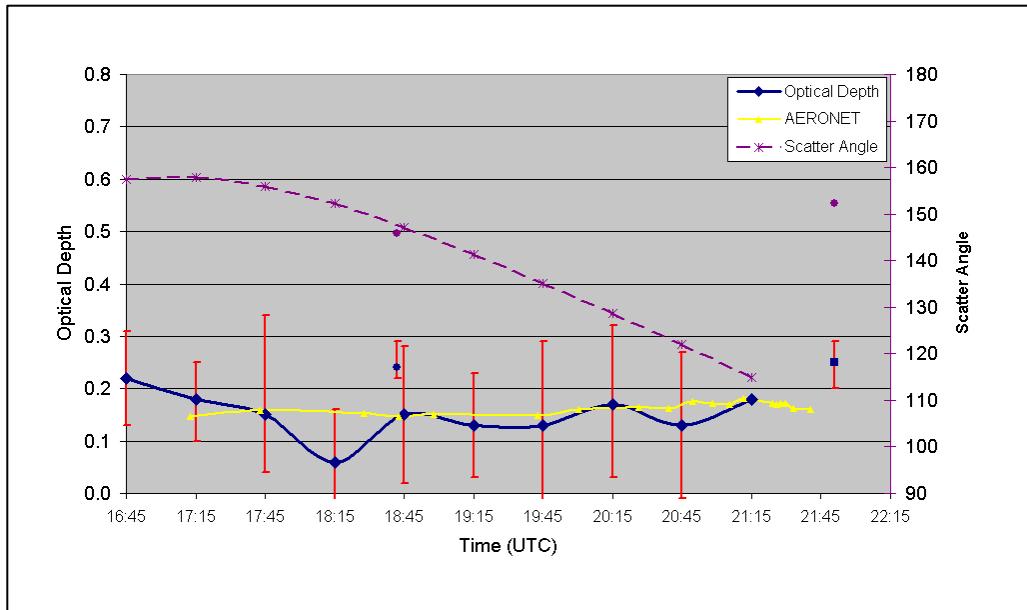
Dates	Satellite Times	Study locations	GOES corr. factors
(1) 27 July	GOES-8: 16:45 –21:15 NOAA-16: 18:42, NOAA-14: 21:51 NOAA-14: 21:51	Guadalupe Island	1.727
(2) 28 July	GOES-8: 17:15 – 21:15 NOAA-16:18:31,NOAA –14 :21:39	La Paguera	1.727
(3) 02 Sept	GOES-8: 17:15 – 21:15 NOAA-16: 17:18, NOAA-14: 21:08	Bermuda	1.734
(4) 04 Sept	GOES-8: 16:45 – 21:15 NOAA-16: 18:35	Guadalupe Island	1.735
(5) 05 Sept	GOES-8: 17:15 – 21:15 NOAA-16: 18:26	La Paguera	1.735
(6) 06 Sept	GOES-8: 17:15 – 21:15 NOAA-16: 18:16	Guadalupe Island	1.735
(7) 07 Sept	GOES-8: 17:15 – 21:15 NOAA-16: 18:05	Guadalupe Island	1.735
(8) 08 Sept	GOES-8: 17:15 – 21:15 NOAA-16: 17:55	Guadalupe Island	1.736
(9) 11 Sept	GOES-8: 15:15 – 20:45 NOAA-14: 21:00	Bermuda	1.736
(10) 11 Sept	GOES-8: 15:15 – 20:45 NOAA-14: 21:00	Guadalupe Island	1.736
(11) 17 Sept	GOES-8: 16:15 – 20:45 NOAA-16: 18:01	Bermuda	1.737

(12) 17 Sept	GOES-8: 16:15 – 20:45 NOAA-16: 18:01	Guadalupe Island	1.737
(13) 18 Sept	GOES-8: 16:45 – 21:15 NOAA-16: 17:50, NOAA-14: 21:16	Bermuda	1.738
(14) 18 Sept	GOES-8: 16:45 – 20:45 NOAA-16: 17:50, NOAA-14: 21:16	Guadalupe Island	1.738
(15) 19 Sept	GOES-8: 15:15 – 21:15 NOAA-16: 17:40, NOAA-14: 21:04	Bermuda	1.738
(16) 19 Sept	GOES-8: 15:15 – 18:45 NOAA-16: 17:40	La Paguera	1.738
(17) 20 Sept	GOES-8: 14:45 – 21:15 NOAA-16: 17:29, NOAA-14: 20:53	Bermuda	1.738
(18) 21 Sept	GOES-8: 14:15 – 21:15 NOAA-16: 17:19, NOAA-16: 19:00	La Paguera	1.738
(19) 22 Sept	GOES-8: 14:15 – 21:15 NOAA-16: 18:47	La Paguera	1.738
(20) 23 Sept	GOES-8: 17:15 – 21:15 NOAA-16: 18:38	La Paguera	1.739
(21) 25 Sept	GOES-8: 13:15 – 20:45 NOAA-16: 18:17	Bermuda	1.739
(22) 29 Sept	GOES-8: 13:15 – 21:15 NOAA-16: 17:35	La Paguera	1.740

## APPENDIX B.

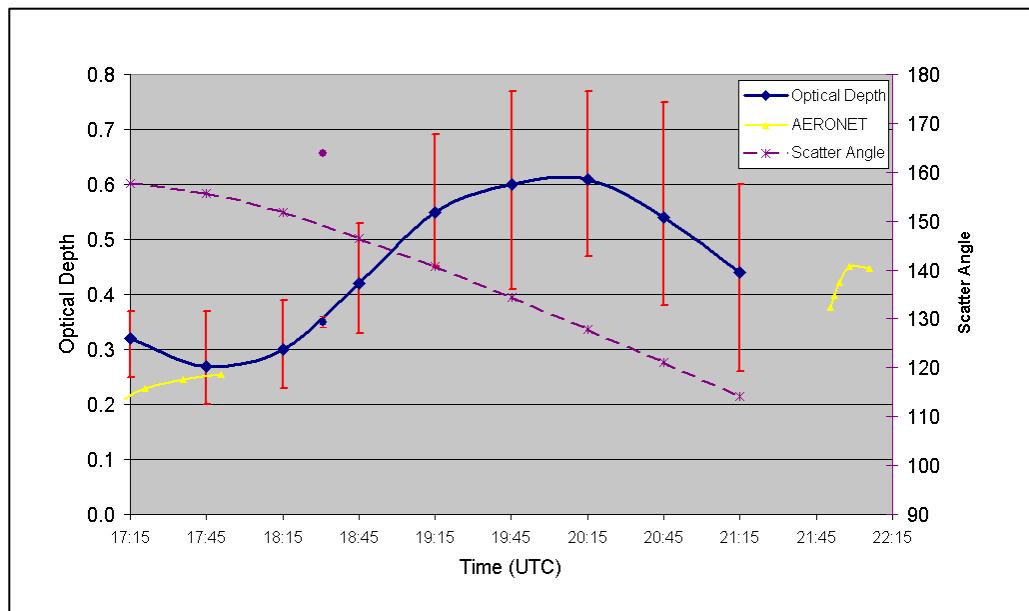
Time series of AOD for 22 cases ranging from 27 July, 2001 through 29 September, 2001 over the regions of Bermuda, Guadalupe Island, and La Paguera, Puerto Rico. Both satellite-derived data (navy blue dots) and AERONET observations (yellow) NOAA data are presented as individual blue dots whereas GOES-8 data are connected with a blue line. Red bars represent variability in AOD measurements. The corresponding scatter angle profile is represented as a purple dashed line.

Case No. 1 20010727 Region: Guadalupe Island



Case No. 2 20010728

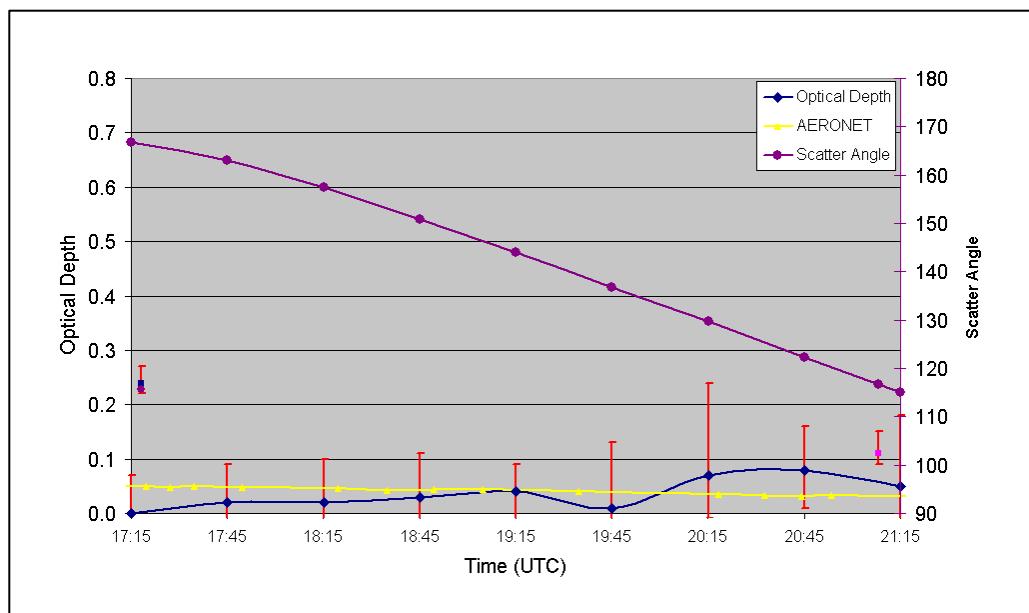
Region: La Paguera, Puerto Rico



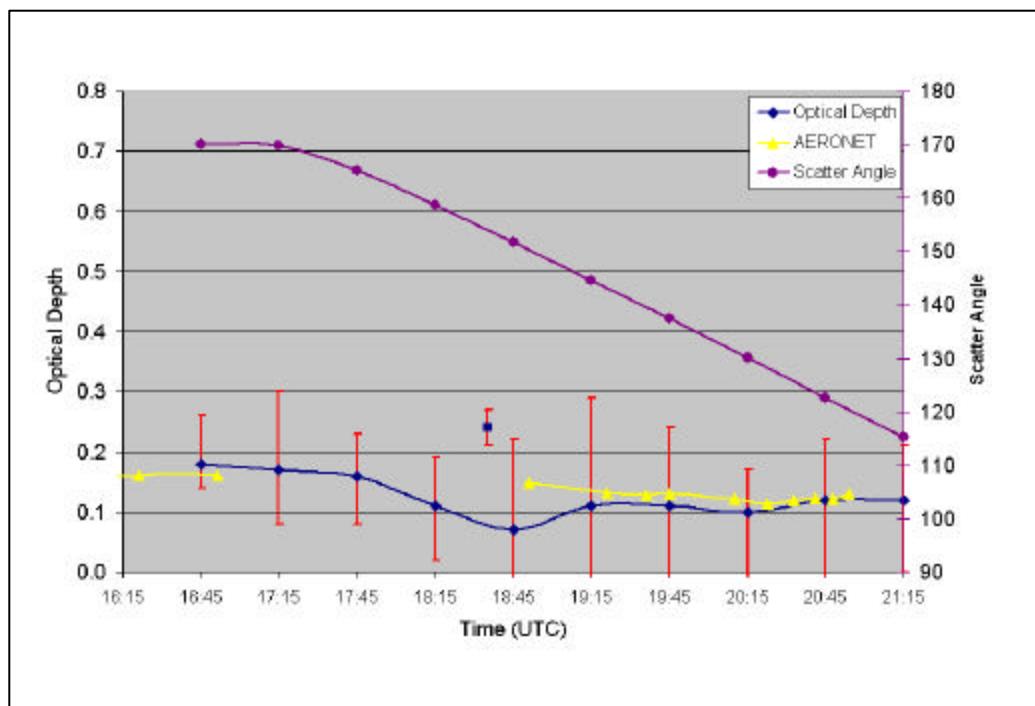
Case No. 3

20010902

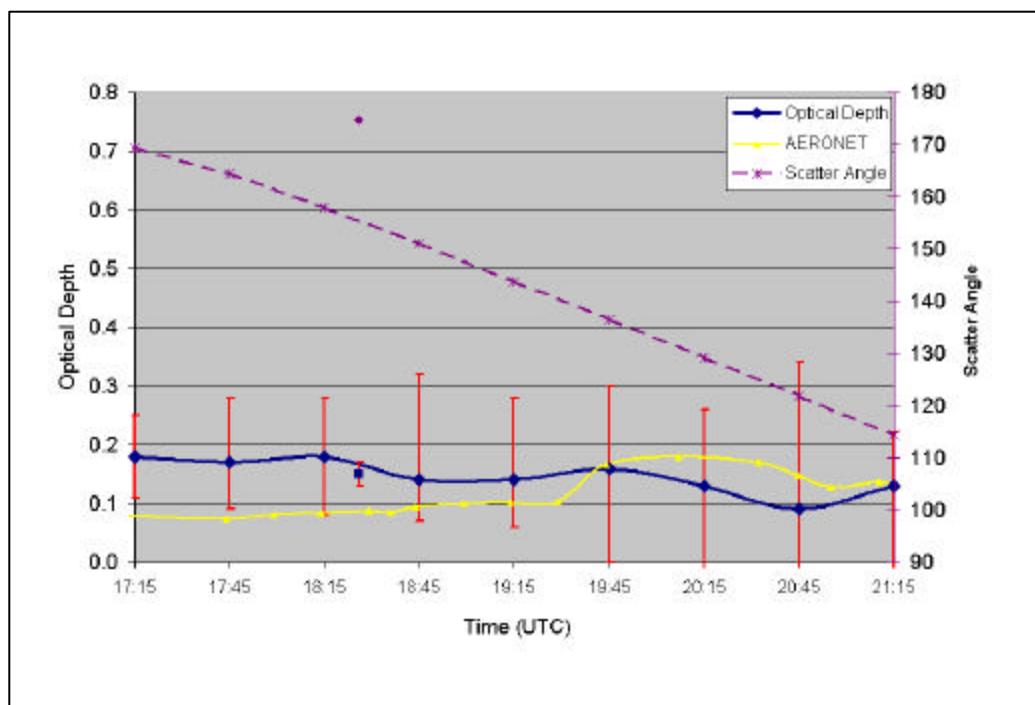
Region: Bermuda



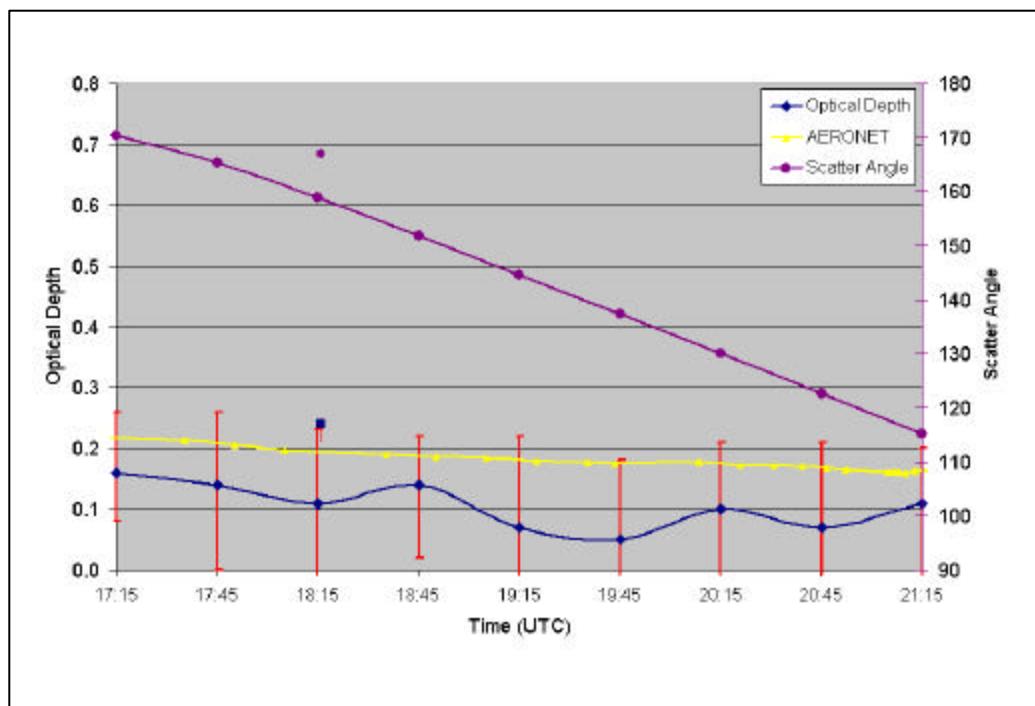
Case No. 4 20010904 Region: Guadalupe Island



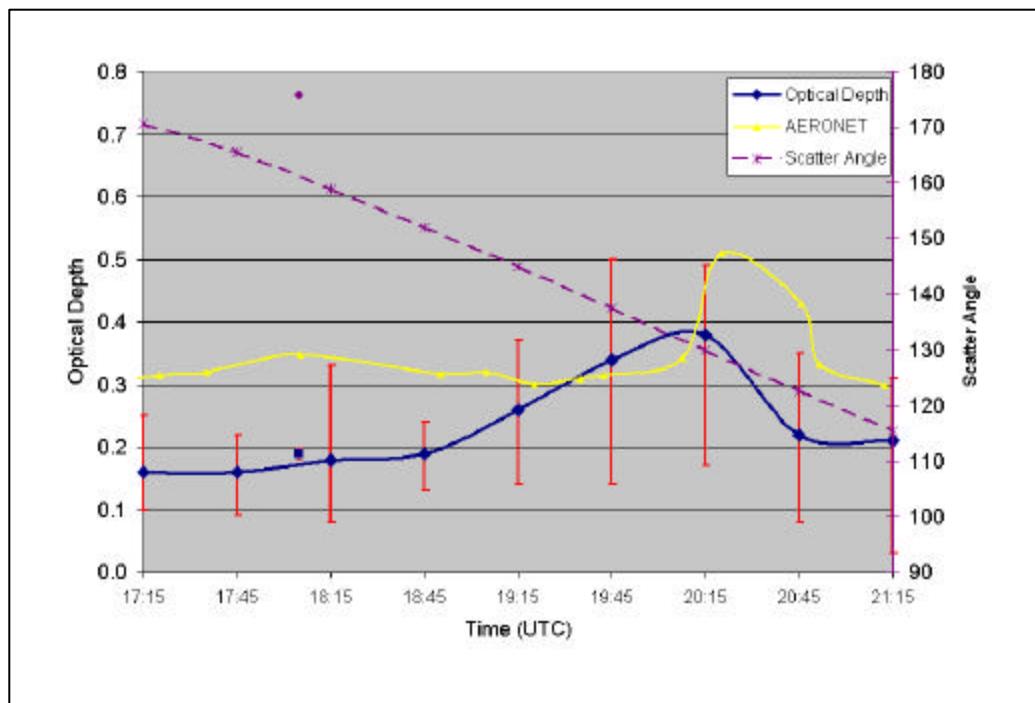
Case No. 5 20010905 Region: La Paguera, Puerto Rico



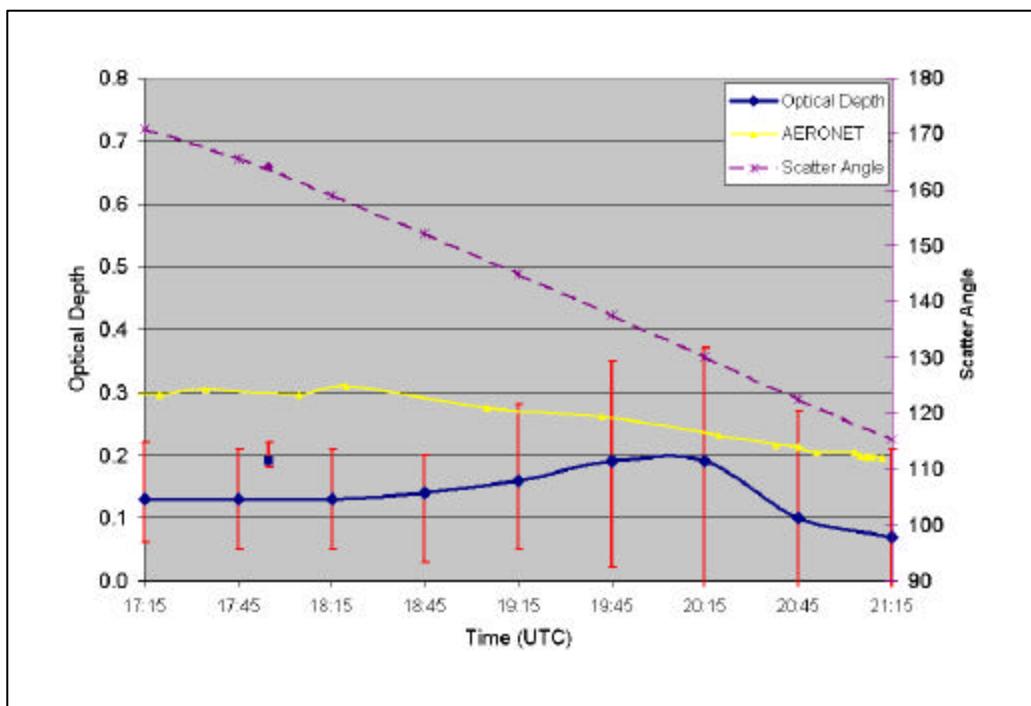
Case No. 6 20010906 Region: Guadalupe Island



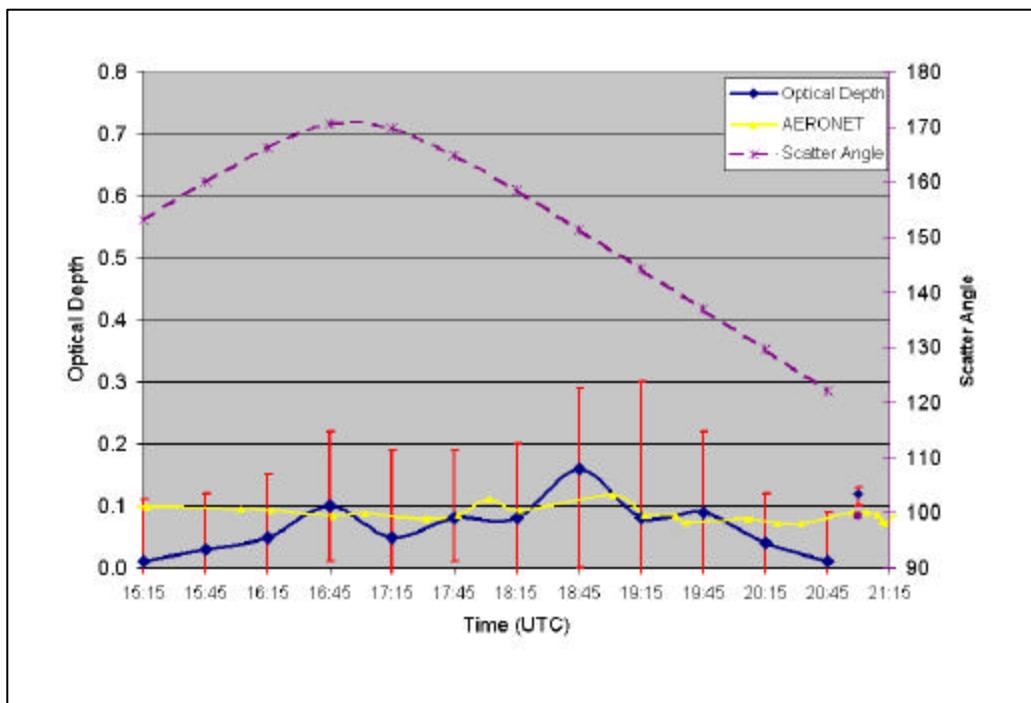
Case No. 7 20010907 Region: Guadalupe Island



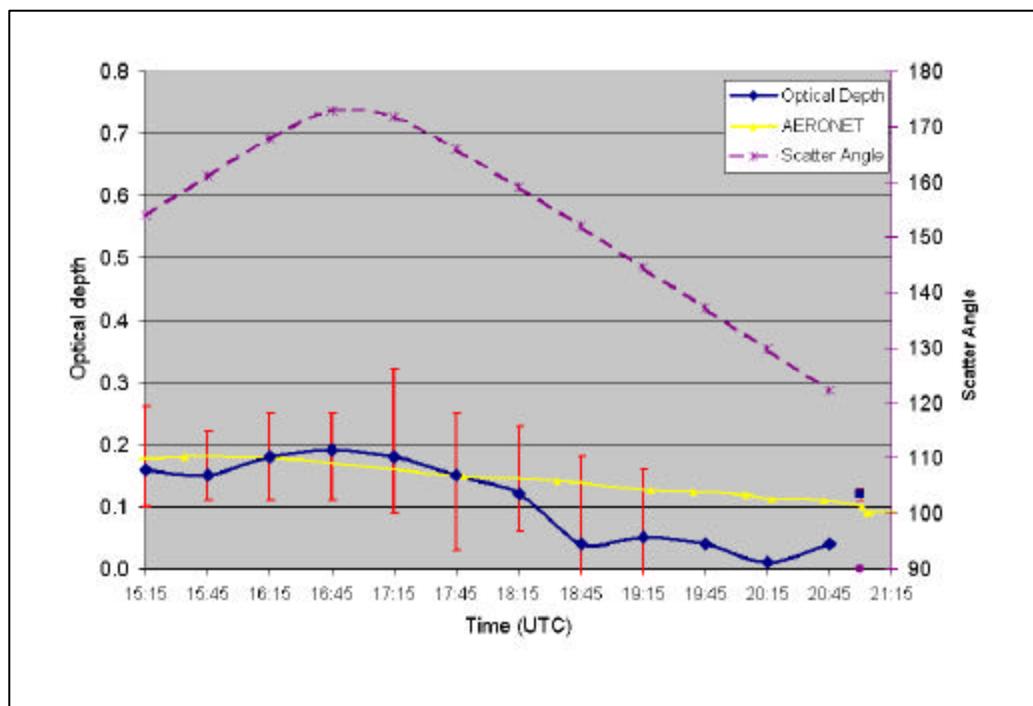
Case No. 8 20010908 Region: Guadalupe Island



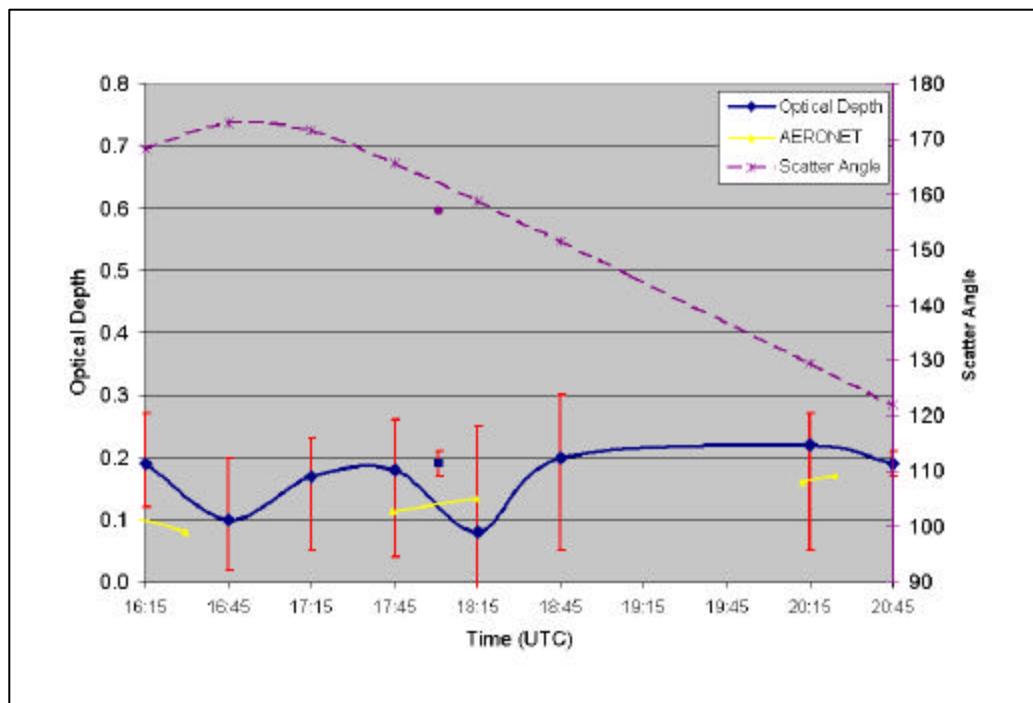
Case No. 9 20010911 Region: Bermuda



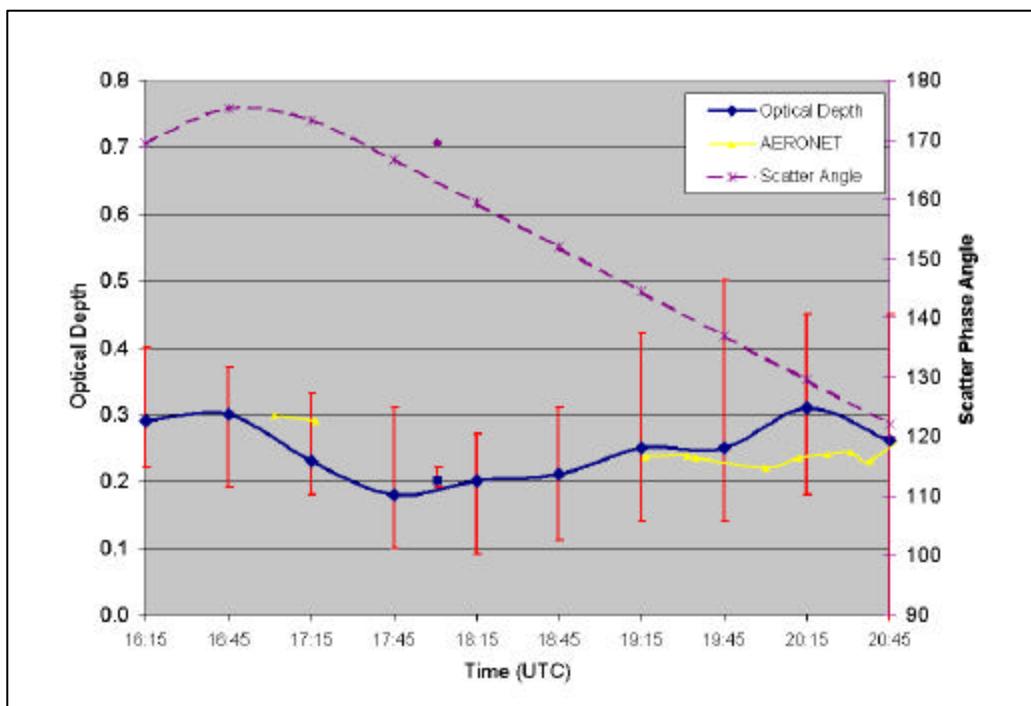
Case No. 10 20010911 Region: Guadalupe Island



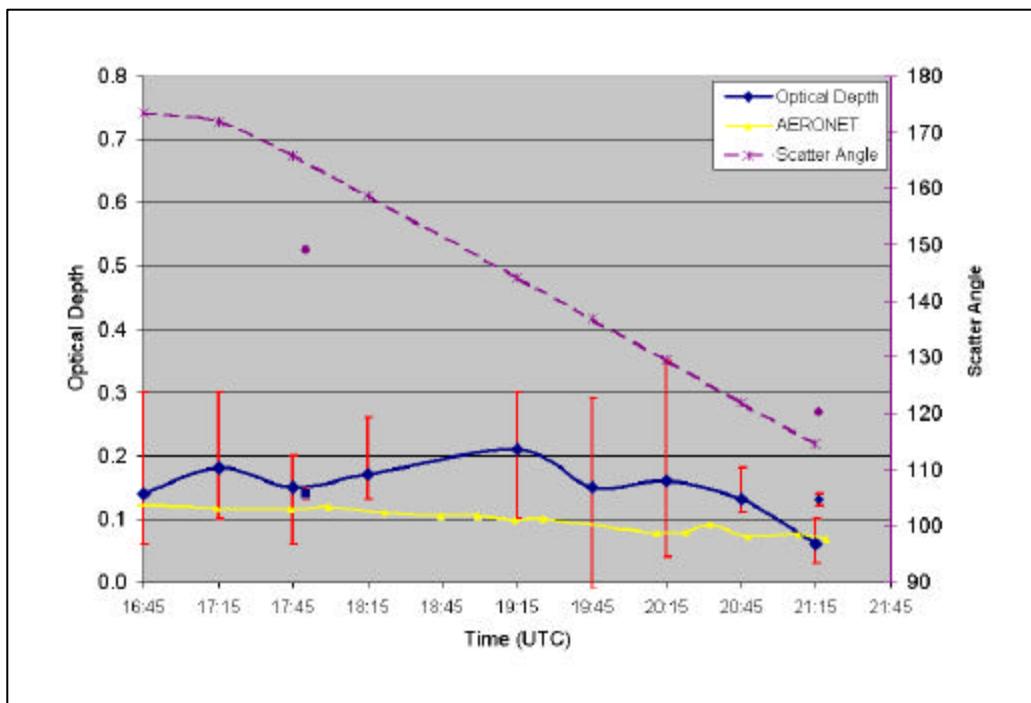
Case No. 11 20010917 Region: Bermuda



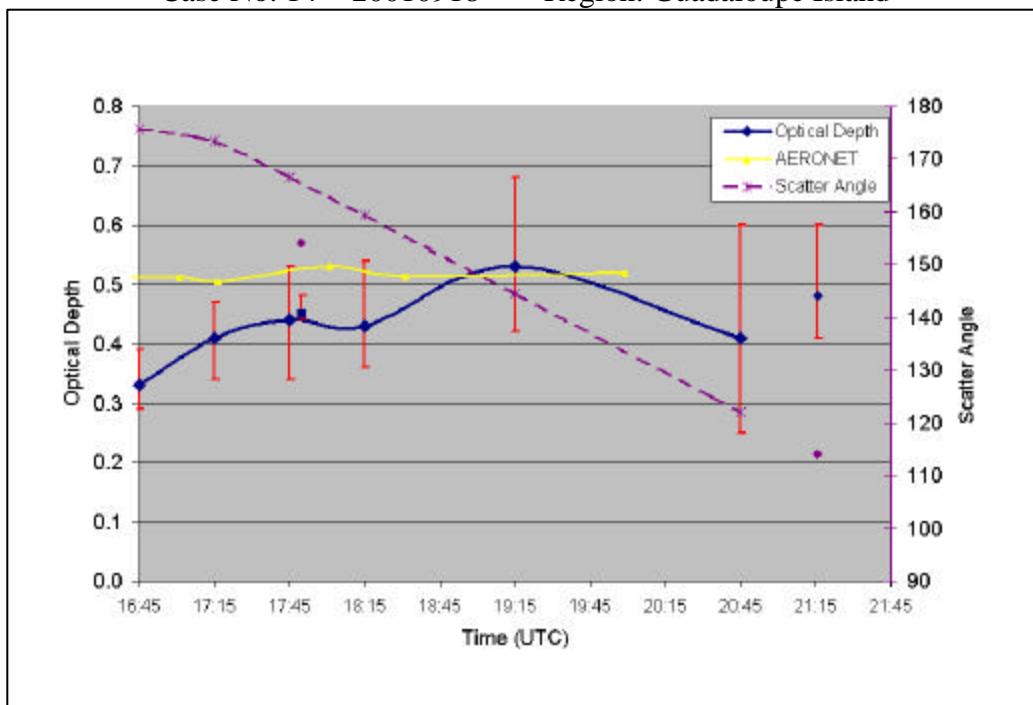
Case No. 12 20010917 Region: Guadalupe Island



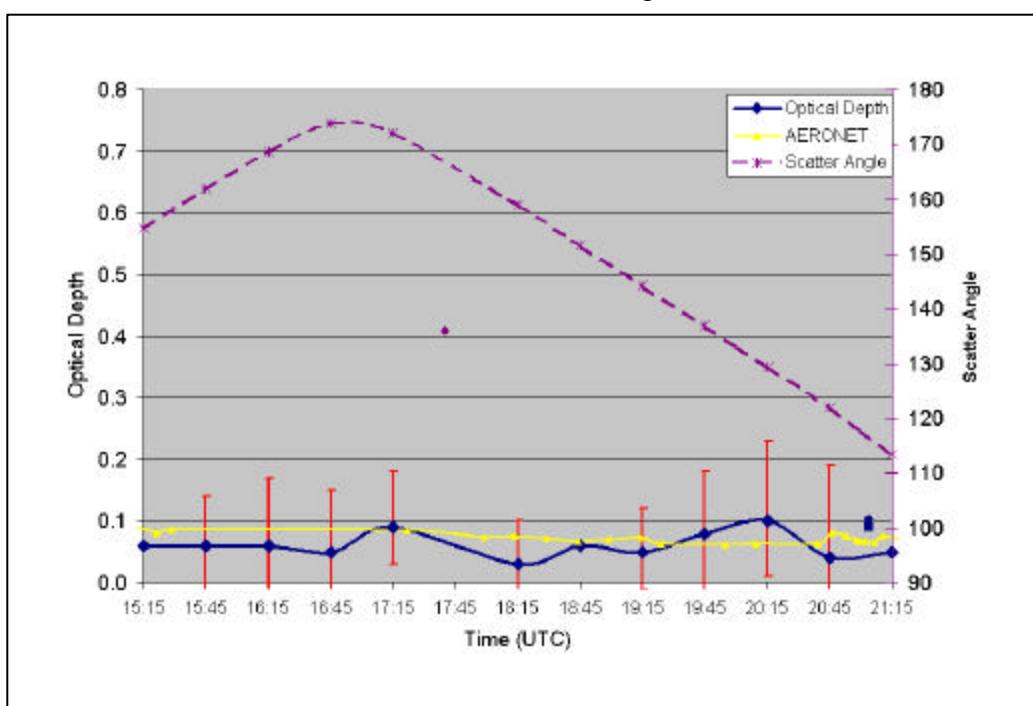
Case No. 13 20010918 Region: Guadalupe Island



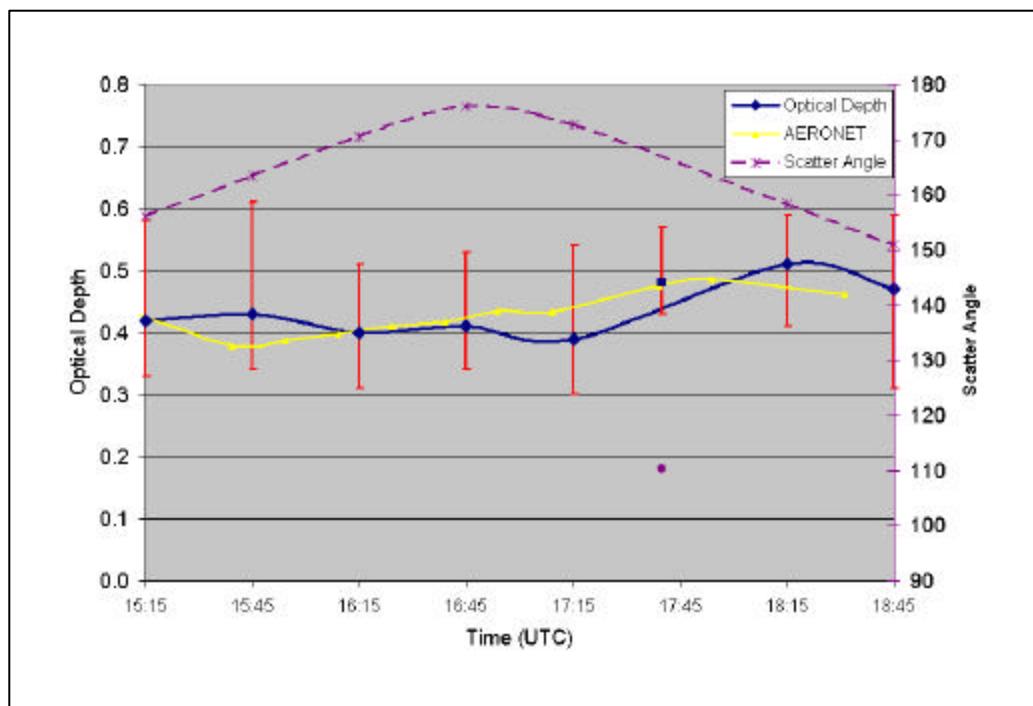
Case No. 14 20010918 Region: Guadalupe Island



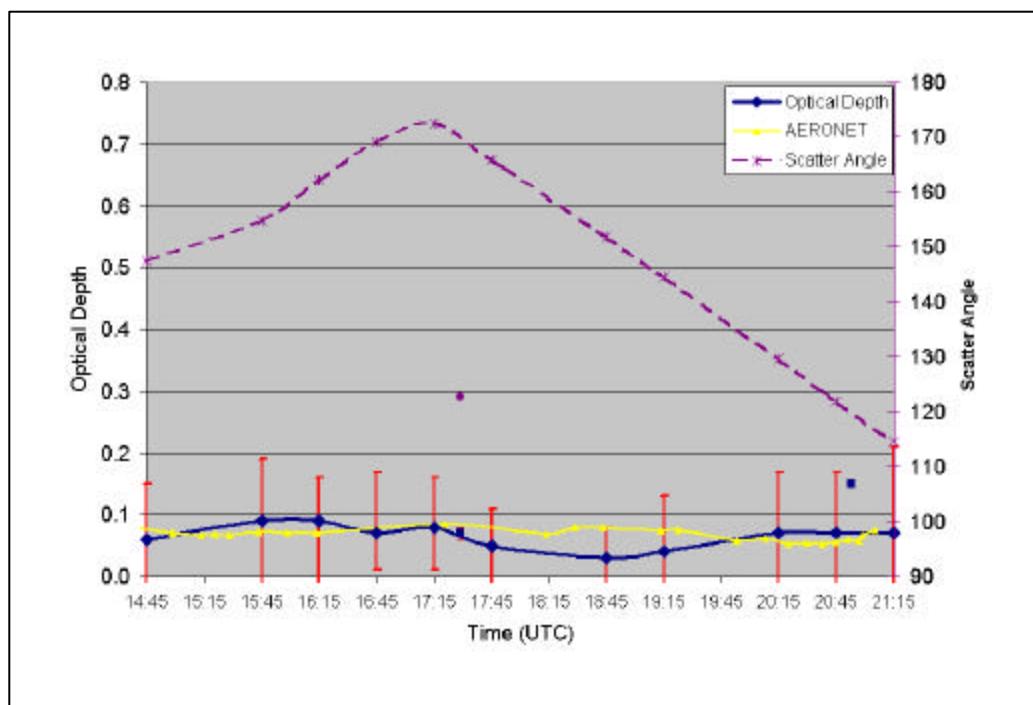
Case No. 15 20010919 Region: Bermuda



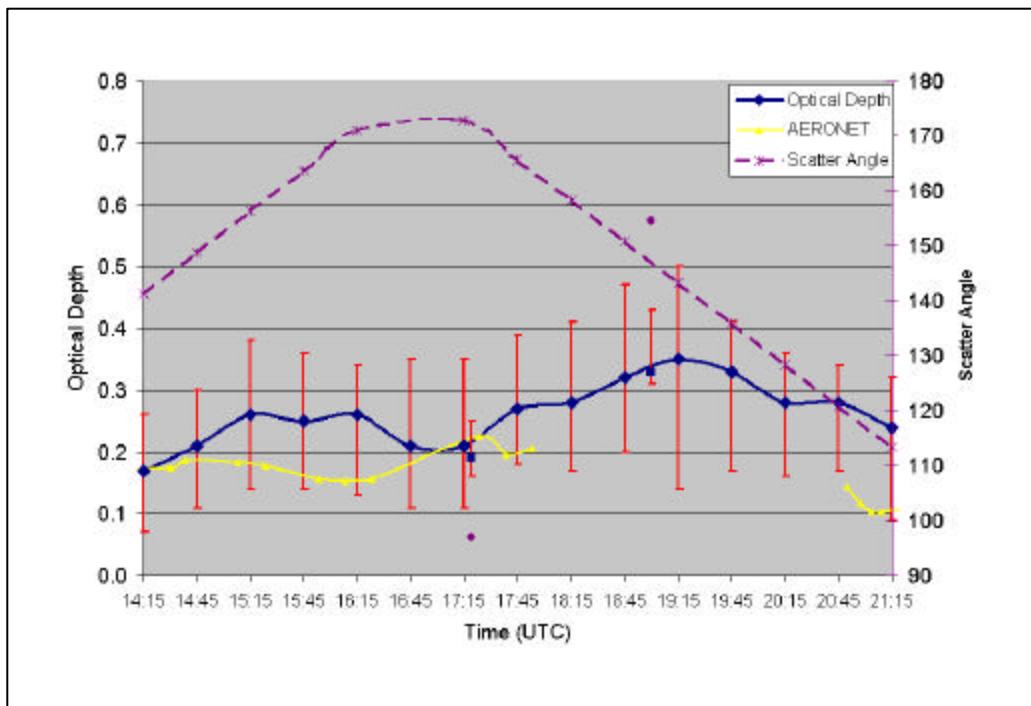
Case No. 16 20010919 Region: La Paguera, Puerto Rico



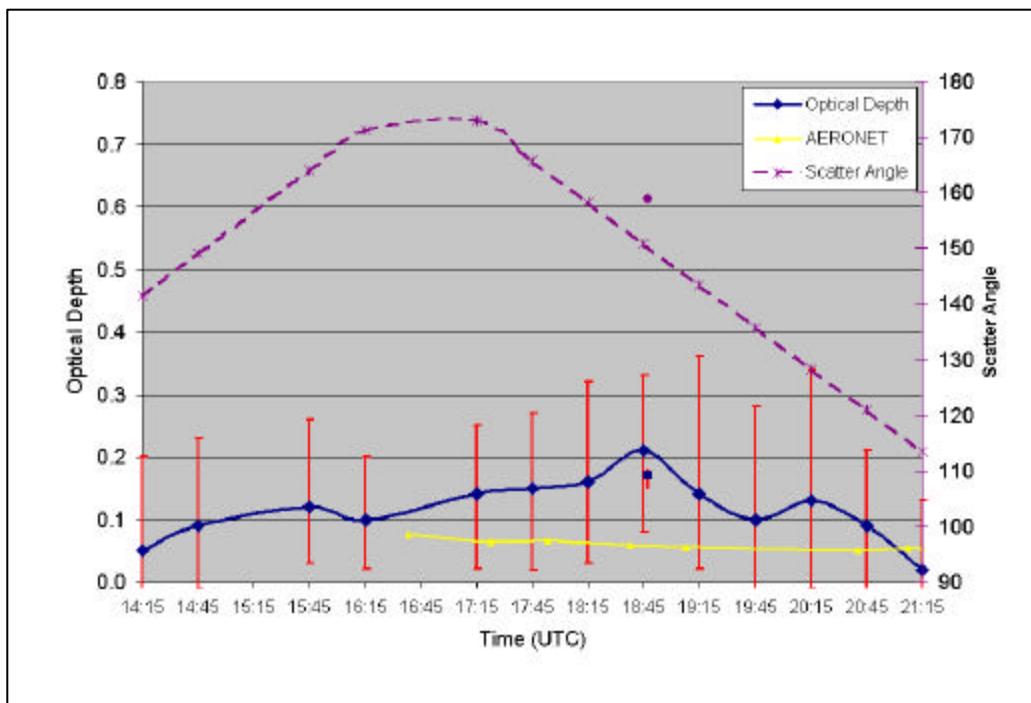
Case No. 17 20010920 Region: Bermuda



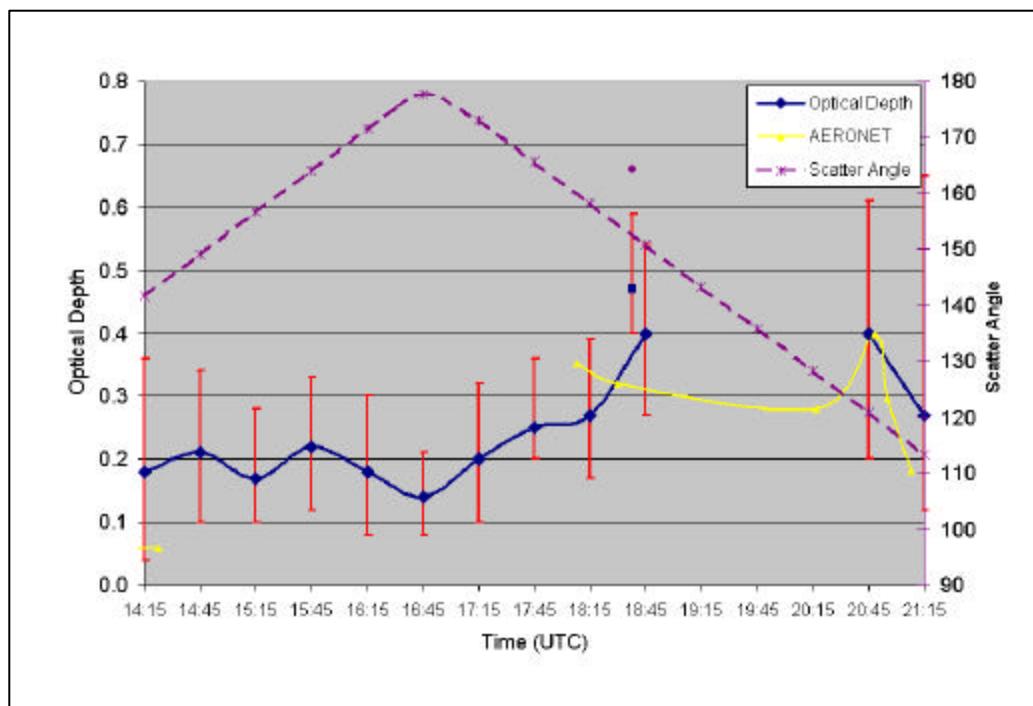
Case No. 18 20010921 Region: La Paguera, Puerto Rico



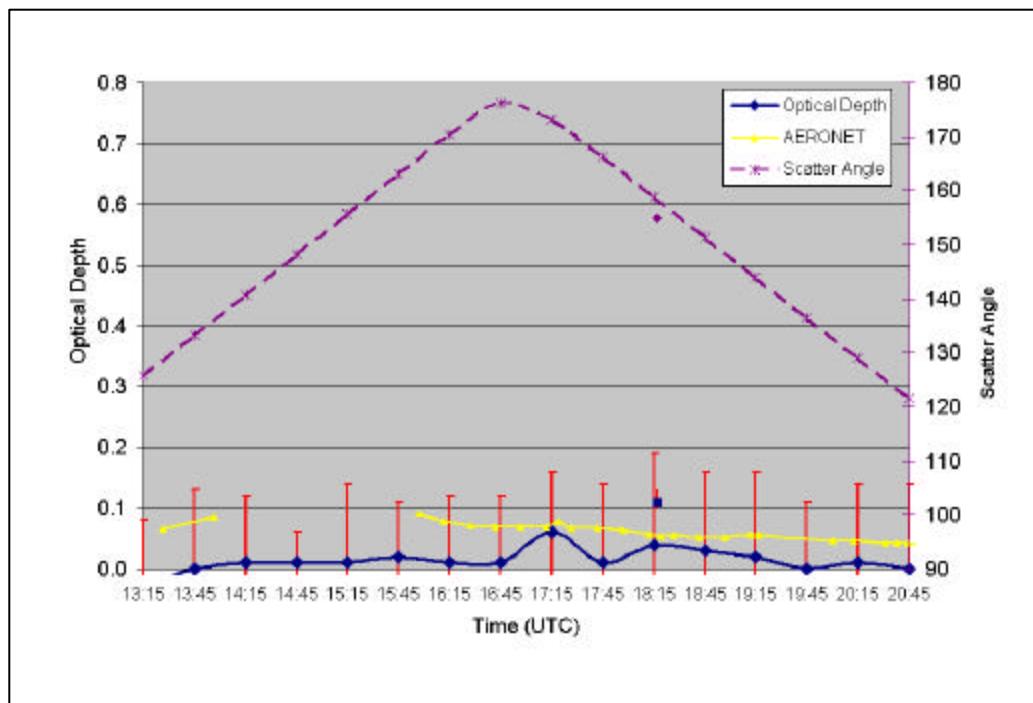
Case No. 19 20010922 Region: La Paguera, Puerto Rico

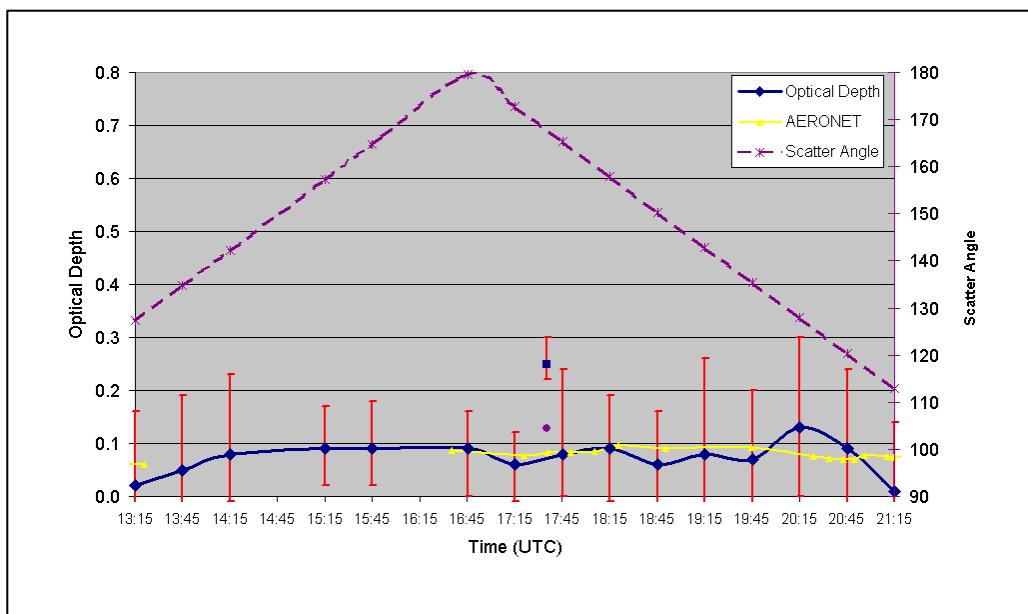


Case No. 20 20010923 Region: La Paguera, Puerto Rico



Case No. 21 20010925 Region: Bermuda





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